# OMRON

**Machine Automation Controller** 

**NX-series** 

**NX102 CPU Unit** 

# Hardware User's Manual

NX102-□□□□

**CPU Unit** 





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# Introduction

Thank you for purchasing an NX-series CPU Unit.

This manual contains information that is necessary to use the NX-series CPU Unit. Please read this manual and make sure you understand the functionality and performance of the NX-series CPU Unit before you attempt to use it in a control system.

Keep this manual in a safe place where it will be available for reference during operation.

### **Intended Audience**

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- · Personnel in charge of introducing FA systems.
- · Personnel in charge of designing FA systems.
- · Personnel in charge of installing and maintaining FA systems.
- Personnel in charge of managing FA systems and facilities.

For programming, this manual is intended for personnel who understand the programming language specifications in international standard IEC 61131-3 or Japanese standard JIS B 3503.

### **Applicable Products**

This manual covers the following products.

NX-series CPU Units
 NX102-□□□□□

Part of the specifications and restrictions for the CPU Units are given in other manuals. Refer to *Relevant Manuals* on page 2 and *Related Manuals* on page 43.

# **Relevant Manuals**

The following table provides the relevant manuals for the NX-series CPU Units. Read all of the manuals that are relevant to your system configuration and application before you use the NX-series CPU Unit.

Most operations are performed from the Sysmac Studio Automation Software. Refer to the *Sysmac Studio Version 1 Operation Manual (Cat. No. W504)* for information on the Sysmac Studio.

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Software settings															
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Using the database connection service															
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Using EtherCAT								•							
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Using FINS												•			
Using the database connection service															
Programming error processing															•

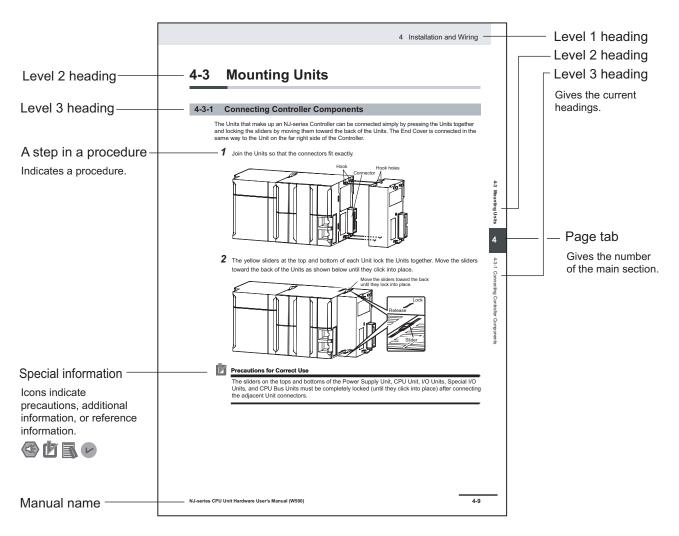
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		NJ/NX-series CPU Unit Software User's Manual	NJ/NX-series Instructions Reference Manual	NJ/NX-series CPU Unit Motion Control User's Manual	NJ/NX-series  Motion Control Instructions Reference Manua	NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual	NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual	NJ/NX-series CPU Unit OPC UA User's Manual	NX-series CPU Unit FINS Function User's Manual	NJ/NX-series Database Connection CPU Units User's Manual	NJ/NX-series Troubleshooting Manual	
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Using motion control				•								
Using EtherCAT						•						
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Using EtherNet/IP							•					

<sup>\*1.</sup> Refer to the *NJ/NX-series Troubleshooting Manual (Cat. No. W503)* for the error management concepts and the error items. However, refer to the manuals that are indicated with triangles ( $\triangle$ ) for details on errors corresponding to the products with the manuals that are indicated with triangles ( $\triangle$ ).

# **Manual Structure**

### **Page Structure**

The following page structure is used in this manual.



Note This illustration is provided only as a sample. It may not literally appear in this manual.

### **Special Information**

Special information in this manual is classified as follows:



#### **Precautions for Safe Use**

Precautions on what to do and what not to do to ensure safe usage of the product.



#### **Precautions for Correct Use**

Precautions on what to do and what not to do to ensure proper operation and performance.



### **Additional Information**

Additional information to read as required.

This information is provided to increase understanding or make operation easier.



#### **Version Information**

Information on differences in specifications and functionality for CPU Units with different unit versions and for different versions of the Sysmac Studio is given.

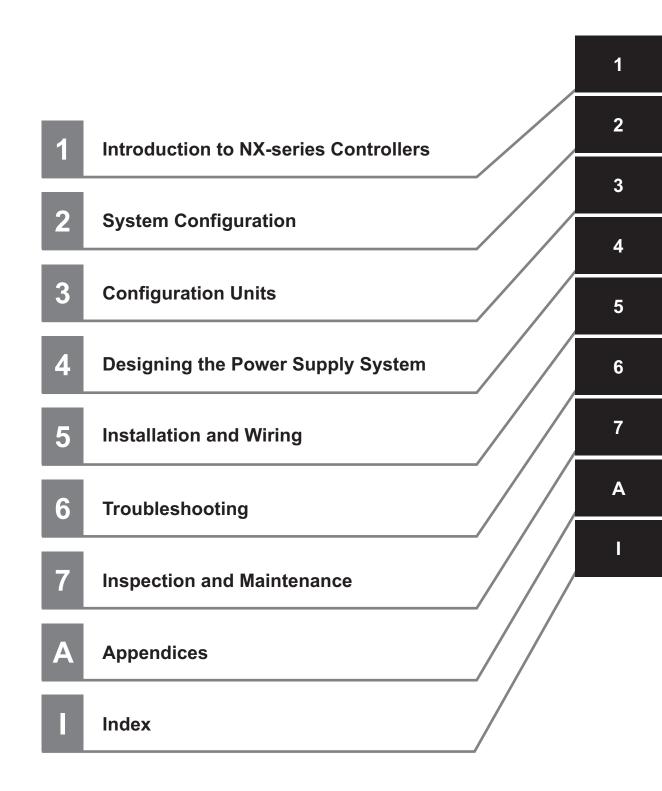
### **Precaution on Terminology**

In this manual, "download" refers to transferring data from the Sysmac Studio to the physical Controller and "upload" refers to transferring data from the physical Controller to the Sysmac Studio.

For the Sysmac Studio, "synchronization" is used to both "upload" and "download" data. Here, "synchronize" means to automatically compare the data for the Sysmac Studio on the computer with the data in the physical Controller and transfer the data in the direction that is specified by the user.

Manual Structure

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### Warranty, Limitations of Liability

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It shall be the users sole responsibility to determine and use adequate measures and checkpoints to satisfy the users particular requirements for (i) antivirus protection, (ii) data input and output, (iii) maintaining a means for reconstruction of lost data, (iv) preventing Omron Products and/or software installed thereon from being infected with computer viruses and (v) protecting Omron Products from unauthorized access.

# **Safety Precautions**

### **Definition of Precautionary Information**

The following notation is used in this manual to provide precautions required to ensure safe usage of the NX-series CPU Unit.

The safety precautions that are provided are extremely important for safety. Always read and heed the information provided in all safety precautions.

The following notation is used.



Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

### **Symbols**



The circle and slash symbol indicates operations that you must not do.

The specific operation is shown in the circle and explained in text.

This example indicates prohibiting disassembly.



The triangle symbol indicates precautions (including warnings).

The specific operation is shown in the triangle and explained in text.

This example indicates a precaution for electric shock.



The triangle symbol indicates precautions (including warnings).

The specific operation is shown in the triangle and explained in text.

This example indicates a general precaution.



The filled circle symbol indicates operations that you must do.

The specific operation is shown in the circle and explained in text.

This example shows a general precaution for something that you must do.



The triangle symbol indicates precautions (including warnings).

The specific operation is shown in the triangle and explained in text.

This example indicates a precaution for high temperatures.

### **WARNING**

# **⚠ WARNING**

## **During Power Supply**

Do not touch any of the terminals or terminal blocks while the power is being supplied. Doing so may result in electric shock.



Do not attempt to take any Unit apart.

In particular, high-voltage parts are present in the Power Supply Unit while power is supplied or immediately after power is turned OFF. Touching any of these parts may result in electric shock. There are sharp parts inside the Unit that may cause injury.



### **Fail-safe Measures**

Provide safety measures in external circuits to ensure safety in the system if an abnormality occurs due to malfunction of the CPU Unit, slaves, or Units or due to other external factors affecting operation. Not doing so may result in serious accidents due to incorrect operation.



Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.



The Controller outputs may remain ON or OFF due to deposition or burning of the output relays or destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safe operation of the system.



The CPU Unit will turn OFF digital outputs on the CPU Rack in the following cases.

- While the CPU Unit is on standby until RUN mode is entered after the power is turned ON
- If an error occurs in the power supply
- · If a system initialization error occurs

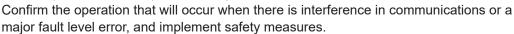
Digital outputs on the CPU Rack will produce outputs according to the settings in the following cases.



- · If a CPU Unit error or CPU Unit reset occurs
- · If a major fault level Controller error occurs

External safety measures must be provided to ensure safe operation of the system in such cases.







Correctly set all of the settings in the slaves and Units.

If external power supplies for Units, slaves or other devices are overloaded or short-circuited, the voltage will drop, outputs will turn OFF, and the system may be unable to read inputs. Provide external safety measures in controls with monitoring of external power supply voltage as required so that the system operates safely in such a case.



Unintended outputs may occur when an error occurs in variable memory. As a countermeasure for such problems, external safety measures must be provided to ensure safe operation of the system.



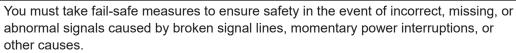
Provide measures in the communications system and user program to ensure safety in the overall system even if errors or malfunctions occur in data link communications or remote I/O communications.



The NX-series Controller continues normal operation for a certain period of time when a momentary power interruption occurs. This means that the NX-series Controller may receive incorrect signals from external devices that are also affected by the power interruption.



Accordingly, take suitable actions, such as external fail-safe measures and interlock conditions, to monitor the power supply voltage of the external device as required.





Not doing so may result in serious accidents due to incorrect operation.

# **Voltage and Current Inputs**

Make sure that the voltages and currents that are input to the slaves and Units are within the specified ranges.



Inputting voltages or currents that are outside of the specified ranges may cause accidents or fire.

## **Downloading**

Always confirm safety at the destination before you transfer a user program, configuration data, setup data, or device variables from the Sysmac Studio.



The devices or machines may perform unexpected operation regardless of the operating mode of the CPU Unit.

# **Actual Operation**

Check the user program, data, and parameter settings for proper execution before you use them for actual operation.



# **Security Measures**

### **Anti-virus protection**

Install the latest commercial-quality antivirus software on the computer connected to the control system and maintain to keep the software up-to-date.



#### Security measures to prevent unauthorized access

Take the following measures to prevent unauthorized access to our products.

- Install physical controls so that only authorized personnel can access control systems and equipment.
- Reduce connections to control systems and equipment via networks to prevent access from untrusted devices.
- Install firewalls to shut down unused communications ports and limit communications hosts and isolate control systems and equipment from the IT network.
- Use a virtual private network (VPN) for remote access to control systems and equip-
- Adopt multifactor authentication to devices with remote access to control systems and equipment.
- Set strong passwords and change them frequently.
- · Scan virus to ensure safety of USB drives or other external storages before connecting them to control systems and equipment.

#### Data input and output protection

Validate backups and ranges to cope with unintentional modification of input/output data to control systems and equipment.

- Checking the scope of data
- Checking validity of backups and preparing data for restore in case of falsification and abnormalities
- Safety design, such as emergency shutdown and fail-soft operation in case of data tampering and abnormalities



Backup data and keep the data up-to-date periodically to prepare for data loss.



When using an intranet environment through a global address, connecting to a SCADA or an unauthorized terminal such as an HMI or to an unauthorized server may result in network security issues such as spoofing and tampering. You must take sufficient measures such as restricting access to the terminal, using a terminal equipped with a secure function, and locking the installation area by yourself.



When constructing an intranet, communication failure may occur due to cable disconnection or the influence of unauthorized network equipment. Take adequate measures, such as restricting physical access to network devices, by means such as locking the installation area.



When using a device equipped with the SD Memory Card function, there is a security risk that a third party may acquire, alter, or replace the files and data in the removable media by removing the removable media or unmounting the removable media. Please take sufficient measures, such as restricting physical access to the Controller or taking appropriate management measures for removable media, by means of locking the installation area, entrance management, etc., by yourself.





### **Cautions**

# **/** Caution

### **Application**

Do not touch any Unit when power is being supplied or immediately after the power supply is turned OFF. Doing so may result in burn injury.



### Wiring

Be sure that all terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. Loose screws may result in fire or malfunction.



When you connect a computer or other peripheral device to a Controller that has a non-isolated DC power supply, either ground the 0-V side of the external power supply for the Unit power supply or do not ground it at all.

If the peripheral devices are grounded incorrectly, the external power supply for the Unit power supply may be short-circuited. Never ground the 24-V side of the power supply, as shown in the following figure.

Non-isolated type Communications Interface Unit, etc. CPU Unit External device Unit power Non-isolated DC supply (e.g. computer) power supply terminals Internal ower supply circuit (No-isola-Cable tion) External power supply (Unit power supply)



# **Online Editing**

Execute online editing only after confirming that no adverse effects will be caused by deviations in the timing of I/O. If you perform online editing, the task execution time may exceed the task period, I/O may not be refreshed with external devices, input signals may not be read, and output timing may change.



# **EtherCAT Communications**

If the cable redundancy function is enabled, always write a program to confirm that the network is in the cable redundancy status. If the program is not written, you cannot check that the network is not in the cable redundancy status due to a disconnection on the ring topology.



Use the \_EC\_RingBreaking system-defined variable to confirm that the network is in the cable redundancy status.



### **Version Information**

The cable redundancy function can be used with project unit version 1.40 or later.

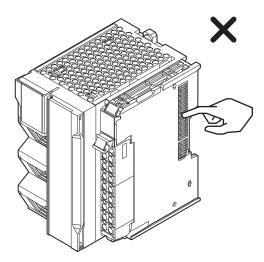
# **Precautions for Safe Use**

# **Transporting and Disassembly**

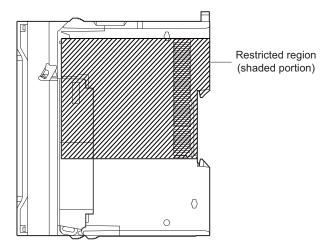
- Do not attempt to disassemble, repair, or modify any Units. Doing so may result in malfunction or fire.
- Do not drop any Unit or subject it to abnormal vibration or shock. Doing so may result in Unit malfunction or burning.
- When transporting any Unit, use the special packing box for it. Also, do not subject the Unit to excessive vibration or shock during transportation.

## **Mounting**

- Always turn OFF the power supply before mounting the Units. If the power supply is not OFF, the
  Unit may result in malfunction or may be damaged.
- Do not apply labels or tape to the Unit. When the Unit is installed or removed, adhesive or scraps may adhere to the pins in the NX bus connector, which may result in malfunctions.
- Do not touch the pins in the NX bus connector on the Unit. Dirt may adhere to the pins in the NX bus connector, which may result in malfunctions.



Do not write anything with ink within the restricted region of the CPU Unit that is shown in the following figure. Also do not get this area dirty. When the Unit is installed or removed, ink or dirt may adhere to the pins in the NX bus connector, which may result in malfunctions in the Unit.
 Refer to the user's manual for the connected NX Unit for information on the restricted region for the NX Unit.



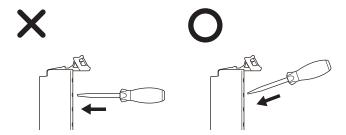
 The End Cover has a metal portion and is heavier than it looks. Be careful not to drop it when handling.

### Installation

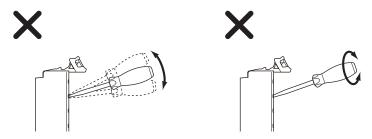
• Always connect to a ground of 100  $\Omega$  or less when installing the Units.

## Wiring

- Follow the instructions in this manual to correctly perform wiring.
   Double-check all wiring and switch settings before turning ON the power supply.
- Use the methods that are specified in this manual for wiring the terminal blocks.
- Use crimp terminals for wiring the M3 screw terminal blocks. Do not connect bare stranded wires directly to the M3 screw terminal blocks.
- Use the correct wiring parts and tools when you wire the system. Otherwise, cables may be disconnected to cause short-circuit or wire breakage.
- Do not pull on the cables or bend the cables beyond their natural limit.
   Do not place heavy objects on top of the cables or other wiring lines.
   Doing so may break the cables.
- Mount terminal blocks, connectors, and other parts only after checking the mounting location carefully.
- Be sure that the terminal blocks and communications cables with tightening screws or locking devices are properly tightened to or locked into place.
- If the external power supply to an Output Unit or slave has polarity, connect it with the correct polarity. If the polarity is reversed, current may flow in the reverse direction and damage the connected devices regardless of the operation of the Controller.
- Do not press a flat-blade screwdriver straight into the release hole on a screwless clamping terminal block. Doing so may break the terminal block.



- When you insert a flat-blade screwdriver into a release hole on a screwless clamping terminal block, press it down with a force of 30N or less. Applying excessive force may damage the terminal block.
- Do not incline or twist the flat-blade screwdriver while it is in a release hole on a screwless clamping terminal block. Doing so may break the terminal block.



## **Power Supply Design**

- Select an external power supply with sufficient capacity by considering the power supply capacity or inrush current when the power is turned ON that is specified in this manual.
   Otherwise, the external power supply may not be turned ON or malfunction due to unstable power supply voltage.
- Use all Units within the I/O power supply ranges that are given in the specifications.
- Do not apply voltages that exceed the rated value to any Input Unit.
- Do not apply voltages or connect loads to the Output Units or slaves in excess of their ratings.
- Surge current occurs when the power supply is turned ON. When selecting fuses or breakers for external circuits, consider the above precaution and allow sufficient margin in shut-off performance. Refer to this manual for surge current specifications.
- If the full dielectric strength voltage is applied or turned OFF using the switch on the tester, the generated impulse voltage may damage the Power Supply Unit. Use the adjustment on the tester to gradually increase and decrease the voltage.
- Install external breakers and take other safety measures against short-circuiting and overcurrents in external wiring.

## **Turning ON the Power Supply**

- It takes a certain time for startup to enter RUN mode after the power supply is turned ON, depending on the type and configuration of the Unit and its settings.
  - During startup, the outputs for NX Units on the CPU Rack will be OFF. Note that the outputs on the slaves will behave according to the setting values.
  - Therefore, use the system-defined variables and the device variables for each Unit in the user program to confirm that startup processing and I/O data communications are established before attempting control operations.

External communications are also not performed during startup.

- Configure the external circuits so that the power supply to the control system turns ON only after the
  power supply to the Controller has turned ON. If the power supply to the Controller is turned ON
  after the control power supply, temporary errors may result in incorrect control system signals because the output terminals on Output Units may momentarily turn ON when power supply is turned
  ON to the Controller.
- If you transfer data from a backup file on an SD Memory Card to the Controller when the power supply is turned ON, properly select the data groups to transfer. If the data for an unintended data group is transferred to the Controller, it may cause the equipment to operate unpredictably.
- You cannot obtain normal input data from NX Units while the Units are restarting. Use the systemdefined variables or device variables for the NX Units on the CPU Unit in the user program to check the validity of the I/O data before you attempt control operations.

# **Actual Operation**

- If you change the fail-soft operation setting, the output status when the error occurs may also change. Confirm safety before you change the setting.
- If you use fail-soft operation, write programming to determine whether Unit I/O data is valid. Without such programming, the user program cannot distinguish between Units for which I/O refreshing is continued and Units for which I/O refreshing is stopped.

## **Turning OFF the Power Supply**

- Never turn OFF the power supply to the Controller when the BUSY indicator is flashing. While the
  BUSY indicator is lit, the user program and settings in the CPU Unit are being backed up in the builtin non-volatile memory. This data will not be backed up correctly if the power supply is turned OFF.
  Also, a major fault level Controller error will occur the next time you start operation, and operation
  will stop.
- Do not turn OFF the power supply or remove the SD Memory Card while SD Memory Card access
  is in progress (i.e., while the SD BUSY indicator flashes). Data may become corrupted, and the
  Controller will not operate correctly if it uses corrupted data. To remove the SD Memory Card from
  the CPU Unit while the power supply is ON, press the SD Memory Card power supply switch and
  wait for the SD BUSY indicator and SD PWR indicator to turn OFF before you remove the SD Memory Card.
- If the Unit power supply is turned OFF before the I/O power supply for the control system is turned
  OFF, the output terminals of Output Units may malfunction and the control system may perform incorrect output temporarily. To avoid this problem, configure the external circuit to make sure that the
  Unit power supply is turned OFF only after the power supply for the control system is turned OFF.
- Do not disconnect the cable or turn OFF the power supply to the Controller when downloading data or the user program from Support Software.
- Always turn OFF the power supply to the Controller before you attempt any of the following.
  - a) Mounting or removing the Units
  - b) Assembling the Units
  - c) Setting DIP switches or rotary switches
  - d) Connecting cables or wiring the system
  - e) Connecting or disconnecting the terminal blocks or connectors

The power supply circuit in the CPU Unit may continue to supply power to the Controller for a few seconds after the power supply turns OFF. The POWER indicator is lit during this time. Confirm that the POWER indicator is not lit before you perform any of the above.

### **Operation**

- · Confirm that no adverse effect will occur in the system before you attempt any of the following.
  - a) Changing the operating mode of the CPU Unit (including changing the setting of the Startup Mode)
  - b) Changing the user program or settings
  - c) Changing set values or present values
  - d) Forced refreshing
  - e) Starting the CPU Unit with the battery exhausted
  - f) Restarting a slave or Unit after you change any settings
  - g) Transferring a backup file on the SD Memory Card
- After you change any slave or Unit settings, carefully check the safety of the controlled system before you restart the Unit.
- If two different function modules are used together, such as when you use EtherNet/IP and Ether-CAT slaves, take suitable measures in the user program and external controls to ensure that safety is maintained in the controlled system if one of the function modules stops. The relevant outputs will behave according to the slave or Unit specifications if a partial fault level error occurs in one of the function modules.
- Always confirm safety at the connected equipment before you reset Controller errors with an event level of partial fault or higher for the EtherCAT Master Function Module.
  - When the error is reset, all slaves that were in any state other than Operational state due to a Controller error with an event level of partial fault or higher (in which outputs are disabled) will go to Operational state and the outputs will be enabled.
  - Before you reset all errors or restart a slave, confirm that no Controller errors with an event level of partial fault have occurred for the EtherCAT Master Function Module.

## **Designing Tasks**

- If the following variables are specified for a condition expression when the execution condition of
  event tasks is the same as the condition expression for a variable, event tasks may not be executed
  when conditions are met, or event tasks may be executed when conditions are not met.
  - a) Structure members whose data size is 16 bits or more, except for system-defined variables for motion control
  - b) Array elements whose data size is 16 bits or more Refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for information on event task execution conditions.

## **Battery Backup**

• If you use the clock data in the user program and turn OFF the power supply for a long time, use a Battery which is sold separately.

- The Battery is not mounted when the product is at factory setting. The clock data is retained by the built-in capacitor. The capacitor is charged while the power is supplied and discharged while the power is not supplied. If the power OFF time rate is high, the clock data is initialized and malfunctions may occur in the program for which the clock data is used.
- · If you use the Battery, connect the Sysmac Studio and set the Battery-related error detection to Use. The Battery-related error detection is set to Do not use at the factory setting because the Battery is not built in. If the Battery-related error detection is set to Do not use, an error cannot be detected when the Battery is exhausted and malfunctions may occur in the program for which the clock data is used.

## Debugging

- · Forced refreshing ignores the results of user program execution and refreshes I/O with the specified values. If forced refreshing is used for inputs for which I/O refreshing is not supported, the inputs will first take the specified values, but they will then be overwritten by the user program. Be careful that this operation differs from the force-set/reset functionality of the CJ/CP-series PLCs.
- · You cannot upload or download information for forced refreshing with the Sysmac Studio. After downloading data that contains forced refreshing, change to RUN mode and then use the Sysmac Studio to perform the operation for forced refreshing. Depending on the difference in the forced status, the control system may operate unexpectedly.
- Do not specify the same address for the AT specification for more than one variable. Doing so would allow the same entity to be accessed with different variable names, which would make the user program more difficult to understand and possibly cause programming mistakes.

### **General Communications**

- When you use data link communications, check the error information that is given in ErrSta (Controller Error Status) to make sure that no error has occurred in the source device. Create a user program that uses reception data only when there is no error in the source device.
  - If there is an error in the source device, the data for the data link may contain incorrect values.
- Unexpected operation may result if inappropriate data link tables are set. Even if appropriate data link tables have been set, confirm that the controlled system will not be adversely affected before you transfer the data link tables. The data links start automatically after the data link tables are transferred.

### **EtherNet/IP Communications**

- · Make sure to use the communications distance, number of nodes connected, and method of connection for EtherNet/IP within specifications. Do not connect EtherNet/IP communications to Ether-CAT or other networks. An overload may cause the network to fail or malfunction.
- All related EtherNet/IP nodes are reset when you transfer settings for the built-in EtherNet/IP port (including IP addresses and tag data links settings). The settings can only be enabled after the reset. Confirm that the system will not be adversely affected by resetting nodes before you transfer the settings.
- · If EtherNet/IP tag data links (cyclic communications) are used with a repeating hub, the communications load on the network will increase. This will increase collisions and may prevent stable

communications. Do not use repeating hubs on networks where tag data links are used. Use an Ethernet switch instead.

### **EtherCAT Communications**

- Make sure to use the communications distance, number of nodes connected, and method of connection for EtherCAT within specifications.
  - Do not connect EtherCAT communications to EtherNet/IP, a standard in-house LAN, or other networks. An overload may cause the network to fail or malfunction.
- Malfunctions or unexpected operation may occur for some combinations of EtherCAT revisions of
  the master and slaves. If you disable the revision check in the network settings, use the Sysmac
  Studio to check the slave revision settings in the master and the actual slave revisions, and then
  make sure that functionality is compatible in the slave manuals or other references. You can check
  the actual slave revisions from the Sysmac Studio or on slave nameplates.
- After you transfer the user program, the CPU Unit is restarted and communications with the Ether-CAT slaves are cut off. During that period, the slave outputs behave according to the slave specifications. The time that communications are cut off depends on the EtherCAT network configuration.
   Before you transfer the user program, confirm that the system will not be adversely affected.
- If the Fail-soft Operation Setting is set to Stop, process data communications will stop for all slaves when an EtherCAT communications error is detected in a slave. At that time, the Servo Drive will operate according to the Servo Drive specifications. Make sure that the Fail-soft Operation setting results in safe operation when a device error occurs.
- Even if the Process Data Communication is stopped and subsequently restored automatically, take
  the external safety measures or set the Fail-soft Operation Settings to Stop to make the system operate safe.
- EtherCAT communications are not always established immediately after the power supply is turned ON. Use the system-defined variables in the user program to confirm that communications are established before attempting control operations.
- If noise occurs or an EtherCAT slave is disconnected from the network, any current communications
  frames may be lost. If frames are lost, slave I/O data is not communicated, and unintended operation may occur. The slave outputs will behave according to the slave specifications. Refer to the
  manual for the slave. If a noise countermeasure or slave replacement is required, perform the following processing.
  - a) Program the Input Data Invalid system-defined variable as an interlock condition in the user program.
  - b) Set the **PDO communications timeout detection count** setting in the EtherCAT master to at least 2. Refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual (Cat. No. W505)* for details.
- When an EtherCAT slave is disconnected, communications will stop and control of the outputs will
  be lost not only for the disconnected slave, but for all slaves connected after it through to the physical end node. Confirm that the system will not be adversely affected before you disconnect a slave.
  At the location in cable redundancy state, only the relevant slave stops communications.
- I/O data communications of NX bus are not always established immediately after the power supply
  is turned ON. Use the system-defined variables and the EtherCAT Coupler Unit device variables in
  the user program to confirm that I/O data communications are established before attempting control
  operations.

- You cannot use standard Ethernet hubs or repeater hubs with EtherCAT communications. If you use
  one of these, a major fault level error or other error may occur.
- If the actual configuration changes, for example, when actual configuration does not contain a disable slave and subsequently you include it in the actual configuration, set the total cable length for the case of the worst scenario.
- Confirm that all of the slaves are connected before you set the transmission delay time by the actual
  measurement. If the transmission delay time is exceeded from the set values due to the changes of
  the unit configuration, such as when the disabled salve is connected to the actual configuration after
  the setting, it may cause illegal communications with slaves.
- When the communications cable that is connected to the slave from other manufacturers on the ring topology is broken or the power supply to the slave from other manufacturers is interrupted, any current communications frames may be lost.
  - If frames are lost, slave I/O data is not communicated, and unintended operation may occur. When slaves from other manufacturers are connected on the ring topology, check the followings in advance.
  - a) Disconnect and connect communications cables that are connected to the output ports of slaves from other manufacturers several times, and there is no error except for a *Ring Disconnection Detected*.
  - b) Disconnect and connect communications cables that are connected to the input ports of slaves from other manufacturers several times, and there is no error except for a *Ring Disconnection Detected*.
  - c) Turn OFF and ON the power supply to the slaves from other manufacturers, and there is no error except for a *Illegal Slave Disconnection Detected*.
- If you use the cable redundancy function, confirm that the task execution time is within the task period while the cable for the end port of the ring is disconnected. When a disconnection occurred on the ring topology, the transmission delay time is increased and the task execution time may be longer.



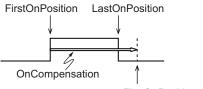
### **Version Information**

The cable redundancy function can be used with project unit version 1.40 or later.

### **Motion control**

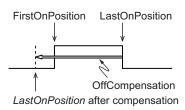
- Confirm the axis number carefully before you perform an MC Test Run.
- The motor is stopped if communications are interrupted between the Sysmac Studio and the CPU
   Unit during an MC Test Run. Connect the communications cable between the computer and CPU
   Unit securely and confirm that the system will not be adversely affected before you perform an MC
   Test Run.
- Always execute the Save Cam Table instruction if you change any of the cam data from the user
  program in the CPU Unit or from the Sysmac Studio. If the cam data is not saved, the previous condition will be restored when the power is turned ON again, possibly causing unexpected machine
  operation.
- The positive drive prohibit input (POT), negative drive prohibit input (NOT), and home proximity input (DEC) of the Servo Drive are used by the MC Function Module as the positive limit input, negative limit input, and home proximity input. Make sure that the signal widths for all of these input signals are longer than the control period of the MC Function Module. If the input signal widths are

- shorter than the control period, the MC Function Module may not be able to detect the input signals, resulting in incorrect operation.
- If you make any changes in the Detailed Settings Area of the Axis Basic Settings Display of the Sysmac Studio, make sure that the devices or machines perform the expected operation before you start actual operation.
  - If the relationship between the functions of the Motion Control Function Module and the EtherCAT slave process data that is assigned to the axes is not correct, the devices or machines may perform unexpected operation.
- Always use the axis at a constant velocity for the MC\_DigitalCamSwitch (Enable Digital Cam Switch) instruction.
  - If you set the Count Mode to Rotary Mode, the following operation will occur if you use OnCompensation or OffCompensation and the axis velocity changes abruptly.
  - a) If the value of OnCompensation or OffCompensation is equivalent to the time for half a rotation or more, InOperation will be FALSE.
  - b) If the value of OnCompensation results in exceeding LastOnPosition, the output timing will be unstable.



FirstOnPosition after compensation

c) If the value of OffCompensation results in exceeding FirstOnPosition, the output timing will be unstable.



- Use the NX\_AryDOutTimeStamp (Write Digital Output Array with Specified Time Stamp) instruction
  only after you confirm that InOperation from the MC\_DigitalCamSwitch (Enable Digital Cam Switch)
  instruction is TRUE.
- If you change the unit conversion settings, perform homing again. If you do not perform homing, unintended operation of the controlled system may occur.
- Do not execute the following instructions to change the cam table which is in operation. Otherwise, an unintended operation may occur.
  - a) MC\_SetCamTableProperty (Setting cam table properties) instruction
  - b) MC SetCamTableEndPointIndex (Setting cam table end point index) instruction
  - c) MC GenerateCamTable (Generating cam tables) instruction

## **Backing Up Data**

 Backup function allows to save various setting data in the Controller to an SD Memory Card or a computer. If you back up data when the operating mode is set to the RUN mode, the concurrency of variables with a Retain attribute (i.e., structure and array variables of two bytes or more) may be lost. To ensure data concurrency, we recommend that you back up data when the operating mode is set to PROGRAM mode.

 We recommend that you back up the present values of variables while the retained variables are not refreshed.

If you back up variables while the values of retained variables are refreshed, the data may not be saved correctly.

Refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for details on the backup function and backing up the present values of variables.

## **Restoring Data**

- You cannot back up, restore, or compare some or all of the settings for certain slaves and Units.
   Also, you cannot back up, restore, or compare data for disabled slaves or Units. After you restore data, sufficiently confirm that operation is correct before you start actual operation.
- If any of the following conditions is met, clear the absolute encoder home offsets from the list of data items to restore, and then restore the data. Then, define the absolute encoder home again. If you do not define home, unintended operation of the controlled system may occur.
  - a) The Servomotor or Servo Drive was changed since the data was backed up.
  - b) The absolute encoder was set up after the data was backed up.
  - c) The absolute data for the absolute encoder was lost.

## **Transferring Programs**

- When you use the program transfer from SD Memory Card whose Startup Mode setting is set to RUN mode, the operating mode changes to RUN after the transfer is completed regardless of the status and setting before the transfer. Use this function after you confirm that system startup does not cause any problem.
- Always confirm safety at the connected equipment before you perform the following operations
  when the device output hold configuration is set to enable. The equipment may operate unexpectedly because the last status for outputs is retained.
  - a) Changing the operating mode of the CPU Unit
  - b) When downloaded
- When you transfer the values retained in the memory of the CJ-series Units, always check the set values of the Device Output Hold Configuration and make sure that the destination is safe.
   The devices or machines may perform unexpected operation regardless of the operating mode of the CPU Unit.

# **Battery Installation and Replacement**

- The Battery may leak, rupture, heat, or ignite. Never short-circuit, charge, disassemble, heat, or incinerate the Battery or subject it to strong shock.
- Dispose of any Battery that has been dropped on the floor or otherwise subjected to excessive shock. Batteries that have been subjected to shock may leak if they are used.

- Apply power for at least five minutes before changing the Battery. Install a new Battery within five minutes (at 25°C) of turning OFF the power supply. If power is not supplied for at least 5 minutes, the retained clock data may be initialized.
- We recommend mounting or replacing the Battery with the power turned OFF to prevent the CPU
  Unit's sensitive internal components from being damaged by static electricity and to prevent malfunctions. The Battery can be mounted or replaced without turning OFF the power supply. To do so,
  always touch a grounded piece of metal to discharge static electricity from your body before you
  start the procedure.

If the Low Battery Voltage error occurs after you mount the Battery, connect the Sysmac Studio and clear the error.

## **Unit Replacement**

- Make sure that the required data, including the user program, configurations, settings, and variables, is transferred to a CPU Unit that was replaced and to externally connected devices before restarting operation. Be sure to include the tag data link settings and routing tables, which are stored in the CPU Unit.
- The absolute encoder home offsets are retained in the CPU Unit as absolute encoder information.
   When you change the combination of the CPU Unit and Servomotor, e.g., when you add or replace a Servomotor, define the absolute encoder home again.
- Always turn OFF the Unit power supply and I/O power supply before you remove the NX Unit.

## Disposal

· Dispose of the Units and Batteries according to local ordinances as they apply.



• The following information must be displayed for all products that contain primary lithium batteries with a perchlorate content of 6 ppb or higher when shipped to or transported through the State of California, USA.

Perchlorate Material - special handling may apply.

 $See\ www.dtsc.ca.gov/hazardouswaste/perchlorate.$ 

The Battery is a primary lithium battery with a perchlorate content of 6 ppb or higher. Place the
above information on the individual boxes and shipping boxes when shipping finished products that
contain a CPU Unit with a mounted Battery to the State of California, USA.

# **Precautions for Correct Use**

# Storage and Installation

- Follow the instructions in this manual to correctly perform installation.
- Do not operate or store the Controller in the following locations. Doing so may result in burning, in operation stopping, or in malfunction.
  - a) Locations subject to direct sunlight
  - b) Locations subject to temperatures or humidity outside the range specified in the specifications
  - c) Locations subject to condensation as the result of severe changes in temperature
  - d) Locations subject to corrosive or flammable gases
  - e) Locations subject to dust (especially iron dust) or salts
  - f) Locations subject to exposure to water, oil, or chemicals
  - g) Locations subject to shock or vibration
- Take appropriate and sufficient countermeasures when installing the Controller in the following locations.
  - a) Locations subject to strong, high-frequency noise
  - b) Locations subject to static electricity or other forms of noise
  - c) Locations subject to strong electromagnetic fields
  - d) Locations subject to possible exposure to radioactivity
  - e) Locations close to power lines
- Before touching a Unit, be sure to first touch a grounded metallic object in order to discharge any static build-up.
- Install the Controller away from sources of heat and ensure proper ventilation. Not doing so may result in malfunction, in operation stopping, or in burning.
- If you use a Controller that has not been operated for more than half a year, check that there is no error when the power is supplied.

# Mounting

- When you install the Unit, be careful not to touch or bump the pins in the NX bus connector.
- When you handle the Unit, be careful not to apply stress to the pins in the NX bus connector.
   If the Unit is installed and the power supply is turned ON when the pins in the connector are deformed, contact failure may cause malfunctions.
- Always mount an End Cover to the end of the CPU Rack to protect the last Unit on the CPU Rack.
   Not mounting the End Cover may result in malfunction or failure of the CPU Unit.
- After you mount the Unit, always secure it with End Plates at both sides. If you do not secure it, the Unit may be damaged or malfunction.
- If you use DIN Track Insulation Spacers to install a CPU Rack, the height will be increased by approximately 10 mm. Make sure that the CPU Rack and connecting cables do not come into contact with other devices.

### Wiring

- Do not allow foreign matter to enter the openings in the Unit. Doing so may result in Unit burning, electric shock, or failure.
- Do not allow wire clippings, shavings, or other foreign material to enter any Unit. Otherwise, Unit burning, failure, or malfunction may occur. Cover the Units or take other suitable countermeasures, especially during wiring work.
- For EtherCAT and EtherNet/IP, use the connection methods and cables that are specified in the
   *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual* (Cat. No. W505) and the *NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual* (Cat. No. W506). Otherwise, communications may
   be faulty.
- Use the rated power supply voltage for the Units that supply power. Take appropriate measures to
  ensure that the specified power with the rated voltage and frequency is supplied in places where the
  power supply is unstable.
- Make sure that the current capacity of the wire is sufficient. Otherwise, excessive heat may be generated. When cross-wiring terminals, the total current for all the terminals will flow in the wire. When wiring cross-overs, make sure that the current capacity of each of the wires is not exceeded.
- If you use reed switches for the input contacts for AC Input Units, use switches with a current capacity of 1 A or greater.
  - If reed switches with smaller allowable currents are used, the contacts may fuse due to surge currents.

## **Operation**

- Confirm the device output hold configuration before you change the operating mode of the CPU Unit
  or execute the download.
- Take safety measures for the controlled system as well.

## **Error Processing**

- In applications that use the results of instructions that read the error status, consider the affect on
  the system when errors are detected and program error processing accordingly. For example, even
  the detection of a minor error, such as Battery replacement during operation, can affect the system
  depending on how the user program is written.
- If you change the event level of a Controller error, the output status when the error occurs may also change. Confirm safety before use.

# **Restoring and Automatically Transferring Data**

- When you edit the restore command file or the automatic transfer command file, do not change anything in the file except for the "yes" and "no" specifications for the selectable data groups. If you change anything else in the file, the Controller may perform unexpected operation when you restore or automatically transfer the data.
- To prevent an unexpected restoration, set to enter the password for each execution before the restore operation.

### **Transferring Programs**

 If you use the program transfer from SD Memory Card, set to enter the password for each execution to prevent an unexpected program transfer.

### **Replacing Slaves and Units**

• If you replace a slave or Unit, refer to the operation manual for the slave or Unit for information on the data required for individual slaves or Units and redo the necessary settings.

# **Task Settings**

 If a Task Period Exceeded error occurs, shorten the programs to fit in the task period or increase the setting of the task period.

### **Motion Control**

- Use the system-defined variable in the user program to confirm that EtherCAT communications are
  established before you attempt to execute motion control instructions. Motion control instructions are
  not executed normally if EtherCAT communications are not established.
- Use the system-defined variables to monitor for errors in communications with the slaves that are controlled by the motion control function module. Motion control instructions are not executed normally if an error occur in slave communications.
- · Before you start an MC Test Run, make sure that the operation parameters are set correctly.
- · Do not download motion control settings during an MC Test Run.

### **EtherCAT Communications**

- If you need to disconnect an EtherCAT slave cable during an operation, specify the disconnection of the software connection of the EtherCAT slave first.
  - Apply the *Disable* function for those EtherCAT slaves which you plan to replace in the future. If you need to replace an EtherCAT slave due to a failure or other troubles, be sure to specify disconnecting the software connection.
- If you replace a slave or Unit, refer to the operation manual for the slave or Unit for information on the data required for individual slaves or Units and redo the necessary settings.
- Set the Servo Drives to stop operation if an error occurs in EtherCAT communications between the Controller and a Servo Drive.
- Make sure that all of the slaves to be restored are participating in the network before you reset a Network Configuration Verification Error, Network Configuration Verification Error (Mismatched Slave), Network Configuration Verification Error (Slave Unconnected), Network Configuration Verification Error (Unnecessary Slave Connected), Network Configuration Verification Error (Incorrect Ring Wiring), Process Data Communications Error, Illegal Slave Disconnection Detected or Link OFF Error in the EtherCAT Master Function Module. If any slave is not participating when any of these errors is reset, the EtherCAT Master Function Module may access salve with a different node address than the specified node address or the error may not be reset correctly.

- Always use the specified EtherCAT slave cables. If you use any other cable, the EtherCAT master
  or the EtherCAT slaves may detect an error and one of the following may occur.
  - a) Continuous refreshing of process data communications will not be possible.
  - b) Continuous refreshing of process data communications will not end during the set cycle.
- If you execute a clear operation of diagnostic and statistical information during readout of the diagnostic and statistical information, the diagnostic and statistical information that is cleared to 0 may be read.

#### **Battery Replacement**

- Be sure to mount a Battery within two years of the production date shown on the Battery label.
- Turn ON the power after replacing the Battery for a CPU Unit that has been unused for a long time.
   Leaving the CPU Unit unused again without turning ON the power even once after the Battery is replaced may result in a shorter Battery life.
- If you use the Battery, use the CJ1W-BAT01 Battery Set which is sold separately.

#### **SD Memory Cards**

- · Insert the SD Memory Card all the way.
- Do not turn OFF the power supply to the Controller during SD Memory Card access. The files may be corrupted.
  - If there is a corrupted file in the SD Memory Card, the file is automatically deleted by the restoration function when the power supply is turned ON.
- If you use an OMRON SD Memory Card, the end of the life of the SD Memory Card can be detected
  in the following ways.
  - a) \_Card1Deteriorated (SD Memory Card Life Warning Flag) system-defined variable
  - b) SD Memory Card Life Exceeded (Observation) event in the event log
    When the end of the life is detected in any of the above ways, replace the SD Memory Card.



#### **Version Information**

Combination of the CPU Unit version and SD Memory Card determines whether the SD memory card life expiration detection function can be used or not. Refer to *Specification of Supported SD Memory Cards, Folders, and Files* in the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for details.

#### **Debugging**

- When performing online editing, the CPU Unit saves a program updated by the online editing to built-in non-volatile memory. Sysmac Studio shows a message that it is in a backup operation. Do not turn OFF the power supply to the Controller while this message is displayed. If the power supply to the Controller is turned OFF, a Controller error will occur when the power supply is turned ON next time.
- Data Tracing allows to sample the variables without any additional programming.
   If you set sampling to be performed on a specified task period and use data tracing to sample an internal variable with a data size of 64 bits or more, members of a structure variable except for system-defined variable for motion control, or the elements of an array variable, specify the task that

assigns the program in which the target variable is defined or the program that refreshes the variable for the sampling interval.

- If a different task is specified, the concurrency of variable values may not be ensured.
- · If you use data tracing to sample the following variables, correct data may not be sampled.
  - a) Structure members whose data size is 16 bits or more, except for system-defined variables for motion control
  - b) Array elements whose data size is 16 bits or more Refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for information on data tracing.

#### **Secure Communication**

- If you transfer a project with project unit version earlier than 1.69 to a CPU Unit that is set to use secure communications version 2, the CPU Unit's secure communications version will be changed to 1.
- If you restore a backup file with project unit version earlier than 1.69 to a CPU Unit that is set to use secure communications version 2, the CPU Unit's secure communications version will be changed to 1
- Setting the secure communications version to 2 always enables user authentication. When user authentication is enabled, users are required to enter their user name and password to go online.
- When you use a CPU Unit that is set to use secure communications version 2 and an NA-series
   Programmable Terminal that supports secure communication, please note that there is the following
   restriction.

The troubleshooter function of the NA-series Programmable Terminal cannot be used.

- When you use a CPU Unit that is set to use secure communications version 2 with an NA-series
  Programmable Terminal and Soft-NA that do not support secure communication, please note that
  there are the following restrictions.
  - a) The NA-series Programmable Terminal cannot be connected.
  - b) The troubleshooter of the NS-series Programmable Terminal cannot be used.

#### Disposal

When disposing of or transferring our products, information such as user data stored in the device
may be seen by third parties, resulting in information leakage. It is recommended that you erase the
data on your responsibility before disposing of or transferring the device. Omron shall not be liable
for any loss, damage, or other expenses incurred directly or indirectly in the event of any information
leakage due to disposal or transfer.

For details on *complete data erasure function* for completely erasing user data, refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)*.

## **Regulations and Standards**

#### **Conformance to EU Directives**

#### **Applicable Directives**

- · EMC Directives
- · Low Voltage Directive

#### **Concepts**

#### EMC Directives

OMRON devices that comply with EU Directives also conform to the related EMC standards so that they can be more easily built into other devices or the overall machine. The actual products have been checked for conformity to EMC standards.\*1

Whether the products conform to the standards in the system used by the customer, however, must be checked by the customer. EMC-related performance of the OMRON devices that comply with EU Directives will vary depending on the configuration, wiring, and other conditions of the equipment or control panel on which the OMRON devices are installed. The customer must, therefore, perform the final check to confirm that devices and the overall machine conform to EMC standards.

\*1. Applicable EMC (Electromagnetic Compatibility) standards are as follows: EMS (Electromagnetic Susceptibility): EN 61131-2 EMI (Electromagnetic Interference): EN 61131-2 (Radiated emission: 10-m regulations).

#### Low Voltage Directive

Always ensure that devices operating at voltages of 50 to 1,000 VAC and 75 to 1,500 VDC meet the required safety standards. The applicable directive is EN 61010-2-201.

#### Conformance to EU Directives

The NX-series Units comply with EU Directives. To ensure that the machine or device in which the NX-series Units are used complies with EU Directives, the following precautions must be observed.

- The NX-series Units must be installed within a control panel.
- You must use SELV power supply for the DC power supplies that are connected as the Unit power supplies and I/O power supplies for the NX-series Units. EMC standard compliance was confirmed for the OMRON S8VK-S Series DC Power Supplies.
- NX-series Units that comply with EU Directives also conform to the Common Emission Standard.
  Radiated emission characteristics (10-m regulations) may vary depending on the configuration of
  the control panel used, other devices connected to the control panel, wiring, and other conditions.
  - You must therefore confirm that the overall machine or equipment in which the NX-series Units are used complies with EU Directives.
- This is a Class A product (for industrial environments). In a residential environment, it may cause radio interference. If radio interference occurs, the user may be required to take appropriate measures.

#### Conformance to UL and CSA Standards

Some NX-series products comply with UL and CSA standards.

If you use a product that complies with UL or CSA standards and must apply those standards to your machinery or devices, refer to the *Instruction Sheet* that is provided with the product. The *Instruction Sheet* provides the application conditions for complying with the standards.

#### **Conformance to KC Certification**

When you use this product in South Korea, observe the following precautions.

#### 사용자안내문

이 기기는 업무용 환경에서 사용할 목적으로 적합성평가를 받은 기기로서 가정용 환경에서 사용하는 경우 전파간섭의 우려가 있습니다.

This product meets the electromagnetic compatibility requirements for business use. There is a risk of radio interference when this product is used in home.

#### **Usage Conditions for KC Certification**

Take the same measures as those described in *Conformance to EU Directives* on page 37. In addition, attach a clamp core to the port side of the EtherNet/IP cable.

The recommended clamp core is given below.

#### **Recommended Clamp Core**

Manufacturer	Product	Model	Turns of cable
TOKIN	Clamp core	ESD-SR-250	1 turn

#### **Conformance to Shipbuilding Standards**

This product complies with the following shipbuilding standards. Applicability to the shipbuilding standards is based on certain usage conditions. It may not be possible to use the product in some locations. Contact your OMRON representative before attempting to use a Controller on a ship.

#### Usage Conditions for NK and LR Shipbuilding Standards

- · This product must be installed within a control panel.
- Gaps in the door to the control panel must be completely filled or covered with gaskets or other material.
- The following noise filter must be connected to the power supply line.

#### **Noise Filter**

Manufacturer	Model
Cosel Co., Ltd.	TAH-06-683

#### **Software Licenses and Copyrights**

This product incorporates certain third party software. The license and copyright information associated with this software is available at http://www.fa.omron.co.jp/nj\_info\_e/.

#### Versions

Hardware revisions and unit versions are used to manage the hardware and software in NX-series Units and EtherCAT slaves.

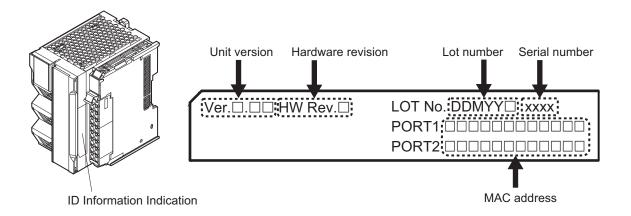
The hardware revision or unit version is updated each time there is a change in hardware or software specifications. Even when two Units or EtherCAT slaves have the same model number, they will have functional or performance differences if they have different hardware revisions or unit versions.

#### **Checking Versions**

You can check versions in the ID information indications on the product or with the Sysmac Studio.

#### **Checking Unit Versions on ID Information Indications**

The unit version is given on the ID information indication on the side of the product. The ID information on an NX-series CPU Unit NX102- $\square$ 00 is shown below.



Note The hardware revision is not displayed for the Unit that the hardware revision is in blank.

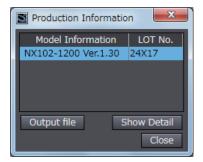
#### **Checking Unit Versions with the Sysmac Studio**

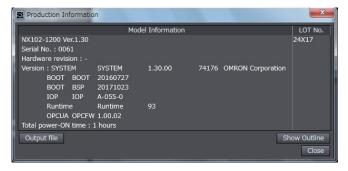
#### Checking the Unit Version of a Unit

You can use the **Production Information** while the Sysmac Studio is online to check the unit version of a Unit. You can do this for the CPU Unit and NX Units on the CPU Rack. Use the following procedure to check the unit version.

- 1 Right-click CPU Rack under Configurations and Setup CPU/Expansion Racks in the Multi-view Explorer and select Display Production Information.
  The Production Information Dialog Box is displayed.
- Click the Show Detail or Show Outline Button at the lower right of the Production Information Dialog Box.

The view will change between the **Production Information** details and outline.





Outline View

**Detail View** 

The information that is displayed is different for the Outline View and Detail View. The Detail View displays the unit version, hardware version, and software versions. The Outline View displays only the unit version.

**Note** The hardware revision is separated by "/" and displayed on the right of the hardware version. The hardware revision is not displayed for the Unit that the hardware revision is in blank.

#### Checking the Unit Version of an EtherCAT Slave

You can use the **Production Information** while the Sysmac Studio is online to check the unit version of an EtherCAT slave. Use the following procedure to check the unit version.

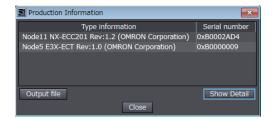
- 1 Double-click **EtherCAT** under **Configurations and Setup** in the Multiview Explorer. Or, right-click **EtherCAT** under **Configurations and Setup** and select **Edit** from the menu.

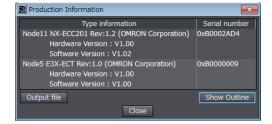
  The EtherCAT Tab Page is displayed for the Controller Configurations and Setup Layer.
- **2** Right-click the master on the EtherCAT Tab Page and select **Display Production Information**. The Production Information Dialog Box is displayed. The unit version is displayed after "Rev."

#### Changing Information Displayed in Production Information Dialog Box

1 Click the Show Detail or Show Outline Button at the lower right of the Production Information Dialog Box.

The view will change between the **Production information** details and outline.





Outline View

**Detail View** 

#### **Unit Versions of CPU Units and Sysmac Studio Versions**

The functions that are supported depend on the unit version of the NX-series CPU Unit. The version of Sysmac Studio that supports the functions that were added for an upgrade is also required to use those functions.

Refer to *Version Information for NX-series Controllers* in the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for the relationship between the unit versions of the CPU Units and the Sysmac Studio versions, and for the functions that are supported by each unit version.

# **Related Manuals**

The following manuals are related. Use these manuals for reference.

Manual name	Cat. No.	Model numbers	Application	Description
NX-series	W593	NX102-□□□	Learning the basic	An introduction to the entire NX102
NX102 CPU Unit			specifications of the	system is provided along with the fol-
Hardware			NX102 CPU Units,	lowing information on the CPU Unit.
User's Manual			including introductory	Features and system configura
			information, design-	tion
			ing, installation, and maintenance.	• Introduction
				Part names and functions
			Mainly hardware in- formation is provid-	General specifications
			ed.	Installation and wiring
				Maintenance and inspection
NJ/NX-series CPU Unit	W501	NX701-□□□□	Learning how to pro-	The following information is provided
Software User's Manual		NX502-□□□□	gram and set up an	on a Controller built with an NJ/NX-
		NX102-□□□□	NJ/NX-series CPU	series CPU Unit.
		NX1P2-□□□□	Unit.	CPU Unit operation
		NJ501-□□□□	Mainly software in-	CPU Unit features
		NJ301-□□□□	formation is provid-	Initial settings
		NJ101-□□□□	ed.	Programming based on IEC
				61131-3 language specifications
NJ/NX-series Instructions	W502	NX701-□□□□	Learning detailed	The instructions in the instruction set
Reference Manual		NX502-□□□□	specifications on the	(IEC 61131-3 specifications) are de-
		NX102-□□□□	basic instructions of	scribed.
		NX1P2-□□□□	an NJ/NX-series	
		NJ501-□□□□	CPU Unit.	
		NJ301-□□□□		
		NJ101-□□□□		
NJ/NX-series CPU Unit	W507	NX701-□□□□	Learning about mo-	The settings and operation of the
Motion Control User's		NX502-□□□□	tion control settings	CPU Unit and programming con-
Manual		NX102-□□□□	and programming	cepts for motion control are descri-
		NX1P2-□□□□	concepts.	bed.
		NJ501-□□□□		
		NJ301-□□□□		
		NJ101-□□□□		
NJ/NX-series	W508	NX701-□□□□	Learning about the	The motion control instructions are
Motion Control Instructions		NX502-□□□□	specifications of the	described.
Reference Manual		NX102-□□□□	motion control in-	
		NX1P2-□□□□	structions.	
		NJ501-□□□□		
		NJ301-□□□□		
		NJ101-□□□□		
NJ/NX-series	W505	NX701-□□□□	Using the built-in	Information on the built-in EtherCAT
CPU Unit		NX502-□□□□	EtherCAT port on an	port is provided.
Built-in EtherCAT® Port		NX102-□□□□	NJ/NX-series CPU	This manual provides an introduction
User's Manual		NX1P2-□□□□	Unit.	and provides information on the con-
		NJ501-□□□□		figuration, features, and setup.
		NJ301-□□□□		
		NJ101-□□□□		

Manual name	Cat. No.	Model numbers	Application	Description
NJ/NX-series	W506	NX701-□□□□	Using the built-in	Information on the built-in
CPU Unit		NX502-□□□□	EtherNet/IP port on	EtherNet/IP port is provided.
Built-in EtherNet/IP <sup>™</sup> Port		NX102-□□□□	an NJ/NX-series	Information is provided on the basic
User's Manual		NX1P2-□□□□	CPU Unit.	setup, tag data links, and other fea-
		NJ501-□□□□		tures.
		NJ301-□□□□		
		NJ101-□□□□		
NJ/NX-series	W588	NX701-□□□□	Using the OPC UA.	Describes the OPC UA.
CPU Unit		NX502-□□□□		
OPC UA		NX102-□□□□		
User's Manual		NJ501-1□00		
NX-series	W596	NX701-□□20	Using the FINS func-	Describes the FINS function of an
CPU Unit		NX502-□□□□	tion of an NX-series	NX-series CPU Unit.
FINS Function		NX102-□□□□	CPU Unit.	
User's Manual				
NJ/NX-series	W527	NX701-□□20	Using the database	Describes the database connection
Database Connection CPU		NX502-□□□□	connection service	service.
Units		NX102-□□20	with NJ/NX-series	
User's Manual		NJ501-□□20	Controllers.	
		NJ101-□□20		
NJ/NX-series	W503	NX701-□□□□	Learning about the	Concepts on managing errors that
Troubleshooting Manual		NX502-□□□□	errors that may be	may be detected in an NJ/NX-series
Ŭ		NX102-□□□□	detected in an	Controller and information on individ-
		NX1P2-□□□□	NJ/NX-series Con-	ual errors are described.
		NJ501-□□□□	troller.	
		NJ301-□□□□		
		NJ101-□□□□		
Sysmac Studio Version 1	W504	SYSMAC	Learning about the	Describes the operating procedures
Operation Manual		-SE2□□□	operating procedures	of the Sysmac Studio.
•			and functions of the	,
			Sysmac Studio.	
NX-series	W519	NX-ECC 🗆 🗆	Learning how to use	The following items are described:
EtherCAT® Coupler Unit			the NX-series Ether-	the overall system and configuration
User's Manual			CAT Coupler Unit	methods of an EtherCAT Slave Ter-
USEI S Mariuai			and EtherCAT Slave	minal (which consists of an NX-ser-
			Terminals.	ies EtherCAT Coupler Unit and NX
				Units), and information on hardware,
				setup, and functions to set up, con-
				trol, and monitor NX Units through
				EtherCAT.
NX-series	W525	NX-00000	Referencing lists of	Lists of the power consumptions,
Data Reference Manual			the data that is re-	weights, and other NX Unit data that
			guired to configure	is required to configure systems with
			systems with NX-ser-	NX-series Units are provided.

Manual name	Cat. No.	Model numbers	Application	Description
NX-series	W521	NX-ID□□□□	Learning how to use	Describes the hardware, setup meth-
NX Units		NX-IA□□□□	NX Units.	ods, and functions of the NX Units.
User's Manual		NX-OC□□□□		Manuals are available for the follow-
		NX-OD□□□□		ing Units.
		NX-MD□□□□		Digital I/O Units, Analog I/O Units,
	W522	NX-AD□□□□		System Units, Position Interface
		NX-DA 🗆 🗆 🗆		Units, Communications Interface
	W592	NX-HAD□□□		Units, Load Cell Input Unit, IO-Link
	W566	NX-TS□□□□		Master Units, and High-speed Counter Units.
		NX-HB□□□□		ter onits.
	W523	NX-PD1□□□		
		NX-PF0□□□		
		NX-PC0□□□		
		NX-TBX01		
	W524	NX-EC0□□□		
		NX-ECS□□□		
		NX-PG0□□□		
	W540	NX-CIF□□□		
	W565	NX-RS□□□□		
	W567	NX-ILM 🗆 🗆		
	W647	NX-CT		
NX-series	Z930	NX-SL□□□□	Learning how to use	Describes the hardware, setup meth-
Safety Control Unit		NX-SI□□□□	NX-series Safety	ods, and functions of the NX-series
User's Manual		NX-SO□□□□	Control Units.	Safety Control Units.
NA-series Programmable	V118	NA5-□□W□□□□(-V□)	Learning about NA-	Describes the pages and object
Terminal			series PT pages and	functions of the NA-series Program-
Software User's Manual			object functions.	mable Terminals.
NS-series Programmable	V073	NS15-□□□□□	Learning how to use	Describes the setup methods, func-
Terminals		NS12-□□□□□	the NS-series Pro-	tions, etc. of the NS-series Program-
Programming Manual		NS10-□□□□□	grammable Termi-	mable Terminals.
		NS8-□□□□	nals.	
		NS5-□□□□□		

# **Terminology**

Term	Description
AT	One of the attributes of a variable.
	This attribute allows the user to specify what is assigned to a variable. An I/O
	port or an address in memory used for CJ-series Units can be specified.
CJ-series Unit	Any of the CJ-series Units that can be used with an NJ-series Controller.
memory used for CJ-series Units	One type of I/O memory that contains addresses to which variables can be as-
	signed, for example, when accessing a CJ-series Unit or CJ-series network. It
	can be accessed only with variables with an AT attribute.
CPU Unit	The Unit that serves as the center of control for a Machine Automation Control-
	ler. The CPU Unit executes tasks, refreshes I/O for other Units and slaves, etc. The NJ/NX-series CPU Units include the NX701-□□□□, NX102-□□□□,
	NX1P2-□□□, NJ501-□□□.
EtherCAT Master Function Module	One of the function modules. This function module controls the EtherCAT slaves
Ethoro, tri Master Fahotton Module	as the EtherCAT master.
EtherNet/IP Function Module	One of the function modules. This function module controls the built-in
	EtherNet/IP port.
FB	An acronym for "function block."
FUN	An abbreviation for "function."
I/O port	A logical interface that is used by the CPU Unit to exchange data with an exter-
	nal device (slave or Unit).
I/O map settings	Settings that assign variables to I/O ports. Assignment information between I/O
	ports and variables.
I/O refreshing	Cyclic data exchange with external devices that is performed with predetermined
	memory addresses.
MC Test Run	A function to check motor operation and wiring from the Sysmac Studio.
NX bus	An internal bus of the NX-series Controller.
NX Units	Any of the NX-series Units that perform I/O processing with connected external devices. The Communications Coupler Units are not included with the NX Units.
PDO communications	An abbreviation for process data communications. Data is exchanged between
1 DO communications	the master and slaves on a process data communications cycle. (The process
	data communications cycle is the same as the task period of the primary periodic
	task.)
PLC Function Module	One of the function modules. This function module executes the user program,
	sends commands to the Motion Control Function Module, and provides an inter-
	face to the USB and SD Memory Card.
POU	An acronym for "program organization unit". A POU is a unit in a program execu-
	tion model that is defined in IEC 61131-3.
	A POU contains an algorithm and a local variable table and forms the basic unit used to build a user program.
	There are three types of POUs: programs, functions, and function blocks.
SDO communications	One type of EtherCAT communications in which service data objects (SDOs) are
CDC communications	used to transmit information whenever required.
Sysmac Studio	A computer software application for setting, programming, debugging, and trou-
-	bleshooting NJ/NX-series Controllers. It also provides operations for motion con-
	trol and a Simulator.
upload	To transfer data from the Controller to the Sysmac Studio with the synchroniza-
	tion operation of the Sysmac Studio.

Term	Description
information	One of the event levels for Controller events or user-defined events. These are not errors, but appear in the event log to notify the user of specific information.
Event Setup	Settings that define user-defined errors and user-defined information.
event task	A task that executes a user program only once when the task execution conditions are met.
event log	A function that recognizes and records errors and other events.
inline ST	ST programming that is included within a ladder diagram.
edge	One of the attributes of a variable.  This attribute makes a BOOL variable pass TRUE to a function block when the variable changes from FALSE to TRUE or when it changes from TRUE to FALSE.
cam data variable	A variable that represents the cam data as a structure array.  A cam data variable is an array structure that consists of phases and displacements.
observation	One of the event levels for Controller events or user-defined events.  These are minor errors that do not affect control operations, but appear in the event log to notify the user of specific information.
function module	One of the functional units of the software configuration of the CPU Unit.
basic data type	Any of the data types that are defined by IEC 61131-3.  They include Boolean, bit string, integer, real, duration, date, time of day, date and time, and text string data types.  "Basic data type" is used as opposed to derivative data types, which are defined by the user.
forced refreshing	Forcing the refreshing of an input from an external device or an output to an external device, e.g., when the user debugs a program.  Addresses that are subject to forced refreshing can still be overwritten from the user program.
union	One of the derivative data types. It allows you to handle the same data as different data types.
global variable	A variable that can be read or written from all POUs (programs, functions, and function blocks).
minor fault level Controller error	An error for which some of the control operations for one of the function modules in the NJ/NX-series Controller stop.  An NJ/NX-series CPU Unit continues operation even after a minor fault level Controller error occurs.
Special Unit Setup	A generic term for the settings for a Special Unit, including the settings in allocated DM Area words.
structure	One of the derivative data types. It consists of multiple data types placed together into a layered structure.
Constant	One of the attributes of a variable.  If you specify the Constant attribute for a variable, the value of the variable cannot be written by any instructions, ST operators, or CIP message communications.
Controller	The range of devices that are directly controlled by the CPU Unit. In the NX-series System, the Controller includes the CPU Rack and EtherCAT slaves (including general-purpose slaves and Servo Drives). In the NJ-series System, the Controller includes the CPU Rack, Expansion Racks, and EtherCAT slaves (including general-purpose slaves and Servo Drives).

Term	Description
Controller error	Errors that are defined by the NJ/NX-series System.  "Controller error" is a collective term for major fault level, partial fault level, minor fault level, and observation Controller events.
Controller event	One of the events in the NJ/NX-series System. Controller events are errors and information that are defined by the system for user notification. A Controller event occurs when the system detects a factor that is defined as a Controller event.
Controller information	Information that is defined by the NJ/NX-series System that is not an error. It represents an information Controller event.
Servo Drive/encoder input slave	Any of the EtherCAT slaves that is assigned to an axis. In the NJ/NX-series System, it would be a Servo Drive or Encoder Input Slave Unit.
axis	A functional unit within the Motion Control Function Module. An axis is assigned to the drive mechanism in an external Servo Drive or the sensing mechanism in an external Encoder Input Slave Unit.
axes group	A functional unit that groups together axes within the Motion Control Function Module.
Axes Group Variable	A system-defined variable that is defined as a structure and provides status information and some of the axes parameters for an individual axes group.  An Axes Group Variable is used to specify an axes group for motion control instructions and to monitor the command interpolation velocity, error information, and other information for the axes group.
Axis Variable	A system-defined variable that is defined as a structure and provides status information and some of the axis parameters for an individual axis.  An Axis Variable is used to specify an axis for motion control instructions and to monitor the command position, error information, and other information for the axis.
system common processing	System processing that is performed by the CPU Unit to perform I/O refreshing and the user program execution within a task. Exclusive control of variables between tasks, data trace processing, and other processing is performed.
system service	Processing that is performed by the CPU Unit in unused time between task processing. The system service includes communications processing, SD Memory Card access processing, self-diagnosis processing, and other processing.
system-defined variable	A variable for which all attributes are defined by the system and cannot be changed by the user.
Initial Value	One of the attributes of a variable. The variable is set to the initial value in the following situations.  • When power is turned ON  • When the CPU Unit changes to RUN mode  • When you specify to initialize the values when the user program is transferred  • When a major fault level Controller error occurs
slave	A device that performs remote I/O for a master.
Slave Terminal	A building-block remote I/O terminal to which a Communications Coupler Unit and NX Units are mounted. A Slave Terminal is one type of slave.
slave and Unit configurations	A generic term for the EtherCAT configuration and Unit configuration.
absolute encoder home offset	This data is used to restore in the CPU Unit the actual position of a Servo Drive with an absolute encoder. The offset is the difference between the command position after homing and the absolute data that is read from the absolute encoder.
project unit version	A unit version to be set for the project. It is set for the project in the Select Device Area of the Project Properties Dialog Box on the Sysmac Studio.

Term	Description
major fault level Controller error	An error for which all NJ/NX-series Controller control operations stop. The CPU Unit immediately stops user program execution and turns OFF the loads for all slaves and Units (including remote I/O).
download	To transfer data from the Sysmac Studio to the Controller with the synchronization operation of the Sysmac Studio.
task	An attribute that defines when a program is executed.
task period	The interval at which the primary periodic task or a periodic task is executed.
Communications Coupler Unit	The generic name of an interface unit for remote I/O communications on a network between NX Units and a host network master. For example, an EtherCAT Coupler Unit is a Communications Coupler Unit for an EtherCAT network.
periodic task	A tasks for which user program execution and I/O refreshing are performed each period.
device	A general term for any Unit or slave that is refreshed by the I/O refreshing that is performed by the CPU Unit. Specifically, it refers to EtherCAT slaves, NX Units on the CPU Unit, built-in I/O, Option Boards, and CJ-series Units.
device output	An output for any Unit or slave that is refreshed by the I/O refreshing that is performed by the CPU Unit.
device variable	A variable that is used to access a specific device through an I/O port.
synchronization	A function that automatically compares the information in the NJ/NX-series Controller with the information in the Sysmac Studio, displays any differences and locations in a hierarchical form, and can be used to synchronize the information.
namespace	A system that is used to group and nest the names of functions, function block definitions, and data types.
Network Publish	One of the attributes of a variable.  This attribute allows you to use CIP message communications or tag data links to read/write variables from another Controller or from a host computer.
array specification	One of the variable specifications. An array variable contains multiple elements of the same data type. The elements in the array are specified by serial numbers called subscripts that start from the beginning of the array.
derivative data type	A data type that is defined by the user. Structures, unions, and enumerations are derivative data types.
Range Specification	One of the variable specifications. You can specify a range for a variable in advance. The variable can take only values that are in the specified range.
general-purpose slave	Any of the EtherCAT slaves that cannot be assigned to an axis.
function	A POU that is used to create an object that determines a unique output for the same input, such as for data processing.
function block	A POU that is used to create an object that can have a different output for the same input, such as for a timer or counter.
partial fault level Controller error	An error for which all of the control operations for one of the function modules in the NJ/NX-series Controller stop.  An NJ/NX-series CPU Unit continues operation even after a partial fault level Controller error.
primary periodic task	The task with the highest priority.
program	Along with functions and function blocks, one of the three types of POUs.  Programs are assigned to tasks to execute them.
process data communications	One type of EtherCAT communications in which process data objects (PDOs) are used to exchange information cyclically and in realtime. Process data communications are also called PDO communications.

Term	Description
variable	A representation of data, such as a numeric value or character string, that is used in a user program.  You can change the value of a variable by assigned the required value. "Variable" is used as opposed to "constant," for which the value does not change.
variable memory	A memory area that contains the present values of variables that do not have AT specifications. It can be accessed only with variables without an AT attribute.
Retain	One of the attributes of a variable. The values of variables with a Retain attribute are held at the following times. (Variables without a Retain attribute are set to their initial values.)  • When power is turned ON after a power interruption  • When the CPU Unit changes to RUN mode  • When you specify to not initialize the values when the user program is transferred
instruction	The smallest unit of the processing elements that are provided by OMRON for use in POU algorithms.  There are ladder diagram instructions (program inputs and outputs), function instructions, function block instructions, and ST statements.
main memory	The memory inside the CPU Unit that is used by the CPU Unit to execute the OS and user program.
Motion Control Function Module	One of the function modules. The MC Function Module performs motion control based on commands from the motion control instructions that are executed in the user program.
motion control instruction	A function block instruction that executes motion control.  The Motion Control Function Module supports instructions that are based on function blocks for PLCopen® motion control as well as instructions developed
user-defined event	Specifically for the Motion Control Function Module.  One of the events in the NJ/NX-series System. These events are defined by the user. "User-defined events" is a generic term for user-defined errors and user-defined information.
user-defined variable	A variable for which all of the attributes are defined by the user and can be changed by the user.
user program	All of the programs in one project.
Unit	A device that mounts to the CPU Rack or an Expansion Rack.
Unit configuration	The configuration information for the Units that are set on the Sysmac Studio.  This information tells what Unit models are connected to the CPU Unit and where they are connected.
literal	A constant expression that is used in a user program.
enumeration	One of the derivative data types. This data type takes one item from a prepared name list of enumerators as its value.
enumerator	One of the values that an enumeration can take expressed as a character string. The value of an enumeration is one of the enumerators.
local variable	A variable that can be accessed only from inside the POU in which it is defined. "Local variable" is used as opposed to "global variable."  Local variables include internal variables, input variables, output variables, in-out variables, and external variables.

# **Revision History**

A manual revision code appears as a suffix to the catalog number on the front and back covers of the manual.

Revision code	Date	Revised content
01	April 2018	Original production
02	July 2018	Made changes accompanying release of unit version 1.31 of the CPU Unit. Corrected mistakes.
03	April 2019	<ul> <li>Made changes accompanying release of unit version 1.32 of the CPU Unit.</li> <li>Added Shipbuilding Standards (NK and LR).</li> </ul>
04	July 2019	Made changes accompanying release of unit version 1.40 of the NX102-□□00.
05	July 2019	Corrected mistakes.
06	August 2019	Corrected mistakes.
07	October 2020	Corrected mistakes.
08	January 2021	Made changes accompanying release of unit version 1.43 of the NX102-□□00 and unit version 1.36 of the NX102-□□20.
09	July 2021	<ul> <li>Made changes accompanying release of unit version 1.46 of the NX102-££00 and unit version 1.37 of the NX102-££20.</li> <li>Made changes on the information of the SD Memory Card.</li> </ul>
10	April 2022	Added information to Terms and Conditions Agreement.
11	June 2022	<ul> <li>Added descriptions on the DIP switch.</li> <li>Changed descriptions on the accuracy of the internal clock.</li> <li>Corrected mistakes.</li> </ul>
12	July 2022	Revisions for adding safety precautions regarding security.
13	January 2023	Made changes accompanying release of unit version 1.60 of the CPU Unit.
14	October 2023	Changed description of OPC UA server in specifications.
15	July 2025	<ul> <li>Made changes accompanying release of unit version 1.69 of the CPU Unit.</li> <li>Added information related to precautions for safe use.</li> </ul>
16	January 2026	Corrected mistakes.

**Revision History** 



# Introduction to NX-series Controllers

This section describes the features, basic system configuration, specifications, and overall operating procedure of an NX-series Controller NX102.

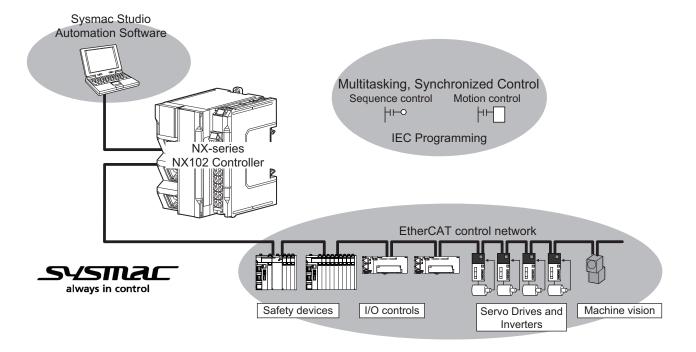
1-1	The N	NX-series Controller	1-2
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#### 1-1 The NX-series Controller

The SYSMAC NX-series are next-generation machine automation controllers that provide the functionality and high-speed performance that are required for machine control. They provide the safety, reliability, and maintainability that are required of industrial controllers.

The NJ/NX-series Controllers provide the functionality of previous OMRON PLCs, and they also provide the functionality that is required for motion control. Synchronized control of I/O devices on high-speed EtherCAT can be applied to safety devices, vision systems, motion equipment, discrete I/O, and more.

Especially, the NX-series NX102 Controller can perform I/O operation with a mounted NX Unit. OMRON offers the new Sysmac Series of control devices designed with unified communications specifications and user interface specifications. The NX-series Machine Automation Controllers are part of the Sysmac Series. You can use them together with EtherCAT slaves, other Sysmac products, and the Sysmac Studio Automation Software to achieve optimum functionality and ease of operation. With a system that is created from Sysmac products, you can connect components and commission the system through unified concepts and usability.



#### 1-1-1 Features

#### **Hardware Features**

#### Standard-feature EtherCAT Control Network Support

All CPU Units provide an EtherCAT master port for EtherCAT communications.

EtherCAT is an advanced industrial network system that achieves faster, more-efficient communications. It is based on Ethernet. Each node achieves a short fixed communications cycle time by transmitting Ethernet frames at high speed.

The standard-feature EtherCAT control network allows you to connect all of the devices required for machine control (e.g., I/O systems, Servo Drives, Inverters, and machine vision) to the same network.

#### Support for EtherCAT Slave Terminals

You can use EtherCAT Slave Terminals to save space. You can also flexibly build systems with the wide variety of NX Units.

#### Achieving a Safety Subsystem

You can use NX-series Safety Control Units to integrate safety controls in sequence and motion control systems.

#### Standard-feature EtherNet/IP Communications Ports

All CPU Units provide two EtherNet/IP ports for EtherNet/IP communications.

EtherNet/IP is a multi-vendor industrial network that uses Ethernet. You can use it for networks between Controllers or as a field network. The use of standard Ethernet technology allows you to connect to many different types of general-purpose Ethernet devices.

Moreover, with two EtherNet/IP ports these CPU Units enable the integrated control of two separate control systems, for example, one of the host information control system for communications between Controllers and the other for a lower-level field network control system.

#### NX-series Units Connectable

The CPU Unit can be connected with up to 32 NX Units including NX-series Digital I/O Units, Analog I/O Units, and other I/O Units.

#### Battery-free Operation

The following data (other than the clock data) is retained in the built-in non-volatile memory.

- User program
- · Set values
- Variables retained during power interruption
- Event logs

The retention period for the clock data is limited\*1.

When the clock data is not needed or the equipment's power OFF time is shorter than the clock data retention period, the battery-free operation is possible and man-hours for battery replacement can be reduced.

If you turn OFF the power supply to the equipment for a longer period of time than the clock data retention period, mount a battery which is sold separately.

\*1. Approximately 10 days at an ambient temperature of 40°C. Refer to 3-1-6 Battery on page 3-13 for detail.

#### Standard-feature SD Memory Card Slot

You can access an SD Memory Card that is mounted in the CPU Unit from the user program.

#### Highly Reliable Hardware

The NX-series Controllers provide the hardware reliability and RAS functions that you expect of a PLC.

#### **Software Features**

#### Integrated Sequence Control and Motion Control

An NX-series CPU Unit can perform both sequence control and motion control. You can simultaneously achieve both sequence control and multi-axes synchronized control. Sequence control, motion control, and I/O refreshing are all executed in the same control period.

The same control period is also used for the process data communications cycle for EtherCAT. This enables precise sequence and motion control in a fixed period with very little deviation.

#### Programming Languages Based on the IEC 61131-3 International Standard

The NJ-series Controllers support language specifications that are based on IEC 61131-3. To these, OMRON has added our own improvements. Motion control instructions that are based on PLCopen<sup>®</sup> standards and an instruction set (POUs) that follows IEC rules are provided.

#### Programming with Variables to Eliminate Worrying about the Memory Map

You access all data through variables in the same way as for the advanced programming languages that are used on computers. Memory in the CPU Unit is automatically assigned to the variables that you create so that you do not have to remember the physical addresses.

#### A Wealth of Security Features

The many security features of the NX-series Controllers include operation authority settings and restriction of program execution with IDs.

#### Complete Controller Monitoring

The CPU Unit monitors events in all parts of the Controller, including mounted NX Units and Ether-CAT slaves.

Troubleshooting information for errors is displayed on the Sysmac Studio or on an NS-series PT. Events are also recorded in logs.

#### Sysmac Studio Automation Software

The Sysmac Studio provides an integrated development environment that covers not only the Controller, but also covers peripheral devices and devices on EtherCAT. You can use consistent procedures for all devices regardless of the differences in the devices. The Sysmac Studio supports all phases of Controller application, from designing through debugging, simulations, commissioning, and changes during operation.

#### • A Wealth of Simulation Features

The many simulation features include execution, debugging, and task execution time estimates on a virtual controller.

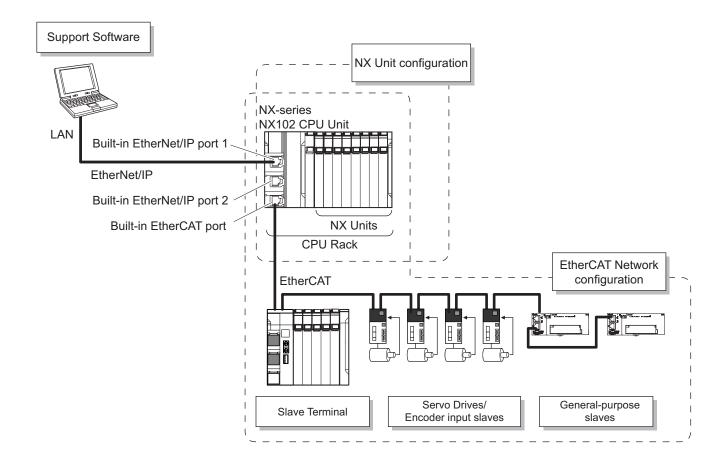
#### 1-1-2 Introduction to the System Configurations

The NX-series Controller NX102 supports the following system configurations.

#### **Basic System Configurations**

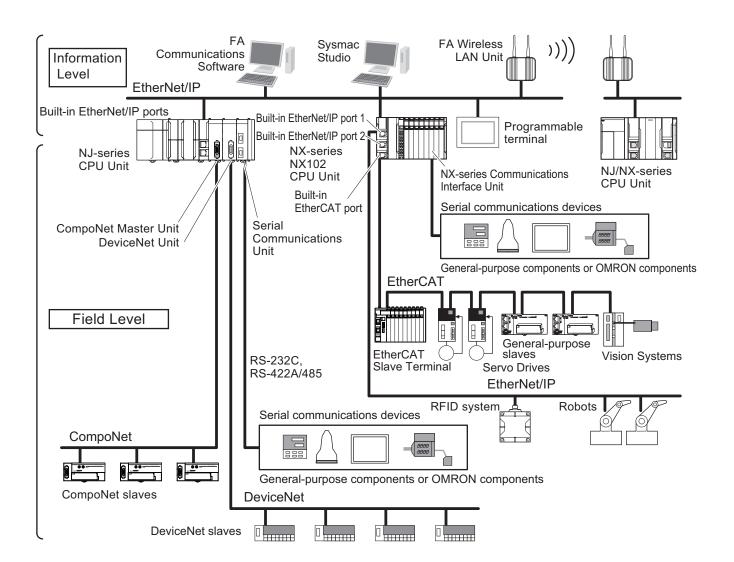
The NX-series Controller NX102 basic configurations include the EtherCAT network configuration, NX Unit configuration, and the Support Software.

- · EtherCAT Network Configuration
  - You can use the built-in EtherCAT port on the CPU Unit to connect to EtherCAT Slave Terminals, to general-purpose slaves for analog and digital I/O, and to Servo Drives and encoder input slaves. An EtherCAT network configuration enables precise sequence and motion control in a fixed cycle with very little deviation.
- NX Unit configuration
   The CPU Unit can be connected with up to 32 NX Units (NX-□□□□□□) including NX-series Digital I/O Units, Analog I/O Units, and other I/O Units. These NX Units can be flexibly combined with the CPU Unit and configure a CPU Rack to support various applications.
- · Support Software
  - You can connect the Support Software through an Ethernet cable that is connected to the built-in EtherNet/IP port 1 or 2 in the CPU Unit.
  - Refer to 3-5-2 Connection on page 3-19 for details on the connection configuration of the Support Software.



#### **Network Configurations**

- Host computers, HMIs, and other NJ/NX-series Controllers or field network devices are connected to the two built-in EtherNet/IP ports on the CPU Unit.
- A DeviceNet network is connected to a CJ-series DeviceNet Unit mounted to the NJ-series CPU
  Unit.
- A serial communications network is connected to the following Units.
   NX-series Communications Interface Unit
   CJ-series Serial Communications Unit



Refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for details on the network configuration.

#### **Support Software**

You can use the following Support Software to set up, monitor, and debug an NX-series Controller.

- · Sysmac Studio
  - The Sysmac Studio is the main Support Software that you use for an NX-series Controller. On it, you can set up the Controller configurations, parameters, and programs, and you can debug and simulate operation.
- Other Support Software
   The following Support Software is also included in the Sysmac Studio Software Package Standard Edition.

Configuration software	Application					
Sysmac Studio	The Sysmac Studio is used for sequence control, motion control, and all other operations					
	except those described below.					
Network Configurator	The Network Configurator is used for tag data links on EtherNet/IP ports. *1					
CX-Integrator	The CX-Integrator is used for remote I/O communications with a CJ-series DeviceNet Unit					
	or CJ-series CompoNet Master Unit.					
CX-Protocol	The CX-Protocol is used for protocol macros with the CJ-series Serial Communications					
	Units.					
CX-Designer	The CX-Designer is used to create screens for NS-series PTs.					

<sup>\*1.</sup> If the NJ/NX-series Controller is a target device, you may also use Sysmac Studio version 1.10 or higher. Use the Network Configurator if a CS/CJ-series PLC operates as the originator device.

# 1-2 Specifications

This section gives the specifications of the NX-series NX102 CPU Units.

	ltem -			NX1	102-		
			12□□	11□□	10□□	90□□	
Proc-	Instruction	LD instruction	LD instruction				
essing	execution	Math instruc	ctions (for	70 ns or more			
time	times	long real da	ta)				
		Size		5 MB			
			Number of	3,000			
	Program ca-		POU defi-				
	pacity*1	Quantity	nitions	0.000			
			Number of POU in-	9,000			
			stances				
	Memory capacity for	Retain at- tribute	Size	1.5 MB			
			Number of	10,000			
			variables				
	variables*2	No Retain	Size	32 MB			
Pro-	variables -		Number of	90,000			
gram-	<u> </u>		variables				
ming	Data types	Number of d	lata types	1,000			
		CIO Area		0 to 6,144 words			
	Memory for			(CIO 0 to CIO 6,	143) <sup>*3</sup>		
	CJ-series	Work Area		0 to 512 words			
	Units (Can			(W0 to W511)*3			
		Holding Area		0 to 1,536 words	3		
	with AT	Tiolaling Air	<u> </u>	(H0 to H1,535)*4	•		
	specifica- tions for var-	DM Area		0 to 32,768 word			
	iables.)	Dill Alea		(D0 to D32,767)	*4		
	14.5100.1	EM Area		32,768 words × 3			
		LIVI AI Ca	EM Area		2,767)*4*5		

		NX102-						
	It	em		12□□	11□□	10□□	90□□	
		Maximum nu		15 axes			4 axes	
			Motion control ax-	11 axes				
			Single-axis position control ax-	4 axes				
		Maximum nu used real ax		12 axes	8 axes	6 axes	4 axes	
	Number of controlled axes*6		Used mo- tion con- trol servo axes	8 axes	4 axes	2 axes		
Motion			Used sin- gle-axis position control servo axes	4 axes				
control		Maximum number of axes for linear interpolation axis control		4 axes per axes	group			
		Number of axes for cir- cular interpolation axis control		2 axes per axes	group			
	Maximum nur	nber of axes g	roups	8 axes groups				
	Motion contro	ol period		The same control period as that is used for the process data communications cycle for EtherCAT.				
		Number of	Maximum points per cam table	65,535 points				
	Cams	cam data points	Maximum points for all cam tables	262,140 points				
		Maximum nu	umber of	160 tables				
	Position units	3		Pulse, mm, µm, nm, degree, and inch				
	Override facto	ors		0.00%, or 0.01%	to 500.00%			

				NX102-		
	I1	em		1200 1100 1000 9000		
	Number of po	rts		2		
	Physical layer	<u>r                                      </u>		10BASE-T/100BASE-TX		
	Frame length			1,514 bytes max.		
	Media access	method		CSMA/CD		
	Modulation			Baseband		
	Topology			Star		
	Baud rate			100 Mbps (100BASE-TX)		
	Transmission	media		STP (shielded, twisted-pair) cable of Ethernet category 5, 5e or higher		
	Maximum tran			100 m		
	Maximum nur tions	nber of casca	de connec-	There are no restrictions if an Ethernet switch is used.		
		Maximum n	umber of	32 per port		
		connections	<u> </u>	64 total		
		Packet inter	val <sup>*7</sup>	Can be set for each connection.		
				1 to 10,000 ms in 1-ms increments		
		Permissible cations ban		12,000 pps*8*9 (including heartbeat, CIP Safety routing)		
			umber of tag	32 per port		
		sets		40 total*10		
		Tag types		Network variables CIO/WR/HR/DM		
Death to	CIP service: Tag data			8 (7 tags if Controller status is included in the tag set.)		
Ether- Net/IP	Ether-	Maximum number of tags		256 per port 512 total		
port	tions)	Maximum lii	nk data size	19,200 bytes per port		
port		per node (to	tal size for	38,400 bytes total		
		all tags)				
		Maximum data size per connection		600 bytes		
		Maximum number of registrable tag sets  Maximum tag set size		32 per port		
				40 total* <sup>10</sup>		
				(1 connection = 1 tag set)		
				600 bytes (Two bytes are used if Controller status is included in the		
				tag set.) Supported.		
		Multi-cast pa	acket filter*11			
		Class 3 (nur	mber of con-	32 per port 64 total		
		nections)		(clients plus server)		
			Maximum	32 per port		
			number of	64 total		
			clients that			
	CIP mes-		can com-			
	sage serv- ice: Explicit	UCMM	municate at one time			
	messages	(non-con-	Maximum	32 per port		
	3-1	nection	number of	64 total		
		type)	servers			
			that can			
			communi-			
			cate at one			
			time			

Maximum number of routile CIP Safety connections   16 total   16		NX102-					
routable CIP Safety connections  routing  Miximum routable safety data length per connection  Number of TCP sockets  Secure socket services 12  ITLS version 1.2  OPC UA server 13  Communications standard IEC 61158 Type 12  EtherCAT master specifications Class B (Feature Pack Motion Control compilant)  Physical layer 100BASE-TX  Modulation Baseband Base		lt	em	12□□	11□□	10□□	90□□
ty data length per con-   nection		CIP Safety	routable CIP Safety con-	16 total			
Secure socket sery-   clos ***12   TLS version   1.2		routing	ty data length per con-	32 bytes			
Socket servatices **12		Number of TC	P sockets	60			
Communications standard   IEC 61158 Type12				60			
Communications   Standard   IEC 61158 Type12		ices*12	TLS version	1.2			
EtherCAT master specifications   Class B (Feature Pack Motion Control compliant)		OPC UA serve	er	*13			
Physical layer   100BASE-TX   Baseband   Baud rate   100 Mbps (100BASE-TX)		Communication	ons standard	IEC 61158 Type <sup>2</sup>	2		
Modulation   Baseband		EtherCAT mas	ster specifications	Class B (Feature	Pack Motion Cor	ntrol compliant)	
Baud rate   Duplex mode		Physical layer	,	100BASE-TX			
Duplex mode   Auto		Modulation		Baseband			
Topology		Baud rate		100 Mbps (100B	ASE-TX)		
Transmission media		Duplex mode		Auto			
Transmission media   Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)		Topology		Line, daisy chain	, branching, and r	ing <sup>*14</sup>	
Maximum rumber of slaves   100 m	Duillé la	Transmission media			e of category 5 or	higher (double-sh	ielded straight
Maximum number of slaves   64	Ether-		smission distance be-	100 m			
Set   Input: 5,736 bytes   Output: 5,736 bytes   Output: 5,736 bytes		Maximum nun	nber of slaves	64			
Maximum process data size   Output: 5,736 bytes				1 to 192			
Units on CPU Rack Units on CPU Unit  Maximum number of NX Units for entire controller  Power supply  Model Power OFF detection time  Accuracy*17  Accuracy*17  Maximum process data size per slave  Output: 1,434 bytes  1,000 to 32,000 µs (in 250-µs increments)  1 µs max.  32  Inputs: 8,192 bytes*16  Outputs: 8,192 bytes*16		Maximum process data size		Output: 5,736 by			
Sync jitter		Maximum pro	cess data size per slave				
Units on CPU Rack Units on CPU Rack Units on CPU Rack Units on CPU Rack  Maximum I/O data size that can be allocated in the CPU Unit  Maximum number of NX Units for entire controller  Maximum number of NX Units for entire controller  Model Power Supply  Model Power OFF detection time  Accuracy*17  At ambient temperature of 55°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 40°C: 10 days		Communication	ons cycle	1,000 to 32,000	us (in 250-µs incre	ements)	
Units on CPU Rack Units on CPU Rack Unit configuration  Maximum I/O data size that can be allocated in the CPU Unit  Maximum number of NX Units for entire controller  Power supply  Model A non-isolated power supply for DC input is built into the CPU Unit.  2 to 8 ms  Accuracy*17 At ambient temperature of 55°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 40°C: 10 days		Sync jitter		1 μs max.			
Unit configuration  Maximum number of NX Units for entire controller  Model  Power supply  Model  Power OFF detection time  Accuracy*17  Accuracy*17  Accuracy*17  Retention time of built-in capacitor  Maximum I/O data size that can be allocated in the CPU Unit.  Allocated in the CPU Unit and the CPU Unit.  Allocated in the CPU Unit.  Allocated power supply for DC input is built into the CPU Unit.  At ambient temperature of 55°C: -3.0 to 2.0 min error per month  At ambient temperature of 25°C: -2.0 to 2.0 min error per month  At ambient temperature of 40°C: -3.0 to 2.0 min error per month  At ambient temperature of 40°C: 10 days			Units that can be mounted to the CPU	32			
that can be allocated in the CPU Unit  Maximum number of NX Units for entire controller  Power supply  Model  Power OFF detection time  Accuracy*17  Accuracy*17  Accuracy*17  Accuracy*17  Retention time of built-in capacitor  At ambient temperature of 40°C: 10 days  Outputs: 8,192 bytes*16  A32  An non-isolated power supply for DC input is built into the CPU Unit.  2 to 8 ms  At ambient temperature of 55°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 40°C: 10 days		CPU Rack	Maximum I/O data size	Inputs: 8,192 bytes*16			
Maximum number of NX Units for entire controller   432	configu-						
Power OFF detection time  2 to 8 ms  At ambient temperature of 55°C: -3.0 to 2.0 min error per month At ambient temperature of 25°C: -2.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month At ambient temperature of 40°C: 10 days	ration	Maximum number of NX Units for enti		432			
Power OFF detection time   2 to 8 ms		Power cup	Model	A non-isolated p	ower supply for D	C input is built into	the CPU Unit.
Internal clock  Accuracy*17  At ambient temperature of 25°C: -2.0 to 2.0 min error per month At ambient temperature of 0°C: -3.0 to 2.0 min error per month  Retention time of built-in capacitor  At ambient temperature of 40°C: 10 days		· .		2 to 8 ms			
		Accuracy*17		At ambient temp	erature of 25°C: -2	2.0 to 2.0 min erro	r per month
			<u> </u>		erature of 40°C: 1	0 days	

<sup>\*1.</sup> Execution objects and variable tables (including variable names)

<sup>\*2.</sup> Memory used for CJ-series Units is included.

<sup>\*3.</sup> The value can be set in 1-word increments. The value is included in the total size of variables without a Retain attribute.

<sup>\*4.</sup> The value can be set in 1-word increments. The value is included in the total size of variables with a Retain attribute.

- \*5. It is not possible to use the maximum number of words simultaneously for all banks, because the memory capacity for variables with a Retain attribute is limited to 1.5 MB.
- \*6. For terminology, refer to the NJ/NX-series CPU Unit Motion Control User's Manual (Cat. No. W507).
- \*7. Data will be refreshed at the set interval, regardless of the number of nodes.
- \*8. "pps" means packets per second, i.e., the number of communications packets that can be sent or received in one second.
- \*9. The allowable bandwidth varies depending on the RPI of the connection in use, the primary task period, and the number of ports simultaneously used for EtherNet/IP communications.
- \*10. When tag sets that exceed the total of 40 are set, a Number of *Tag Sets for Tag Data Links Exceeded* (840E0000 hex) occurs.
- \*11. As the EtherNet/IP port implements the IGMP client, unnecessary multi-cast packets can be filtered by using an Ethernet switch that supports IGMP Snooping.
- \*12. An NX102- $\square$ 00 CPU Unit with unit version 1.46 or later, NX102- $\square$ 20 CPU Unit with unit version 1.37 or later, and Sysmac Studio version 1.46 or higher are required to use the secure socket services.
- \*13. Refer to the NJ/NX-series CPU Unit OPC UA User's Manual (Cat. No. W588) for information on the specifications for the OPC UA server.
- \*14. A ring topology can be used with project unit version 1.40 or later.
- \*15. However, for project unit version earlier than 1.40, the data must be within four frames.
- \*16. You can check the I/O allocation status with the Sysmac Studio. Refer to the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for how to check the I/O allocation status. Also, refer to the relevant manuals for specific Units for the maximum I/O data size per NX Unit.
- \*17. These are values in continuous operation state.

## 1-3 Overall Operating Procedure for the CPU Unit

This section gives the overall operating procedure for the NX102 CPU Unit and then describes it in more detail.

#### 1-3-1 Overall Procedure

The overall procedure to use an NX102 CPU Unit is given below.

#### STEP 1. Software Design

Design the overall system configuration, task configuration, programs, and variables.

Step 1-1 Designing I/O and Processing

Step 1-2 Designing Tasks

Step 1-3 Designing Programs



#### STEP 2. Software Setups and Programming

Create the system configurations that you designed in step 1 on the Support Software and assign the variables. Create the tasks and programs, and debug them, e.g., with simulations.

Step 2-1 Slave and NX Unit Configurations

Step 2-2 Controller Setup

Step 2-3 Programming

Step 2-4 Offline Debugging



#### STEP 3. Mounting and Setting Hardware

Mount the Units and make the required hardware settings.



#### STEP 4. Wiring

Connect the network cables and wire the I/O.



# STEP 5. Confirming Operation and Starting Actual System Operation

Connect the Support Software to the physical system and download the project. Check operation on the physical system and then start actual system operation.

#### 1-3-2 Procedure Details

STEP1. Software Design					
Step	Description	Reference			
Step 1-1	External I/O devices and Unit configuration	NJ/NX-series CPU Unit			
Designing I/O and	Refresh periods for external devices	Software User's Manual			
Processing	Program contents	(Cat. No. W501)			



Step 1-2	Task configuration	NJ/NX-series CPU Unit
<b>Designing Tasks</b>	Relationship between tasks and programs	Software User's Manual
	Task periods	(Cat. No. W501)
	Slave and NX Unit refresh cycles	
	Exclusive control methods for variables between tasks	



Step 1-3		
<b>Designing Programs</b>		
POU (Program Organi-	Programs	NJ/NX-series CPU Unit
zation Unit) Design	Functions and function blocks	Software User's Manual
	Determining the algorithm languages	(Cat. No. W501)
Variable Design	<ul> <li>Defining variables that you can use in more than one POU and variables that you use in only specific POUs</li> <li>Defining the variables names for the device variables that you use to access slaves and NX Units</li> <li>Defining the attributes of variables, such as the Name and Retain attributes</li> <li>Designing the data types of variables</li> </ul>	NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)



#### STEP2. Software Setups and Programming

Step	Description	Sysmac Studio	Reference
·	·	Operations	
Project Creation	Create a project in the Sysmac Studio.     Select a Controller.	Select New Project Select the device in the Project Proper- ties Dialog Box	Sysmac Studio Version 1 Operation Manual(Cat. No. W504)



The following Controller Configurations and Setup and the Programming and Task Settings can be performed in either order.

Step 2-1	
Slave and NX Unit	
Configurations	

1) Creating the Slave and NX Unit Configura- tions	1.	Creating the slave configuration and NX Unit configuration either offline or online.  (For online configuration, make the online connection that is described in step 5.)  Setting up any Slave Terminals that	EtherCAT Tab Page CPU and Expan- sion Racks Tab Page Slave Terminal Tab Page	NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) NX-series EtherCAT Coupler Units User's Manual (Cat. No. W519)
		are used.		
-				



2) Assigning Device	Assigning Device Registering device variables in variable		NJ/NX-series CPU Unit
Variables to I/O Ports	tables (Variable names are user defined		Software User's Manual
	or automatically created.)		(Cat. No. W501)



(The following step is for motion control.)

3) Creating the Axes	Creating the axes and setting them as	Configurations	NJ/NX-series CPU Unit
and Assigning Them to	real axes or virtual axes.	and Setup -	Software User's Manual
the Servo Drive/Encod-	Creating axes groups to perform interpo-	Motion Control	(Cat. No. W501)
er Input Slaves	lated axes control.	Setup	



Step 2-2
Controller Setup

Setting the following parameters from the Sysmac Studio

Setting the initial values for the PLC	Configurations	NJ/NX-series CPU Unit
Function Module	and Setup -	Software User's Manual
	Controller Setup -	(Cat. No. W501)
	Operation Settings	<i>3-1-6 Battery</i> on page 3-13
Setting the battery-related error de-	Configurations	
tection when the battery is mounted	and Setup -	
	Controller Setup -	
	Operation Settings	
Setting the initial values for the NX	Configurations	
Bus Function Module	and Setup - CPU/	
	Expansion Racks	
	- CPU Rack	
(To use motion control)	Configurations	
Setting the initial settings for the	and Setup -	
Motion Control Function Module	Motion Control	
	Setup	
Setting the initial values for the	Configurations	
EtherCAT Function Module	and Setup -	
	EtherCAT	
Setting the initial values for the	Configurations	
EtherNet/IP Function Module	and Setup -	
	Controller Setup -	
	Built-in	
	EtherNet/IP Port	
	Settings	



Step 2-3
Programming

1) I	Registering Varia- es	<ul> <li>Registering the variables used by more than one POU in the global variable table with Sysmac Studio</li> <li>Registering the local variable table for each program</li> <li>Registering the local variable table for</li> </ul>	Global Variable Ta- ble Editor Local Variable Table Editor	Sysmac Studio Version 1 Operation Manual(Cat. No. W504) NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)
-	Writing Algorithms POUs	each function block and function  Writing the algorithms for the POUs (programs, function blocks, and functions) in the required languages	Programming Editor	NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) NJ/NX-series Instructions Reference Manual (Cat. No. W502) NJ/NX-series Motion Control Instructions Reference Manual (Cat. No. W508)
3) \$	Setting the Tasks	Making task settings	Configurations and Setup - Task Settings	NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)



Step 2-4	Checking the algorithms and task execu-	NJ/NX-series CPU Unit
Offline Debugging	tion times on the Simulator (virtual con-	Software User's Manual
	troller)	(Cat. No. W501)



# Step Description Reference 1) Mounting • Connecting adjacent Units 5-3 Mounting and Removing Units on page 5-8 2) Setting Hardware • Setting the node addresses of the EtherCAT slaves Operation manuals for the EtherCAT slaves



STEP4. Wiring			
Step	Description	Reference	
1) Connecting the Power Supply to the CPU Unit	Connecting the power supply and ground wires	Section 4 Designing the Power Supply System on page 4-1 5-4 Wiring on page 5-34	
2) Connecting Ethernet Cable	Connecting the built-in EtherCAT port     Connecting the built-in EtherNet/IP port	NJ/NX-series CPU Unit Built- in EtherCAT Port User's Manual (Cat. No. W505) NJ/NX-series CPU Unit Built- in EtherNet/IP Port User's Manual (Cat. No. W506)	
3) Wiring I/O	Wiring I/O for NX Units	Manuals for the specific NX Units	

	Wiring I/O to EtherCAT slaves	Operation manuals for the EtherCAT slaves
		<i>5-4 Wiring</i> on page 5-34
4) Connecting the	Connecting the built-in EtherNet/IP port	Sysmac Studio Version 1
Computer That Runs		Operation Manual(Cat. No.
the Sysmac Studio		W504)



#### STEP5. Checking Operation and Starting Operation on the Actual System

Step	Description	Sysmac Studio Operations	Reference
1) Online Connection to Sysmac Studio and Project Download	Turn ON the power supply to the Controller and place the Sysmac Studio online.  Then, download the project. *1  Perform this step before you create the slave configuration or NX Unit configuration from the mounted Units in step 2-1.	Controller – Communications Setup Controller – Synchronization	NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)



2) Clock Data Setting	Set the clock data with the clock function	Controller -	NJ/NX-series CPU Unit
	when the battery is mounted or when the	Controller Clock	Software User's Manual
	battery-free operation is performed.		(Cat. No. W501)



3) Operation Check on Controller	Check the wiring by using forced refreshing of real I/O from the I/O Map or Watch Tab Page.	 NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)
	2. For motion control, use the MC Test Run operations in PROGRAM mode to check the wiring. Then check the motor rotation directions for jogging, travel distances for relative positioning (e.g., for electronic gear settings), and homing operation.	
	Change the Controller to RUN mode and check the operation of the user program.	



4) Actual Controller	Start actual operation.	 
Operation		

<sup>\*1.</sup> Use the Synchronize Menu of the Sysmac Studio to download the project.

# **System Configuration**

This section describes the basic system configuration used for NX-series Controllers.

2-1	Basic	c System Configuration	2-2
		EtherCAT Network Configuration	
		NX Unit Configuration	
2-2	Conr	necting to the Sysmac Studio	2-6
2-3	Netw	ork Configuration	2-7

# 2-1 Basic System Configuration

An NX-series Controller NX102 supports the following two types of configurations.

· Basic Configuration

The basic configurations include the CPU Unit and the Configuration Units that are controlled directly by the CPU Unit. The followings are basic configurations.

- a) EtherCAT network configuration
- b) NX Unit configuration
- · Other Network Configurations

These are the configurations of the systems that are connected to the CPU Unit's built-in EtherNet/IP ports and Communications Units.

# **Basic Controller Configuration**

# EtherCAT Network Configuration

With an NX-series CPU Unit, you can use an EtherCAT network as a basic system.

With the EtherCAT network system of the NX-series CPU Unit, the period for sequence processing and motion processing in the CPU Unit is the same as the EtherCAT communications period.

This enables high-precision sequence control and motion control with a constant period and little fluctuation.

For information on EtherCAT, refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual* (Cat. No. W505).

# NX Unit Configuration

The CPU Rack consists of the following items.

- NX102 CPU Unit
- NX Unit NX-
- End Cover NX-END02

Up to 32 NX Units can be connected.

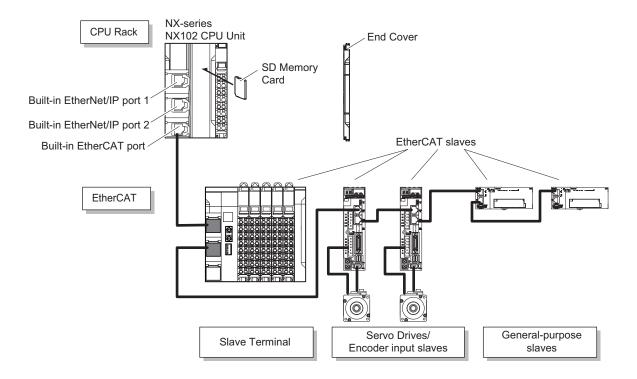
By using the NX Units that support synchronous I/O refreshing, all I/O refreshing is synchronized with the task period of the primary periodic task of the CPU Unit.

This enables high-precision synchronized control with a stable fixed period.

# 2-1-1 EtherCAT Network Configuration

The EtherCAT network configuration consists of an NX-series NX102 CPU Unit, an End Cover, and the EtherCAT slaves.

You use the built-in EtherCAT port on the NX-series NX102 CPU Unit to connect EtherCAT slaves.



For information on the system configuration of an EtherCAT network, refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual* (Cat. No. W505).

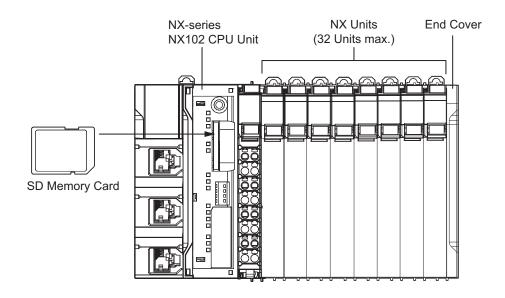
Refer to 2-1-2 NX Unit Configuration on page 2-4 for information on the CPU Unit and End Cover.

# 2-1-2 NX Unit Configuration

The following shows the configuration of NX Units.

# **CPU Rack**

The CPU Rack consists of an NX-series NX102 CPU Unit, NX Units, and an End Cover. Up to 32 NX Units can be connected.



Series	Configuration		Remarks
NX-series	NX-series NX102 CPU Unit End Cover		One required for every CPU Rack.
			Must be connected to the right end of the CPU
			Rack. One End Cover is provided with the
			CPU Unit.
	NX Units	Digital I/O Unit	Up to 32 Units can be mounted to each CPU
		Analog I/O Unit	Rack.
		System Unit	Refer to A-5 Support Functions of the CPU
		Position Interface Unit	Units and Restrictions on the NX Units on page A-8 for information such as restrictions
		Communications Inter-	on the NX Units.
		face Unit	For information on the most recent lineup of
		Load Cell Input Unit	NX Units, refer to NX-series catalogs or OM-
			RON websites, or ask your OMRON represen-
			tative.
NJ/NX-series	SD Memory C	ard	Install as required.

# **Configuration Units**

#### NX-series NX102 CPU Unit

The Unit that serves as the center of control for a Machine Automation Controller. It executes tasks, refreshes I/O for other Units and slaves, etc. In the NX-series, this type of Units is called NX102 CPU Unit.

Refer to 3-1 CPU Units on page 3-2 for the models and specifications of individual NX-series NX102 CPU Unit.

# SD Memory Card

With the NX-series NX102 CPU Unit, various data can be saved, backed up, restored, and compared using the SD Memory Card.

Refer to 3-2 SD Memory Cards on page 3-16 for the models and specifications of individual SD Memory Cards.

#### NX Unit

Up to 32 NX Units can be connected to the CPU Unit.

Refer to A-5 Support Functions of the CPU Units and Restrictions on the NX Units on page A-8 for information such as restrictions on the NX Units.

#### End Cover

A cover to protect the NX Unit and CPU Unit. This is provided with the CPU Unit. The model number is NX-END02.

#### Recommended Communications Cables for EtherCAT and EtherNet/IP

EtherCAT communications are performed in accordance with the 100BASE-TX standard. Refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual* (Cat. No. W505) for recommended cables.

EtherNet/IP communications are performed in accordance with the 100BASE-TX or 10BASE-T standard

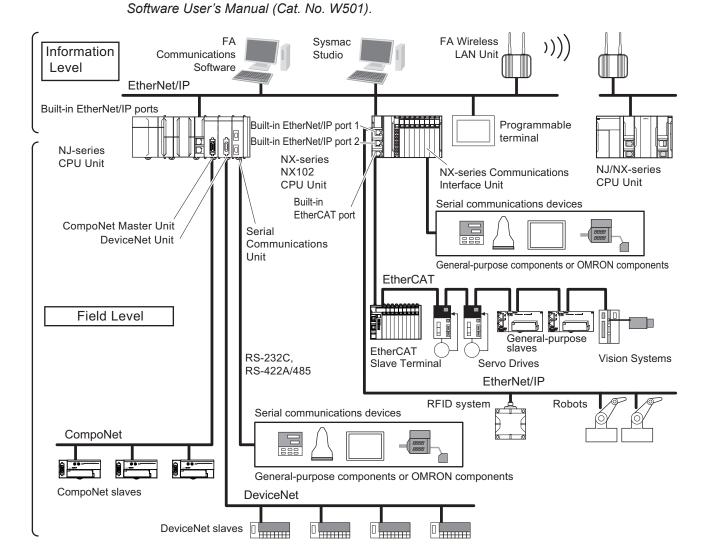
Refer to the *NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual (Cat. No. W506)* for recommended cables.

# 2-2 Connecting to the Sysmac Studio

Connect the NX-series NX102 CPU Unit and the Sysmac Studio through EtherNet/IP. Refer to *3-5-2 Connection* on page 3-19 for information on how to make the connection between the NX-series NX102 CPU Unit and the Sysmac Studio.

# 2-3 Network Configuration

You can make networks in the following layers with an NJ/NX-series Controller. For details on communications networks that you can connect to, refer to the *NJ/NX-series CPU Unit* 



	Connection	Connection method		
Sysmac Studio		Use the built-in EtherNet/IP port.		
Between Controllers NJ/NX-series Controller or CJ-series PLC		Use the built-in EtherNet/IP port or a port on an		
		EtherNet/IP Unit.*1		
Devices	Servo Drives, general-purpose slaves	Use the built-in EtherCAT port.		
	and Vision Systems			
	Ethernet communications devices	Use the built-in EtherNet/IP port or a port on an		
		EtherNet/IP Unit.*1		
	Serial communications devices	Mount the following Units and use RS-232C port or		
		RS-422A/485 ports.		
		CJ-series Serial Communications Unit <sup>*2</sup>		
		NX-series Communications Interface Unit*3		
	DeviceNet slaves	Mount a CJ-series DeviceNet Unit*2 and use DeviceNet.		
	CompoNet slaves	Mount a CJ-series CompoNet Master Unit*2 and use		
		CompoNet.		

	Connection	Connection method		
Programmable Termin	als	Use the built-in EtherNet/IP port or a port on an		
		EtherNet/IP Unit.*1		
Servers Connections to BOOTP server, DNS		Use the built-in EtherNet/IP port or a port on an		
	server, or NTP server	EtherNet/IP Unit.*1		

<sup>\*1.</sup> Use a CJ-series EtherNet/IP Unit with a unit version of 2.1 or later.

Also, mount the EtherNet/IP Unit to an NJ-series CPU Unit with unit version 1.01 or later, and use Sysmac Studio version 1.02 or higher.

Refer to the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for information on version upgrades.

- \*2. Mount to an NJ-series CPU Unit.
- \*3. Mount the Unit to the NX-series NX102 CPU Unit.

# **Configuration Units**

This section describes configuration devices in the NX-series Controller configuration.

3-1	CPU	Units	3-2
	3-1-1	Models and Specifications	
	3-1-2	Part Names and Functions	
	3-1-3	DIP Switch	
	3-1-4	Operation Status Indicators	3-8
	3-1-5	Terminal Blocks	3-12
	3-1-6	Battery	3-13
	3-1-7	ID Information Indication	3-14
3-2	SD N	lemory Cards	3-16
	3-2-1		
	3-2-2	Purpose	
3-3	Powe	er Supply-related Units	3-17
3-4	NX U	Inits	3-18
3-5	Sysn	nac Studio	3-19
	3-5-1	Model Numbers	3-19
	3-5-2	Connection	3-19

# 3-1 CPU Units

This section describes the models and specifications of the CPU Units as well as the names and functions of the parts.

# 3-1-1 Models and Specifications

This section describes the outline of the CPU Unit specifications. The electrical and mechanical specifications of the CPU Unit are also given. Refer to *1-2 Specifications* on page 1-9 for information on other main specifications.

# **Models and Outline of Specifications**

The models and outline of specifications are given below.

Model	Program capacity	Memory capacity for variables	Maximum number of controlled axes (Maximum number of used real axes)	Database connection
NX102-1200	5 MB	1.5 MB (Retained during power interruptions)	15 axes (12 axes)	Not supported
NX102-1100		or 32 MB (Not retained during power interruptions)	15 axes (8 axes)	
NX102-1000			15 axes (6 axes)	
NX102-9000			4 axes (4 axes)	
NX102-1220			15 axes (12 axes)	Supported
NX102-1120			15 axes (8 axes)	
NX102-1020			15 axes (6 axes)	
NX102-9020			4 axes (4 axes)	

# **Electrical and Mechanical Specifications**

The electrical and mechanical specifications are given below.

	Item	Specification
Model		NX102-□□□
Enclosure		Mounted in a panel
Dimensions (mm)*1		72 × 100 × 90 mm (W×H×D)
Weight*2		390 g max.
	Power supply voltage	24 VDC (20.4 to 28.8 VDC)
	Unit power consumption*3	5.80 W max.
Unit power supply	Inrush current*4	For cold start at room temperature: 10 A max./0.1 ms max. and 2.5 A max./150 ms max.
	Current capacity of power supply terminal*5	4 A max.
	Isolation method	No isolation: between the Unit power supply terminal and internal circuit
	NX Unit power supply capacity	10 W max.
Power supply to the NX Unit power supply	NX Unit power supply efficiency	80%
	Isolation method	No isolation: between the Unit power supply terminal and NX Unit power supply
I/O Power Supply to NX U	nits	Not provided*6
	Communication connector	RJ45 for EtherNet/IP Communications × 2 RJ45 for EtherCAT Communications × 1
External connection ter-	Screwless clamping terminal block	For Unit power supply input and grounding (Removable)
minal	Output terminal (service supply)	Not provided
	RUN output terminal	Not provided
	NX bus connector	32 NX Units can be connected

- \*1. Includes the End Cover, and does not include projecting parts.
- \*2. Includes the End Cover. The weight of the End Cover is 82 g.

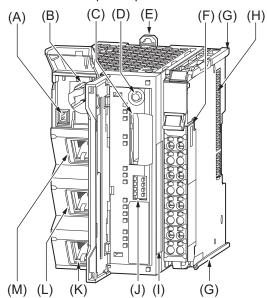
function, which cause an inrush current of approximately 30 A/0.3 ms.

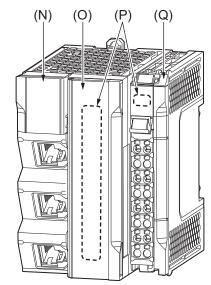
- \*3. Includes an SD Memory Card. The NX Unit power consumption to NX Units is not included.
- \*4. The inrush current that occurs when the supplied power is changed to ON from a continuous OFF state. The inrush current may vary depending on the operating condition and other conditions. Therefore, select fuses, breakers, and external power supply devices that have enough margin in characteristic and capacity, considering the condition under which the devices are used.

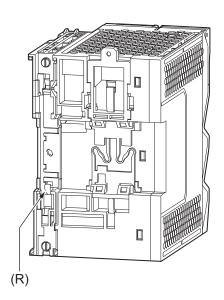
  In particular, in case when you insert a switch to turn ON/OFF the DC power supplied from an external power supply, if the duration of an ON-OFF-ON cycle is one second or less, the inrush control circuit may not
- 5. The amount of current that can be passed constantly through the terminal. Do not exceed this current value when you use a through-wiring for the Unit power supply.
- \*6. When the type of the I/O power supply to NX Units you use is the supply from NX bus, an Additional I/O Power Supply Unit is required. Refer to 4-3 Designing the I/O Power Supply System on page 4-13 for details.

# 3-1-2 Part Names and Functions

This section explains parts of the CPU Unit and their functions.







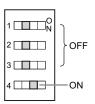
Letter	Name	Function
Α	Battery connector	Connects a separately-sold backup battery to the CPU Unit.
В	Battery slot	Allows a separately-sold backup battery to be mounted into the CPU Unit.
С	SD Memory Card connector	Connects the SD Memory Card to the CPU Unit.
D	SD Memory Card power supply switch	Turns OFF the power supply so that you can remove the SD Memory Card.  5-3-8 Installing and Removing the SD Memory Card on page 5-23
Е	DIN Track mounting hook	This hook is used to mount the NX Unit to a DIN Track.
F	Terminal block	The terminal block is used for wiring for the Unit power supply and grounding cable.

Letter	Name	Function
G	Unit hookup guides	These guides are used to mount an NX Unit or the End Cover.
Н	NX bus connector	This connector is used to connect the NX Unit mounted on the right side.
1	ID information indication	Shows the ID information of the CPU Unit.  3-1-7 ID Information Indication on page 3-14
J	DIP switch	Used in Safe Mode or when backing up data. Normally, turn OFF all of the pins.
K	Built-in EtherCAT port (port 3)	Connects the built-in EtherCAT with an Ethernet cable.
L	Built-in EtherNet/IP port (port 2)	Connects the built-in EtherNet/IP with an Ethernet cable.
М	Built-in EtherNet/IP port (port 1)	Use port 1 to perform OPC UA communications.
N	Battery cover	A cover for the battery slot. It opens upward.
0	SD Memory Card	A cover for the SD Memory Card and the DIP switch. It opens toward the left.
Р	Operation Status Indicators	Shows the operation status of the CPU Unit by multiple indicators.  3-1-4 Operation Status Indicators on page 3-8
Q	End Cover	A cover to protect the NX Unit and CPU Unit. One End Cover is provided with the CPU Unit.
R	DIN Track contact plate	This plate is used to contact the functional ground terminal with a DIN Track.

# 3-1-3 DIP Switch

Set the DIP switch when backing up data or using Safe Mode, etc. The meanings of each function, DIP switch settings, and reference manuals are shown in the table below. If you do not want to use these functions, turn OFF all pins.

The figure below shows an example setting when the Safe Mode is used.



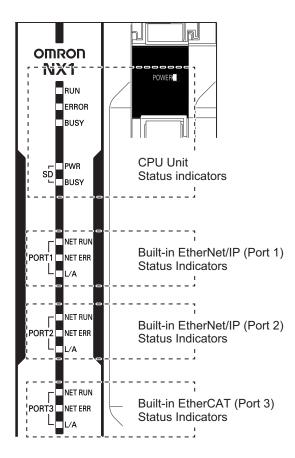
Function	Magning	DIP switch				Deference manual
Function	Meaning	4	3	2	1	Reference manual
Backup	You can back up all of the data in the Controller to an SD Memory Card.	OFF	ON	OFF	OFF	NJ/NX-series CPU Unit Software User's Manual (Cat. No.
Restore*1	You can transfer the various setting data stored in the SD Memory Card to the Controller.	ON	ON	OFF	OFF	W501)
Automatic transfer from SD Memory Card*1	You can automatically transfer the various setting data stored in the SD Memory Card to the Controller when the power is turned ON.	OFF	OFF	ON	OFF	
Safe Mode*1	You can start the Unit in PRO-GRAM mode when the power is turned ON. Use the Safe Mode if you do not want to execute the user program immediately after the power is turned ON, or if it is difficult to connect the Sysmac Studio.	ON	OFF	OFF	OFF	NJ/NX-series Trouble- shooting Manual (Cat. No. W503)

Function	Magning	DIP switch				Reference manual
runction	Meaning	4	3	2	1	Reference manual
Enabling connections to the Sysmac Studio	You can use this function to communicate with the Sys-	OFF	OFF	ON	ON	NJ/NX-series CPU Unit Software User's
and NA that are not supporting secure	mac Studio with versions that are not supporting secure					Manual (Cat. No. W501)
communication*1	communication, or NA-series HMI.					, , ,
Safe Mode, and ena-	You can set both of the Safe	ON	OFF	ON	ON	
bling connections to	Mode and enabling connec-					
the Sysmac Studio	tions to the Sysmac Studio					
and NA that are not	and NA that are not support-					
supporting secure	ing secure communication.					
communication*1						
Automatic transfer	You can set both of the auto-	OFF	ON	ON	ON	
from SD Memory	matic transfer from SD Memo-					
Card, and enabling	ry Card and enabling connec-					
connections to the	tions to the Sysmac Studio					
Sysmac Studio and	and NA that are not support-					
NA that are not sup-	ing secure communication.					
porting secure com-						
munication*1						

<sup>\*1.</sup> This function operates when the power supply to the CPU Unit is turned ON after you change the DIP switch settings. If you want to use this function, turn ON power to the CPU Unit after you change the DIP switch settings.

# 3-1-4 Operation Status Indicators

There are the indicators to show the operation status of CPU Unit in the center of the front side of the CPU Unit.



# CPU Unit Status Indicators

These indicators show the main operation status of the CPU Unit.

The following table describes these indicators. The POWER indicator is located on the top of the terminal block.

Indicator	Color	Status		Meaning
POWER	Green	Lit.		Power is ON.
			Not lit.	Power is not ON. Or, the power supply voltage is outside the allowable voltage range.

Indicator	Color		Status	Meaning
RUN	Green	\	Lit.	The CPU Unit is in normal operation in RUN mode. (The user
				program is in execution.)
			Flashing	The CPU Unit is starting (entering RUN mode or PROGRAM
			at 2-s inter-	mode at startup).
			vals, then	
			flashing at	
			0.5-s inter-	
			vals.	
			Flashing	System initialization error occurs.
			at 2-s inter-	
			vals contin-	
			ues for 30 seconds or	
			longer.	
			Not lit.	Operation is stopped in PROGRAM mode, when a CPU Unit
			NOT III.	reset is in progress, or when any of the following errors occurs.
				Controller error in the major fault level
				CPU error (WDT error)
ERROR	Red		Lit.	Self-diagnosis found one of the following errors.
				Controller error in the major fault level
				CPU error
			Flashing	Self-diagnosis found one of the following errors.
		/ <b>-</b>	at 1-s inter-	Controller error in the partial fault level (an error in which all
			vals.	control of a Function Module is disabled)
				Controller error in the minor fault level (an error in which par-
				tial control of a Function Module is disabled)
				CPU Unit operation will continue for either of these errors.
				Operation will stop for the Function Module in which a Control-
				ler error in the partial fault level occurred.  Operation will continue for the Function Module in which a
				Controller error in the minor fault level occurred.
			Not lit.	The CPU Unit is in normal operation, a CPU reset is in prog-
			Not lit.	ress, or monitored information occurred (CPU Unit operation
				will continue.).
BUSY	Yellow		Flashing	Built-in non-volatile memory access in progress.
				, , ,
			Not lit.	Other than the above.
SD PWR	Green		Lit.	Power is being supplied to the SD Memory Card and the SD
				Memory Card can be used.
			Flashing	A backup, restore or verification operation is in progress.*1
			Not lit.	The power supply for the SD Memory Card is stopped, an SD
				Memory Card is not mounted, or the file format of the mounted
				SD Memory Card is not supported.
SD	Yellow		Flashing	SD Memory Card access in progress.
BUSY				
			Not lit.	SD Memory Card access not in progress.

<sup>\*1.</sup> Refer to the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for details on backing up data.



#### **Precautions for Safe Use**

- Never turn OFF the power supply to the Controller when the BUSY indicator is flashing. While
  the BUSY indicator is lit, the user program and settings in the CPU Unit are being backed up
  in the built-in non-volatile memory. This data will not be backed up correctly if the power supply is turned OFF. Also, a major fault level Controller error will occur the next time you start
  operation, and operation will stop.
- Do not turn OFF the power supply or remove the SD Memory Card while SD Memory Card access is in progress (i.e., while the SD BUSY indicator flashes). Data may become corrupted, and the Controller will not operate correctly if it uses corrupted data. To remove the SD Memory Card from the CPU Unit while the power supply is ON, press the SD Memory Card power supply switch and wait for the SD BUSY indicator and SD PWR indicator to turn OFF before you remove the SD Memory Card.

You can check the operation status of the CPU Unit with the CPU Unit status indicators (POWER, RUN, and ERROR indicators).

Refer to the *NJ/NX-series Troubleshooting Manual (Cat. No. W503)* for the procedures to check the operation status of the CPU Unit.



#### **Precautions for Correct Use**

For products with lot numbers that represent the date of or after March 20, 2019, the shape of the light emitting part of each indicator has been changed from a square to a pentagon.



Before change

After change

# Built-in EtherNet/IP (Port 1/Port 2) Status Indicators

These indicators show the operation status of the built-in EtherNet/IP port of the CPU Unit. The indicator name and other information are the same for port 1 and port 2.

Indicator	Color	S	tatus	Meaning
NET RUN	Green		Lit.	Normal startup status.
			Flashing	Ethernet communications are in progress.
		/ <b>-</b>		Tag data link connection establishment in progress.
				IP address acquisition with BOOTP in progress.
			Not lit.	You cannot perform Ethernet communications.
				The power supply is OFF or the CPU Unit was reset.
				A MAC address error or communications Controller error occurred.
NET ERR	Red		Lit. An error for which the user cannot recover operation occurre  • A MAC address error or communications Controller error	
			Flashing	An error for which the user can recover operation occurred.
				An error occurred in TCP/IP communications or CIP communications.
FTP server setting error, NTP server setting		FTP server setting error, NTP server setting error, etc.		
				Tag data link setting error, tag data link verification error, etc.
		Not lit. There are no Ethernet communications errors.		There are no Ethernet communications errors.
				The power supply is OFF or the CPU Unit was reset.

Indicator	Color	Status		Meaning	
L/A	Yellow Lit.		Lit.	The link was established.	
			Flashing	The link is established, and data communications are in progress.	
			Not lit.	A link was not established.	
				The cable is not connected.	
				The power supply is OFF or the CPU Unit was reset.	

# • Built-in EtherCAT (Port 3) Status Indicators

These indicators show the operation status of the built-in EtherCAT port of the CPU Unit.

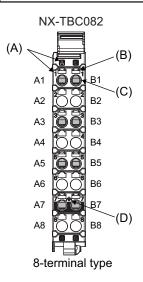
Indicator	Color	Status Meaning		Meaning	
NET RUN	Green		Lit.	EtherCAT communications are in progress.	
		/		Inputs and outputs for I/O data are in operation.	
			Flashing	EtherCAT communications are established.	
		/ <b>~</b>		This indicator shows either of the following conditions.	
				Only message communications are in operation.	
				Only message communications and I/O data inputs are in op-	
				eration.	
			Not lit.	EtherCAT communications are stopped.	
				The power supply is OFF or the CPU Unit was reset.	
				A MAC address error, communications Controller error, or oth-	
				er error occurred.	
NET ERR	Red		Lit.	A hardware error or unrecoverable error occurred, such as for	
				exception processing.	
			Flashing	A recoverable error occurred.	
		/ <b>~</b>			
			Not lit.	There are no errors.	
L/A	Yellow		Lit.	A link is established.	
		/ <mark></mark> -			
			Flashing	Data communications are in progress after establishing link.	
				Flashes every time data is sent or received.	
			Not lit.	The link was not established.	

# 3-1-5 Terminal Blocks

The terminal blocks on the CPU Unit are removable screwless clamping terminal blocks that allow you to easily connect and remove the wiring.

Connect the Unit power supply and ground lines to the screwless clamping terminal block.

# **Terminal Block Part Names and Functions**



Letter	Name	Function	
(A)	Terminal number indication Indicates the terminal numbers (A1 to A8 and B1 to B8).		
		The terminal number indication is the same regardless of the numb	
		terminals on the terminal block.	
(B)	Release hole Insert a flat-blade screwdriver into this hole when you connect or re-		
		move the wire.	
(C)	Terminal hole	The wire is inserted into this hole.	
(D)	Ground terminal mark	This symbol indicates that it is the ground terminal.	

Refer to 5-4-1 Wiring the Unit Power Supply on page 5-34 and 5-4-8 Wiring to the CPU Unit Terminal Block on page 5-40 for the wiring procedure.

There are three types of terminal blocks: 8-terminal type, 12-terminal type, and 16-terminal type. Only the 8-terminal type terminal block can be attached to the NX102 CPU Units.

To prevent mis-insertion, the terminal blocks other than of the 8-terminal type cannot be used.



#### **Additional Information**

No terminal and release holes with the numbers A2, A4, A6, A8, B2, B4, B6, and B8 are provided for the 8-terminal type terminal block.

# 3-1-6 Battery

The battery is not mounted when the product is shipped.

You need to prepare a battery for the CPU Unit to retain the clock data while the CPU Unit is left powered off for a long period of time.

The following describes the purpose of the battery mounting, the battery model, and the battery-related error detection and clock data settings.

# **Purpose of the Battery Mounting**

The battery is used to retain the clock data while the power is not supplied to the CPU Unit. The clock data is retained by the built-in capacitor whether the battery is mounted or not, but the retention period depends on the continuous power-ON time of the CPU Unit, as shown below.

Continuous power- ON time of CPU Unit*1	Retention period during no power supply at an ambi- ent temperature of 40°C		
100 hours	Approx. 10 days		
100 hours 8 hour	Approx. 10 days Approx. 8 days		

<sup>\*1.</sup> This is equivalent to the time to charge a built-in capacitor in which no electric charge is accumulated.

When you use the clock data for programming, use a battery if you cannot ensure the continuous power-ON time shown above or the power-OFF time is longer than the above power-ON time.

The following data (other than the clock data) is retained in the built-in non-volatile memory, so they are not lost even if the battery and built-in capacitor are fully discharged.

- · User program
- · Set values
- · Variables retained during power interruption
- · Event logs

# **Battery Model**

The table below shows the model and specifications of the battery that can be used.

Model	Appearance	Specification
CJ1W-BAT01		Service life: 5 years For the battery lifetime, refer to <i>Battery Service Life and Replacement Period</i> on page 7-7. The clock information is retained during power interruptions.

# **Battery-related Error Detection and Clock Data Settings**

Because the CPU Unit is shipped with the battery not mounted, the **Battery-related error detection** is set to **Do not use** by default.

The behavior of the CPU Unit when a battery-related error is detected depends on whether battery error detection is used or not used as shown in the table below.

When the battery is not mounted, you can set the **Battery-related error detection** to **Do not use** to suppress battery errors.

When the battery is mounted, however, you can set the **Battery-related error detection** to **Use** to detect battery errors.

	What is af-	Behavior		
Cause of error	fected	When the Battery-related error detection is set to Do not use	When the Battery-related error detection is set to Use	
One of the following was detected at power ON.  Built-in capacitor discharged  Battery not mounted  Mounted battery discharged	Clock data  Error detection	In case of clock oscillator stoppir     Time measurement starts from J.     In case of low battery voltage     Time measurement continues.  No error is detected.		
One of the following was detected	Clock data	Time measurement continues.		
<ul><li>after power ON.</li><li>Battery was removed</li><li>Mounted battery discharged</li></ul>	Error detection	No error is detected.	The following error is detected.  • Low Battery Voltage	

When you mount the battery, set the **Battery-related error detection** to **Use**.

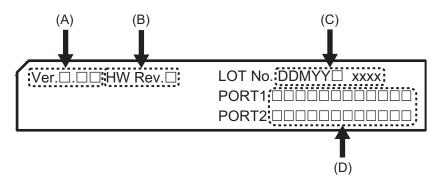
The measurement of clock data starts from January 1st, 1970 if the clock oscillator stops. If this occurs, readjust the CPU Unit's clock data to the current time.

In order to use the clock data for programming, you need to use system-defined variables to read the presence or absence of the Low Battery Voltage and Real-Time Clock Stopped errors and confirm that the clock data is normal.

Refer to the *Sysmac Studio Version 1 Operation Manual (Cat. No. W504)* for battery-related error detection and clock data settings.

# 3-1-7 ID Information Indication

You can check the followings in the ID information indications on the right side of the CPU Unit.



Letter	Name	Function	
Α	Unit version	Shows the unit version of the CPU Unit.	

Letter	Name	Function	
В	Hardware revision	Shows the hardware revision of the CPU Unit. *1	
С	Lot number and serial number	Shows the lot number and the serial number of the CPU Unit.  DDMYY: Lot number, □: For use by OMRON, SSSS: Serial number	
		M is 1 to 9 for January to September, X for October, Y for November, and Z for December.	
D	MAC addresses	Shows the MAC addresses of the built-in EtherNet/IP ports (port 1 and port 2) on the CPU Unit.	

<sup>\*1.</sup> The hardware revision is not displayed for the Unit that the hardware revision is in blank.

# 3-2 SD Memory Cards

This section describes the models, specifications, and application of the SD Memory Cards.

# 3-2-1 Models and Specifications

Refer to Specification of Supported SD Memory Cards, Folders, and Files in the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for details.

# 3-2-2 Purpose

You can use the SD Memory Card for the following applications.

- · Read and write files in the SD Memory Card with instructions.
- · Read and write files in the SD Memory Card from an FTP client on EtherNet/IP.
- · Back up, restore, and verify data in the Controller.
- Transfer data from the SD Memory Card to the Controller when the power is turned ON.

Refer to the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for details on the functions for SD Memory Cards.

# 3-3 Power Supply-related Units

The following NX Units are the NX-series power supply-related Units. When configuring NX Units, you can use these Units as necessary to supply power to the NX Units. These NX Units are collectively called as the System Units.

- · Additional NX Unit Power Supply Unit
- · Additional I/O Power Supply Unit
- I/O Power Supply Connection Unit

Refer to 4-1-2 NX-series Power Supply-related Units on page 4-3 for details on the functions of NX-series power supply-related Units.

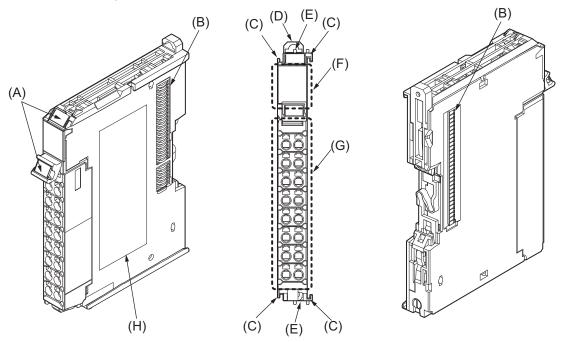
# 3-4 NX Units

The NX Units perform I/O processing with connected external devices. The NX Units refers to NX-series NX-

Up to 32 NX Units can be connected to the CPU Unit.

The following is an example of NX Unit's part names and functions.

For details on the part names and functions of NX Units, refer to the user's manual for each NX Unit.



Symbol	Name	Function	
Α	Marker attachment loca-	The locations where markers are attached. OMRON markers are pre-in-	
	tion	stalled at the factory. You can also install commercially available mark-	
		ers.	
В	NX bus connector	This connector is used to connect another Unit.	
С	Unit hookup guides	These guides are used to connect two Units.	
D	DIN Track mounting hook	This hook is used to mount the NX Unit to a DIN Track.	
E	Protrusions for removing	The protrusions to hold when removing the Unit.	
	the Unit		
F	Indicators	The indicators show the current operating status of the Unit.	
G	Terminal block	The terminal block is used to connect external devices.	
		The number of terminals depends on the type of Unit.	
Н	Unit specifications	The specifications of the Unit are given here.	

# 3-5 Sysmac Studio

The Sysmac Studio is a Support Software package that provides an integrated development environment to design, program, debug, and maintain NJ/NX-series Controllers.

This section describes the models and connecting methods of the Sysmac Studio.

# 3-5-1 Model Numbers

The model numbers of the Sysmac Studio are given in the following table. The model numbers are different for the media and licenses.

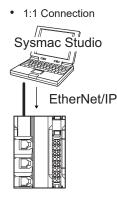
Product	Configuration software	Media	Number of user licenses	Model
Sysmac Studio	Sysmac Studio	DVD		SYSMAC-SE200D
Standard Edition	The following Support Software is also	Licenses	1	SYSMAC-SE201L
	included.  Network Configurator  CX-Integrator  CX-Protocol  CX-Designer		3	SYSMAC-SE203L
			10	SYSMAC-SE210L

# 3-5-2 Connection

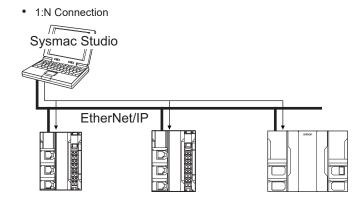
With an NX102 CPU Unit, you can connect the Sysmac Studio online in the following ways.

# Configuration

## Connection with EtherNet/IP



- A direct connection is made from the computer that runs Sysmac Studio. You do not need to specify the IP address or connection device.
- You can make the connection whether or not an Ethernet switch is used.
- Support for Auto-MDI enables the use of cross cables or straight cables if a direct connection is made.



• Directly specify the IP address of the remote device.

<sup>\*1.</sup> This function is available only when you connect Sysmac Studio to the built-in EtherNet/IP port (PORT1).

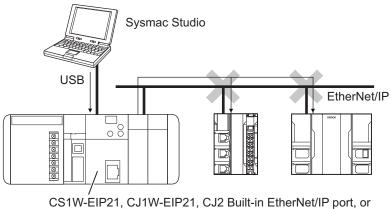


#### **Additional Information**

The Sysmac Studio cannot connect online to an NJ/NX-series CPU Unit in the following type of configuration.

• If the built-in EtherNet/IP port is not used, you cannot connect to an NJ/NX-series CPU Unit on an EtherNet/IP network.

Example: Connection to NJ/NX-series CPU Unit Routing through an EtherNet/IP Unit or Built-in EtherNet/IP Port



CS1W-EIP21, CJ1W-EIP21, CJ2 Built-in EtherNet/IP port, or CJ2M Built-in EtherNet/IP port

• You cannot route through any networks other than EtherNet/IP networks.



# Designing the Power Supply System

This section describes how to design the power supply system for the NX-series NX102 CPU Unit.

4-1	Powe	r Supply System	4-2
•	4-1-1 4-1-2	NX Unit Power Supply and I/O Power Supply NX-series Power Supply-related Units	4-2
4-2	Desig	ning the NX Unit Power Supply System	4-10
	4-2-1	Procedure for Designing the NX Unit Power Supply System	
	4-2-2	Calculation Example for the NX Unit Power Supply	
4-3	Desig	ning the I/O Power Supply System	4-13
	4-3-1	I/O Power Supply Method	
	4-3-2	Designing the I/O Power Supply from the NX Bus	
	4-3-3	Designing the I/O Power Supply from External Sources	
	4-3-4	Restrictions on Inrush Current for ON/OFF Operation	
4-4	Selec	ting External Power Supplies and Protective Devices	4-21
	4-4-1	Selecting the Unit Power Supply	
	4-4-2	Selecting the I/O Power Supplies	
	4-4-3	Selecting Protective Devices	4.04

# 4-1 Power Supply System

The power supply system for the CPU Rack of the NX-series NX102 CPU Unit consists of two power supply lines: one for NX Unit power and the other for I/O power. Therefore, you need to prepare two separate external power supplies for them.

You may need additional power supply Units for NX Unit power or I/O power according to the total power consumption or the total current consumption of NX Units on the CPU Rack.

Design the power supply system for the CPU Rack of the NX-series NX102 CPU Unit as below.

- Calculate the NX Unit power consumption to determine NX Unit power supply specifications, including whether to add additional power supply Units or not.
- Calculate the I/O power current consumption and voltage drop to determine I/O power supply specifications, including whether to add additional power supply Units or not.

# 4-1-1 NX Unit Power Supply and I/O Power Supply

This section provides details on NX Unit power supply and I/O power supply.

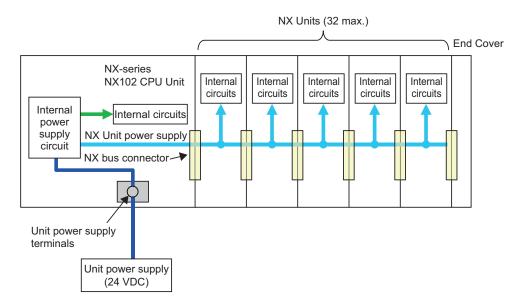
# **NX Unit Power Supply**

NX Unit power is supplied to the internal circuits of each NX Unit on the CPU Rack of the NX102 CPU Unit.

It is delivered via the Unit power supply terminals of the CPU Unit or those of an Additional NX Unit Power Supply Unit. Those terminals are connected to an external power supply device, which is referred to as an Unit power supply.

The Unit power supply provides power for the internal circuits of the CPU Unit, as well as NX Unit power for the NX Units.

Up to 10 W of NX Unit power can be delivered to NX Units via the NX bus connectors.



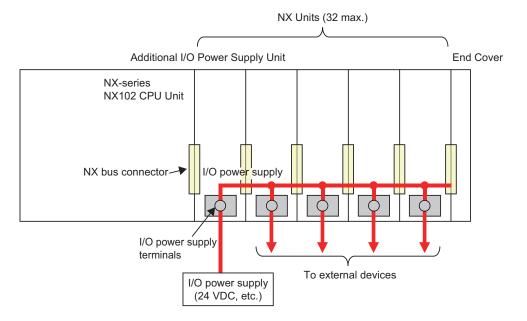
# **I/O Power Supply**

I/O power is supplied to the I/O circuits of each NX Unit on the CPU Rack of the NX102 CPU Unit, as well as to external devices connected to the NX Units.

Some NX Units receive I/O power through the NX bus, and others receive from external devices. If any NX Unit on the CPU Rack receives I/O power through the NX bus, you need to prepare an external I/O power supply device. For details on how to supply I/O power to NX Units, refer to the datasheet included in the user's manuals for the NX Units.

To connect an external I/O power supply, you need an Additional I/O Power Supply Unit. Connect its power supply terminals to the I/O power supply.

The I/O power supply can provide up to 10 A for NX Units via the NX bus connectors.





#### **Precautions for Correct Use**

Make sure to prepare separate power supply devices for NX Unit power and I/O power. Using the same power supply for them may generate noise and result in malfunction.

# 4-1-2 NX-series Power Supply-related Units

There are three types of NX-series power supply-related Units: Additional NX Unit Power Supply Unit, Additional I/O Power Supply Unit, and I/O Power Supply Connection Unit. The following table explains each Unit.

Unit name	Description
Additional NX	Supply additional NX Unit power via this Unit if the total power consumption of the internal
Unit Power Sup-	circuits of the NX Units on the CPU Rack exceeds the NX Unit power supply capacity of the
ply Unit	CPU Unit.

Unit name	Description
Additional I/O Power Supply Unit	<ul> <li>Connect an external I/O power supply to this Unit to deliver the I/O power to NX Units on the CPU Rack through the NX bus, if necessary.</li> <li>Supply additional I/O power via this Unit if over 10 A is consumed in total by the I/O circuits of the NX Units on the CPU Rack and external devices connected to the NX Units.</li> <li>Supply additional I/O power via this Unit if the I/O power voltage goes below the voltage levels specified for the I/O circuits of the NX Units on the CPU Rack or those specified for the connected external devices.</li> <li>Insert this Unit to separate the I/O power supply line if any NX Unit on the CPU Rack is connected to an external device with a different I/O power supply voltage.</li> <li>Insert this Unit to separate the I/O power supply line to prevent noise and other factors from affecting the other NX Units.</li> </ul>
I/O Power Sup- ply Connection Unit	Add this Unit to provide additional I/O power supply terminals if required to connect external devices to a Digital I/O Unit or Analog I/O Unit.

For the specifications of NX-series power supply-related Units, refer to the *NX-series System Units User's Manual (Cat. No. W523*). For information on the latest lineup of the NX-series power supply-related Units, refer to the relevant catalogs or OMRON websites, or ask your OMRON representative.

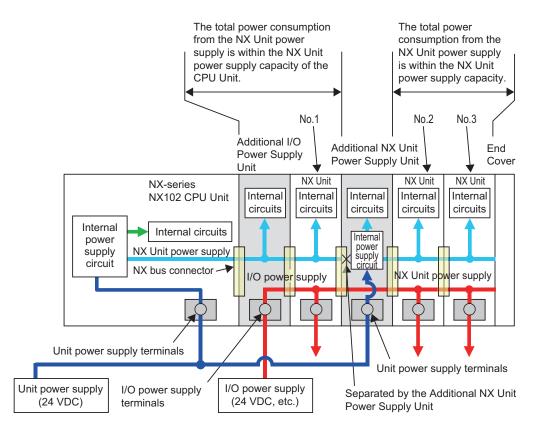
# **Additional NX Unit Power Supply Unit**

You can use Additional NX Unit Power Supply Units to deliver additional supply of NX Unit power when the total power consumption of the internal circuits of NX Units on the CPU Rack exceeds the NX Unit power supply capacity of the CPU Unit.

The following figure shows how to use an Additional NX Unit Power Supply Unit. Assume that three NX Units, No.1 to No.3, are connected to the CPU Rack, as shown below. Also assume that only NX Unit No.1 is supplied with adequate NX Unit power because the total power consumption of the internal circuits of the three NX Units exceeds the NX Unit power supply capacity of the CPU Unit. In this case, insert an Additional NX Unit Power Supply Unit between NX Units No.1 and No.2. Connect its Unit power supply terminals to the Unit power supply. The NX Unit power is supplied to NX Units No.2 and No.3 via the inserted Additional NX Unit Power Supply Unit, instead of the CPU Unit.

More than one Additional NX Unit Power Supply Unit can be connected to the CPU Rack. If adequate NX Unit power is not provided for all the NX Units on the right side of the Additional NX Unit Power Supply Unit, add another Additional NX Unit Power Supply Unit to an appropriate place.

Basically, the NX Unit power supply line connects adjacent NX Units through the NX bus. However, the NX Unit power supply line is separated by an inserted Additional NX Unit Power Supply Unit. In the figure below, the NX Unit power supply line is separated between NX Unit No.1 and the Additional NX Unit Power Supply Unit. However, the I/O power supply line is not separated by the Additional NX Unit Power Supply Unit. Therefore, the I/O power supply line is connected through all the NX Units, No.1 to No.3.



# Additional I/O Power Supply Unit

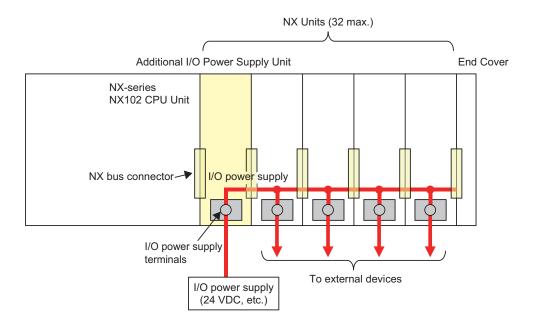
The following explains how to use Additional I/O Power Supply Units.

- Connect an external I/O power supply to this Unit to deliver the I/O power to NX Units through the NX bus, if necessary.
- Supply additional I/O power via this Unit if over 10 A is consumed in total by the I/O circuits of the NX Units on the CPU Rack and external devices connected to the NX Units.
- Supply additional I/O power via this Unit if the I/O power voltage goes below the voltage levels specified for the I/O circuits of the NX Units on the CPU Rack or those specified for the connected external devices.
- Insert this Unit to separate the I/O power supply line if any NX Unit on the CPU Rack is connected to an external device with a different I/O power supply voltage.
- Insert this Unit to separate the I/O power supply line to prevent noise and other factors from affecting the other NX Units.

#### • I/O Power Supply for NX Units through the NX Bus

Some NX Units receive I/O power through the NX bus, and others receive from external devices. If any NX Unit on the CPU Rack receives I/O power through the NX bus, you need to prepare an external I/O power supply device. For details on how to supply I/O power to NX Units, refer to the datasheet included in the user's manuals for the NX Units.

Insert an Additional I/O Power Supply Unit on the right side of the CPU Unit, as shown below. Connect its power supply terminals to an external I/O power supply device. It supplies I/O power to all the NX Units through the NX bus.



#### Additional Supply of I/O Power

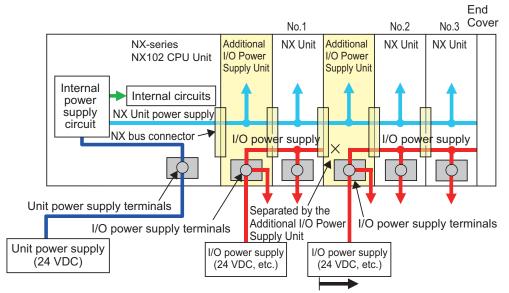
In the following cases, you need another Additional I/O Power Supply Unit in addition to the one inserted on the right side of the CPU Unit.

- Over 10 A is consumed in total by the I/O circuits of the NX Units on the CPU Rack and external devices connected to the NX Units.
- The I/O power voltage goes below the voltage levels specified for the I/O circuits of the NX Units on the CPU Rack or those specified for the connected external devices.

Assume that three NX Units, No.1 to No.3, are connected to the CPU Rack, as shown below. Also assume that only NX Unit No.1 is supplied with adequate current and voltage because one existing Additional I/O Power Supply Unit and one external I/O power supply device cannot cover the total current consumption of the I/O circuits of the three NX Units, the total current consumption of the connected external devices, or I/O power voltage. In this case, insert another Additional I/O Power Supply Unit between NX Units No.1 and No.2. Connect its I/O power supply terminals to an I/O power supply device which is prepared separately from the one connected to the existing Additional I/O Power Supply Unit. The I/O power is supplied to NX Units No.2 and No.3 via the inserted Additional I/O Power Supply Unit.

More than one Additional I/O Power Supply Unit can be connected to the CPU Rack. If adequate I/O power is not provided for all the NX Units on the right side of the Additional I/O Power Supply Unit, add another Additional I/O Power Supply Unit to an appropriate place.

Basically, the I/O power supply line connects adjacent NX Units through the NX bus. However, the I/O power supply line is separated by an inserted Additional I/O Power Supply Unit. In the figure below, the I/O power supply line is separated between NX Unit No.1 and the Additional I/O Power Supply Unit. However, the NX Unit power supply line is not separated by the Additional I/O Power Supply Unit. Therefore, the NX unit power supply line is connected through all the NX Units, No.1 to No.3, as shown below.



When the I/O power supply becomes the following states for the subsequent NX Units.

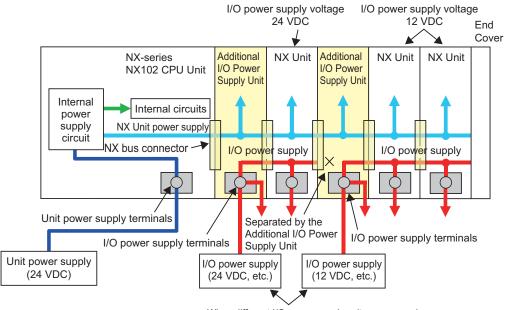
- When it exceeds the maximum I/O power supply current, 10 A
- When it goes below the voltage specifications of the connected external devices

## Separating the I/O Power Supply Line

Insert an Additional I/O Power Supply Unit to separate the I/O power supply line when you connect an NX Unit on the CPU Rack to an external device with a different I/O power voltage, or when you prevent noise or other factors from affecting other NX Units.

Assume that the CPU Rack contains one NX Unit with I/O power voltage of 24 VDC and two NX Units with 12 VDC, as shown in the figure below. In this case, you need two Additional I/O Power Supply Units; one for the NX Unit with 24 VDC, and the other for the two NX Units with 12 VDC. Connect the I/O power supply terminals of each to the corresponding I/O power supply device with 24 VDC or 12 VDC.

Basically, the I/O power supply line connects adjacent NX Units through the NX bus. However, the I/O power supply line is separated by an inserted Additional I/O Power Supply Unit. In the figure below, the I/O power supply line is separated between the NX Units with 24 VDC and the ones with 12 VDC. However, the NX Unit power supply line is connected through all the NX Units.



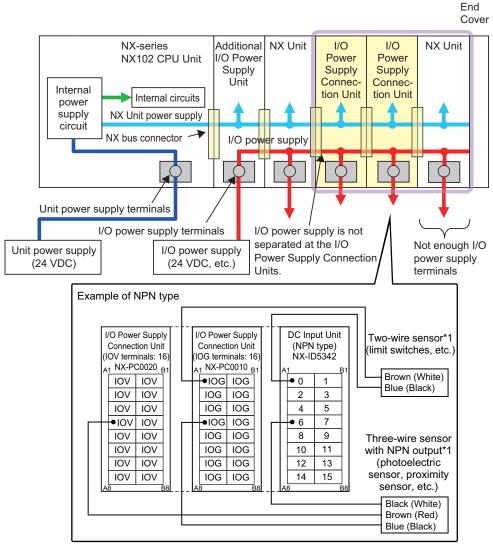
- When different I/O power supply voltage are used
- When the power supply systems is separated

# I/O Power Supply Connection Unit

You can add an I/O Power Supply Connection Unit to provide additional I/O power supply terminals if required to connect external devices to a Digital I/O Unit or Analog I/O Unit.

The following figure shows how to use I/O Power Supply Connection Units. Assume that a PNP-type Digital Input Unit, NX-ID5342, is used to input signals from a two-wire sensor and a three-wire sensor with NPN output. The NX-ID5342 Digital Input Unit does not have I/O power terminals. For the Digital Input Unit, you need to prepare IOG terminals for the two-wire sensor, and IOV terminals as well as IOG terminals for the three-wire sensor. Insert two I/O Power Supply Connection Units: one is NX-PC0020 with 16 IOV terminals, and the other is NX-PC0010 with 16 IOG terminals. Wire them as shown in the figure below.

The NX Unit power supply line as well as the I/O power supply line is connected between the I/O Power Supply Connection Units and adjacent NX Units through the NX bus.



<sup>\*1.</sup> Wire colors have been changed according to revisions in the JIS standards for photoelectric and proximity sensors. The colors in parentheses are the wire colors prior to the revisions.

# 4-2 Designing the NX Unit Power Supply System

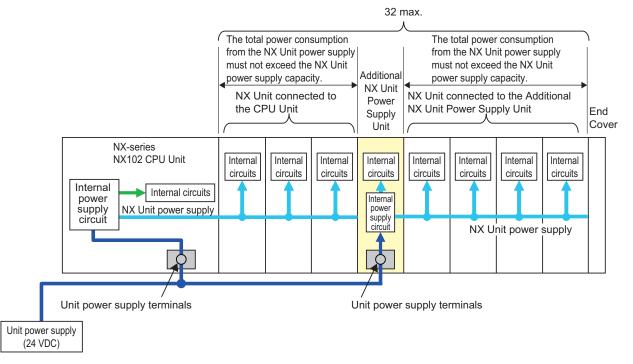
This section describes how to design the NX Unit power supply to the CPU Rack of the NX-series NX102 CPU Unit.

# 4-2-1 Procedure for Designing the NX Unit Power Supply System

The total power consumption from the NX Unit power supply must not exceed the NX Unit power supply capacity of the Unit that supplies the NX Unit power.

Use the following procedure to design the NX Unit power supply.

- 1 Calculate the total power consumption from the NX Unit power supply that is required by the NX Units that are connected to the CPU Unit.
- 2 If the total power consumption from the NX Unit power supply exceeds the NX Unit power supply capacity of the CPU Unit, add an Additional NX Unit Power Supply Unit to the right of an NX Unit before the capacity is exceeded.
- Calculate the total power consumption from the NX Unit power supply that is required by the NX Units that are connected after the Additional NX Unit Power Supply Unit. If the total power consumption of those NX Units exceeds the NX Unit power supply capacity of the Additional NX Unit Power Supply Unit, add another Additional NX Unit Power Supply Unit to the right of an NX Unit before the capacity is exceeded.
- 4 Repeat step 3 until the design conditions for the NX Unit power supply are met.



### • NX Unit Power Supply Capacity and Restrictions

The internal power supply circuits of the CPU Unit or Additional NX Unit Power Supply Unit supply the NX Unit power to the NX Units.

The NX Unit power supply capacity does not include the NX Unit power consumption of the Additional NX Unit Power Supply Units.

The power supply capacity of the CPU Unit is 10 W.

For restrictions on the Additional NX Unit Power Supply Unit, refer to the *NX-series System Units User's Manual* (Cat. No. W523).



#### **Precautions for Correct Use**

- Do not exceed the NX Unit power supply capacity. If you exceed the NX Unit power supply capacity, malfunction may occur.
- Use the same Unit power supply to supply the Unit power to the entire CPU Rack. If you supply power from different Unit power supplies, differences in electrical potential may cause unexpected currents in the NX Unit power supply, which may result in failure or malfunction.

## 4-2-2 Calculation Example for the NX Unit Power Supply

This section provides a calculation example for the NX Unit power supply.

### Unit Configuration Example

Name	Model	Quanti- ty	Power consumption/Unit*1
CPU Unit	NX102-1200	1	5.80 W
Additional I/O Power Supply Unit	NX-PF0630	1	0.85 W
Digital Input Unit	NX-ID3317	4	0.90 W
Relay Output Unit	NX-OC2633	3	1.20 W

<sup>\*1.</sup> For the power consumption of NX Units connected to CPU Unit, refer to the user's manuals for the respective NX Units.

## • Calculating the Total Power Consumption from the NX Unit Power Supply

Calculate the total power consumption from the NX Unit power supply that is required by the NX Units that are connected to the CPU Unit.

Total power consumption from NX Unit power supply [W] = 0.85 W × 1 + 0.90 W × 4 + 1.20 W × 3 = 8.05 W

### Confirming the NX Unit Power Supply Capacity of the CPU Unit

The NX Unit power supply capacity is 10 W max.

Therefore, in this example, the total power consumption from the NX Unit power supply is 8.05 W, and the NX Unit power supply capacity is 10 W max., so the design conditions are met.



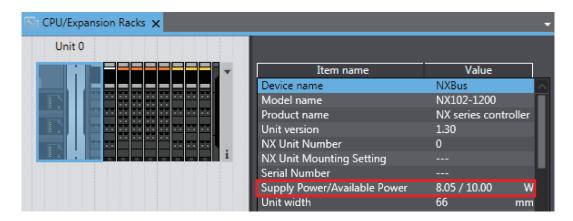
### **Additional Information**

Excess or insufficiency in the NX Unit power supply capacity can be easily checked when the Unit configuration is created on the CPU and Expansion Racks Tab Page on the Sysmac Studio.

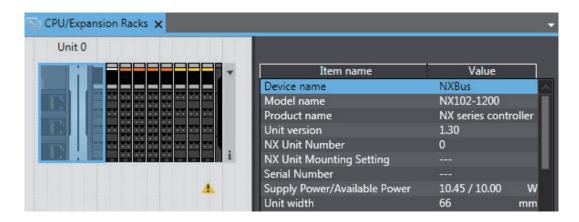
Use the following procedure to check the power supply capacity.

On the CPU and Expansion Racks Tab Page on the Sysmac Studio, select the Unit to supply NX Unit power. The power that is supplied by the NX Unit power supply (i.e., the total power consumption) and the power supply capacity are displayed for the **Supply Power/Available Power** parameter.

The following example is for when selecting the NX102 CPU Unit.



If the power to supply exceeds the NX Unit power supply capacity of the Unit that is selected to supply the NX Unit power, a yellow warning icon is displayed by the first NX Unit for which there is not sufficient capacity and also by all the remaining NX Units.



The Sysmac Studio does not consider the I/O power supply design conditions. When actually designing the power supply, refer to 4-3-2 Designing the I/O Power Supply from the NX Bus on page 4-14.

# 4-3 Designing the I/O Power Supply System

This section describes how to design the I/O power supply to the NX Units connected to the NX-series NX102 CPU Unit.

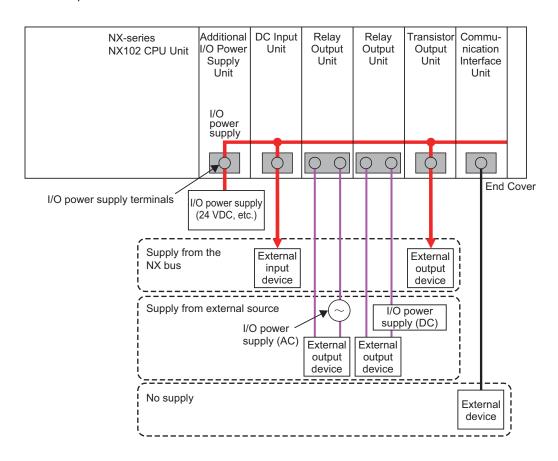
## 4-3-1 I/O Power Supply Method

There are the following three methods to supply the I/O power supply to the NX Units depending on the type and model of the NX Units.

Supply method	Description
Supply from the NX bus	Power is supplied through the NX bus connectors by connecting an I/O power supply to the I/O power supply terminals on the Additional I/O Power Supply Units.
Supply from external source	Power is supplied to the Units from an external source.  I/O power is supplied by connecting an I/O power supply to the terminal blocks on the Units.
No supply	The I/O power supply is not needed when the NX Unit does not use it for the connected external devices, or when power for the interface is generated inside the NX Unit.

Refer to the user's manuals for individual NX Units or to the *NX-series Data Reference Manual (Cat. No. W525)* for the power supply method for specific NX Units.

An example is shown below.



# 4-3-2 Designing the I/O Power Supply from the NX Bus

# Procedure for Designing the I/O Power Supply

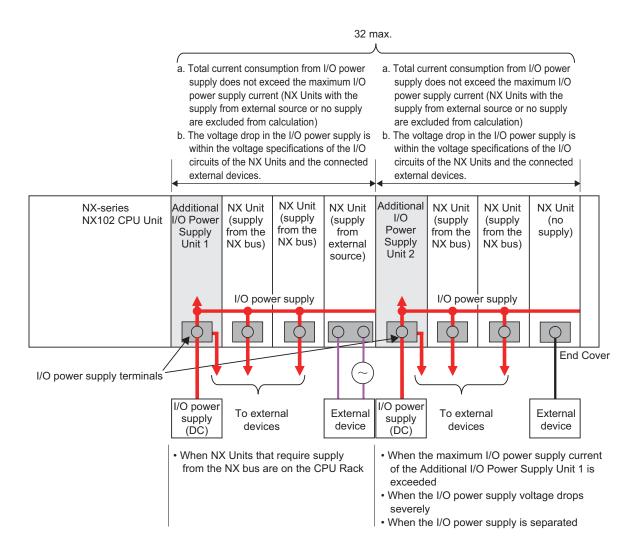
The procedure is explained under the precondition that an Additional I/O Power Supply Unit is connected to the right side of the CPU Unit because an NX Unit that requires the power supply from NX bus is mounted on the CPU Rack.

Make sure that the following design conditions are met when you design the I/O power supply from the NX bus.

- The total current consumption from the I/O power supply must not exceed the maximum I/O power supply current of the Unit that supplies the I/O power.
- The voltage drop in the I/O power supply must be within the voltage specifications of the I/O circuits of the NX Units and the connected external devices.

Use the following procedure to design the I/O power supply.

- 1 Calculate the total current consumption from the I/O power supply of the NX Units that are connected to the CPU Unit and the CPU Unit, and calculate the voltage drop in the I/O power supply.
- Add an Additional I/O Power Supply Unit in either of the following cases, a) or b). Add the Additional I/O Power Supply Unit to the right of the NX Unit for which both a) and b) do not apply.
  - a) The total current consumption for the I/O power supply exceeds the I/O power supply capacity of the Additional I/O Power Supply Unit.
  - b) Voltage drop in the I/O power supply causes the voltage of the I/O power supply to go below the voltage specifications of the I/O circuits of the NX Units or the connected external devices.
- Calculate the voltage drop in the I/O power supply after the Additional I/O Power Supply Unit and the total current consumption from the I/O power supply that is required by the Additional I/O Power Supply Unit and by the NX Units that are connected after the Additional I/O Power Supply Unit. Add another Additional I/O Power Supply Unit in either of the following cases, a) or b). Add the Additional I/O Power Supply Unit to the right of the NX Unit for which both a) and b) do not apply.
  - a) The total current consumption for the I/O power supply exceeds the I/O power supply capacity of the Additional I/O Power Supply Unit.
  - b) Voltage drop in the I/O power supply causes the voltage of the I/O power supply to go below the voltage specifications of the I/O circuits of the NX Units or the connected external devices.
- 4 Repeat step 3 until the design conditions for the I/O power supply are met.



### Maximum I/O Power Supply Current

The maximum I/O power supply current is the maximum current that the I/O power supply that is connected to the Additional I/O Power Supply Unit can supply through the NX bus connectors to the NX Units.

For information on the maximum I/O power current supplied from the Additional I/O Power Supply Unit, refer to the *NX-series System Units User's Manual (Cat. No. W523)*.

# Calculating the Total Current Consumption from the I/O Power Supply

The total current consumption from the I/O power supply from the NX bus is the total of the following current consumptions.

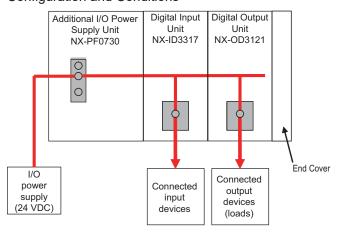
- The current consumption from the I/O power supply that is required for the Additional I/O Power Supply Unit and for the NX Units that are connected to the Additional I/O Power Supply Unit
- · The current consumption between the NX Units and the connected external devices

Current consumption item	Description
Current consumption from I/O power	This is the current that is consumed by the internal circuits that operate on the I/O
supply	power supply.
	Specific values are given in the user's manuals for individual Units.
Current consumption between the NX	This is the current that is consumed between the NX Units and the connected exter-
Units and the connected external de-	nal devices.
vices	For example, this is the current consumed by a Digital Input Unit to supply power to
	photoelectric sensors or to turn ON the input circuits in the Digital Input Unit.
	The current consumption depends on the type of I/O circuit in the NX Unit, the num-
	ber of I/O points that are used, and the current consumption of the connected exter-
	nal device. It must be calculated for each NX Unit.

### Calculation Example of I/O Power Supply Capacity

An example of calculating the required power supply capacity of the I/O power supply is given below.

### Configuration and Conditions



	Item				
I/O power supply voltage		24 VDC			
Inputs	Number of inputs used (that turn ON simultaneously)	4 points			
	Current consumption of connected input devices	50 mA/point			
Outputs	Number of outputs (that turn ON simultaneously)	4 points			
	Load current of connected loads	125 mA/point			
	Current consumption of connected output devices	50 mA/point			

I/O power is supplied to the NX-ID3317 and NX-OD3121 from the NX bus.

### a. Unit Specifications

Model	Current consumption from I/O power supply	Input current
NX-PF0730	10 mA	
NX-ID3317	0 mA	6 mA/point
NX-OD3121	10 mA	

### b. Calculations

The current consumption from the I/O power supply for each Unit is calculated as follows.

NX-PF0730 Current Consumption	=	Current consumption from I/O power supply	
	=	10 mA	
			-

NX-ID3317 Current Consumption	=	Current consumption from I/O power supply + (Input current × Number of inputs used) + Total current consumption of connected input devices
	=	0 mA + (6 mA × 4 points) + (50 mA × 4 points)
	=	224 mA

NX-OD3121 Current Consumption	=	Current consumption from I/O power supply + Total load current of connected loads + Total current consumption of connected output devices
	=	10 mA + (125 mA × 4 points) + (50 mA × 4 points)
	=	710 mA

The required power supply capacity for the I/O power supply is calculated as follows.

Power supply capacity of I/O power supply	=	(Current consumed by NX-PF0730) + (Current consumed by NX-ID3317) + (Current consumed by NX-OD3121)
	=	10 mA + 224 mA +710 mA
	=	944 mA

# Calculating the Voltage Drop in the I/O Power Supply

Voltage drop occurs in the CPU Units and NX Units due to the contact resistance at the points where Units are connected to each other. Design the I/O power supply system to maintain the voltage specifications of the NX Unit I/O circuits and connected external devices even if the voltage of the I/O power supply drops.

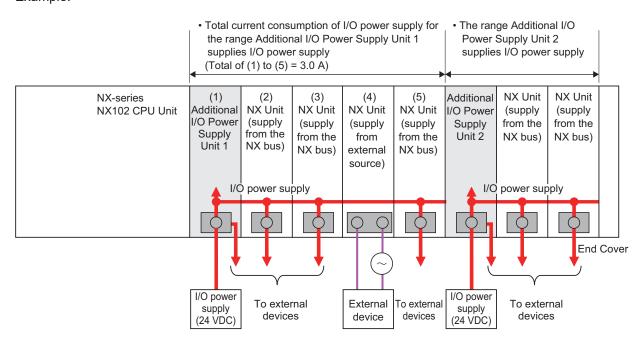
As shown in the following table, the voltage drop per Unit depends on the total current consumption from the I/O power supply.

In this case, the total current consumption from the I/O power supply must not exceed the maximum I/O power supply current of the Unit that supplies the I/O power.

Total current consumption from the I/O power supply	Voltage drop per Unit
10 A	0.20 V
8 A	0.16 V
6 A	0.12 V
4 A	0.08 V
3 A	0.06 V
2 A	0.04 V
1 A	0.02 V

The following is a calculation example of the I/O power supply range applicable to the additional I/O power supply unit that is located on the right side of CPU Unit based on a unit configuration example shown below. You can also use the same calculation procedure to calculate the I/O power supply range after you add more I/O power supply units in addition to the first one.

### Example:



I/O power supply current consumption of each Unit

(1) :  $0.0 \text{ A}^{*1}$  (supply from the NX bus)

(2), (3) : 0.5 A each (supply from the NX bus)

(4) : 0.0 A (supply from external source)

(5) : 2.0 A (supply from the NX bus)

\*1. The current consumption of the Additional I/O Power Supply Unit is not actually 0 A. However, a value of 0 A is used in this calculation example.

In actual calculations, add the current consumption from the I/O power supply that is given in the *NX-series Data Reference Manual (Cat. No. W525*).

#### Outline

Find the I/O power supply voltage of the NX Unit that is the farthest from the Additional I/O Power Supply Unit 1.

In this example, the I/O power supply voltage of Unit (E) is found.

### Conditions

Assume that an I/O power supply voltage of 24.00 VDC is supplied to the I/O power supply terminals on the Additional I/O Power Supply Unit 1.

### Procedure

1 Use the following formula to calculate the total current consumption from the I/O power supply.

```
Total current consumption from the I/O power supply = (1) + (2) + (3) + (4) + (5)
= 0.0 + 0.5 + 0.5 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.0 + 0.
```

**2** Find the I/O power supply voltage and make sure that it is within the voltage specifications of the I/O circuits of the NX Units and the connected external devices.

```
I/O power supply voltage at (5) = I/O power supply voltage on I/O power supply terminals – Voltage drop per
Unit × Number of Units passed through
= 24.00 V - 0.06 V × (5 - 1 Units)
= 23.76 V
```

# **Design to Separate the I/O Power Supply**

If the I/O power supply voltages of the connected external devices are different, connect an Additional I/O Power Supply Unit at the point where the I/O power supply voltage changes and then perform similar calculations to design a system that meets the power supply conditions. The same method is used to separate the power supply systems. Connect an Additional I/O Power Supply Unit at the point where the power supply systems to be separated and then perform similar calculations to design the overall system to meet the power supply conditions.

# 4-3-3 Designing the I/O Power Supply from External Sources

Unlike supplying power from the NX bus, there is no specific design method for supplying I/O power from external sources.

Calculate the total current consumption from the I/O power supply for the NX Units to be supplied power from an external source.

Refer to the user's manuals of the NX Units for the total current consumption from the I/O power supply.

# 4-3-4 Restrictions on Inrush Current for ON/OFF Operation

This section describes the restrictions on inrush current from the I/O power supply that occurs when connected external devices turn ON and OFF.

## **Inrush Current Restrictions**

If inrush current to the I/O power supply occurs when a connected external device turns ON or OFF, do not allow the effective value of the I/O power supply current to exceed the following rated values when the inrush current is added to the current consumption from the I/O power supply.

- Maximum I/O power supply current
- · Current capacity of power supply terminals for the I/O power supply

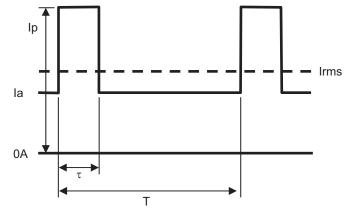
Also, maintain the peak inrush current 20 A maximum and maintain the pulse width 1 s maximum. Refer to 4-4-3 Selecting Protective Devices on page 4-24 for the rated values of the items when the CPU Rack is used.

# Calculating the Effective Value of the I/O Power Supply Current

The formula to calculate the effective value of the I/O power supply current, Irms, is given below.

Irms=
$$\sqrt{Ip^2 \times D + Ia^2 \times (1-D)}$$
  
(D= $\tau/T$ )

- Ip: Peak inrush current (A)
- Irms: Effective value of I/O power supply current (A)
- · la: Total current consumption from the I/O power supply (A)
- · D: Inrush current duty
- τ: Inrush current pulse width (s)
- T: Inrush current period (s)



# 4-4 Selecting External Power Supplies and Protective Devices

This section describes how to select the Unit power supply and the I/O power supply which are the external power supplies for the CPU Rack, and how to select the protective devices.

## 4-4-1 Selecting the Unit Power Supply

This section describes how to select the Unit power supply for the CPU Rack.

# **Recommended Power Supplies**

Use an SELV power supply that meets the following conditions for the Unit power supply.

- · Has overcurrent protection.
- · Has double or reinforced insulation between the input and output.
- Has an output voltage of 24 VDC (20.4 to 28.8 VDC).

Recommended Power Supplies: S8VK-S Series (manufactured by OMRON)

# Calculating the Required Power Supply Capacity of the Unit Power Supply

### Formula

This section describes how to calculate the required capacity of the Unit power supply for the CPU Rack.

Required capacity of the Unit power supply for	=	Total of required Unit power supply capacity for
the CPU Rack		each block

Use the following formula to calculate the required Unit power supply capacity for each block in the CPU Rack.

Required Unit power supply capacity of the CPU Unit block = (A) + (B)/(C)

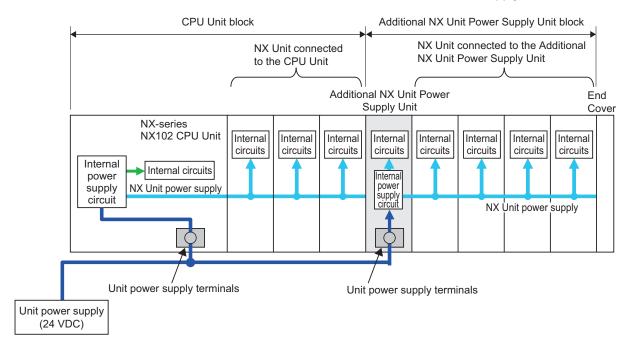
Required Unit power supply capacity of an Additional NX Unit Power Supply Unit block = ((D) + (E))/(F)

(A)	Unit power consumption of the CPU Unit
(B)	Total NX Unit power consumption of NX Units that are connected to the CPU Unit
(C)	NX Unit power supply efficiency of the CPU Unit
(D)	NX Unit power consumption of the Additional NX Unit Power Supply Unit
(E)	Total NX Unit power consumption of NX Units that are connected to the Additional NX Unit
	Power Supply Unit
(F)	NX Unit power supply efficiency of the Additional NX Unit Power Supply Unit

### Blocks

A block consists of the Unit that supplies the NX Unit power and the range of Units to which that Unit supplies the NX Unit power.

For example, in the configuration in the following figure there are two blocks in the CPU Rack: the block with the CPU Unit and the block with the Additional NX Unit Power Supply Unit.



The total of the required Unit power supply capacity for these two blocks is the required power supply capacity of the Unit power supply for the CPU Rack.



## **Precautions for Correct Use**

Use the same Unit power supply to supply the Unit power to one CPU Rack. If you supply power from different Unit power supplies, differences in electrical potential may cause unexpected currents in the NX Unit power supply, which may result in failure or malfunction.

### Calculation Example

This section provides a calculation example for the configuration example that is given in 4-2-2 Calculation Example for the NX Unit Power Supply on page 4-11.

Name	Model	Quantity	Power consumption/Unit
CPU Unit	NX102-1200	1	5.80 W
Additional I/O Power Supply Unit	NX-PF0630	1	0.85 W
Digital Input Unit	NX-ID3317	4	0.90 W
Relay Output Unit	NX-OC2633	3	1.20 W

• The NX Unit power supply efficiency of the CPU Unit is 80%.

In this configuration example, there is only one block, the CPU Unit block. Required power supply capacity of Unit power supply to CPU Rack

= Required Unit power supply capacity of CPU Unit block

= (CPU Unit power consumption + Total power consumption from NX Unit power supply of NX Units connected to CPU Unit)/NX Unit power supply efficiency of CPU Unit

- $= 5.80 \text{ W} + (0.85 \text{ W} \times 1 + 0.90 \text{ W} \times 4 + 1.20 \text{ W} \times 3)/0.8$
- = Approx. 15.9 W

The above is the constant power consumption during operation. When you select the power supply, consider the inrush current that will flow when the power is turned ON.

Refer to *Electrical and Mechanical Specifications* on page 3-3 for information on inrush current specifications.



### **Precautions for Safe Use**

Select an external power supply with sufficient capacity by considering the power supply capacity or inrush current when the power is turned ON that is specified in this manual. Otherwise, the external power supply may not be turned ON or malfunction due to unstable power supply voltage.

# 4-4-2 Selecting the I/O Power Supplies

This section describes how to select the I/O power supplies for the CPU Rack.

# **Recommended Power Supplies**

Use an SELV power supply that meets the following conditions for the I/O power supply.

- · Has overcurrent protection.
- · Has double or reinforced insulation between the input and output.
- Has an output voltage of 5 to 24 VDC (4.5 to 28.8 VDC).\*1
- \*1. Use an output voltage that is appropriate for the I/O circuits of the NX Units and the connected external devices.

Recommended Power Supplies: S8VK-S Series (manufactured by OMRON)

# Calculating the Required Power Supply Capacity of the I/O Power Supply for NX Units

Use the calculation method that is described in 4-3-2 Designing the I/O Power Supply from the NX Bus on page 4-14 and calculate the total current consumption from the I/O power supply and the required power supply capacity of the I/O power supply.

Unlike the Unit power supply, it is not necessary to use only one I/O power supply to supply power to all NX Units on the CPU Rack.



### **Precautions for Safe Use**

Select an external power supply with sufficient capacity by considering the power supply capacity or inrush current when the power is turned ON that is specified in this manual. Otherwise, the external power supply may not be turned ON or malfunction due to unstable power supply voltage.

# 4-4-3 Selecting Protective Devices

This section describes how to select protective devices (e.g., breakers and fuses) to protect against short circuits and overcurrents in external circuits.

Overcurrent is the current that flows when an excessive load is connected and one of the following ratings is exceeded.

Unit	Item for rating	Rated value	
CPU Unit	NX Unit power supply capacity	10 W max.	
	Current capacity of power supply terminal	4 A max.	
Additional NX Unit Power	NX Unit power supply capacity	Refer to the NX-series System Units User's Manual (Cat. No. W523).	
Supply Unit	Current capacity of power supply terminal		
Additional I/O Power Supply	Maximum I/O power supply current		
Unit	Current capacity of I/O power supply ter-		
	minals		

# **Selecting Protective Devices**

Consider the following items when you select protective devices.

- Protective device specifications (breaking/fusing, detection characteristics, steady current value, etc.)
- · Inrush current when power is turned ON
- Inrush current when connected external devices turn ON and OFF\*1
- \*1. Refer to 4-3-4 Restrictions on Inrush Current for ON/OFF Operation on page 4-20 for information on the inrush current when connected external devices are turned ON and OFF.

For the breaking/fusing time, use protective devices that meet the conditions in the following table.

### For Unit Power Supply

Current	Breaking/fusing time
6 A	1 min max.
12 A	15 s max.
21 A	5 s max.
30 A	2.5 s max.

### For I/O Power Supply

The following values apply when the current capacity of power supply terminal is 10 A.

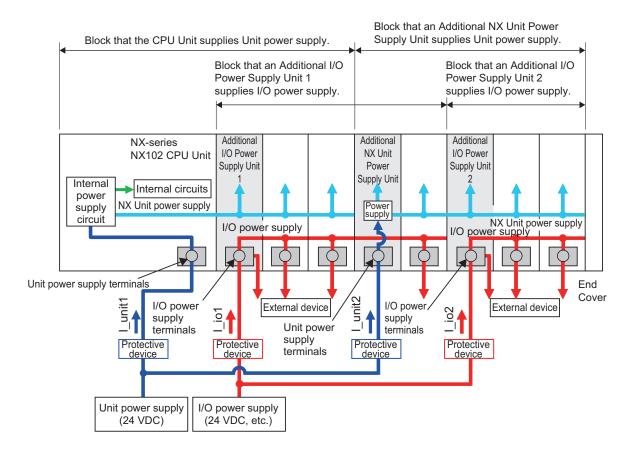
Current	Breaking/fusing time	
14 A	1 min max.	
28 A	9 s max.	
56 A	1.5 s max.	
70 A	0.8 s max.	

The following values apply when the current capacity of power supply terminal is 4 A.

Current	Breaking/fusing time
6 A	1 min max.
12 A	15 s max.
21 A	5 s max.
30 A	2.5 s max.

# **Installation Locations for Protective Devices**

Install protective devices for the Unit power supply and I/O power supply in the locations that are shown in the following figure.

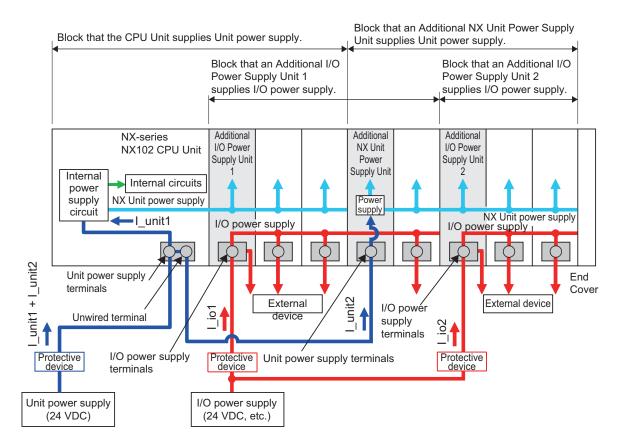


However, fewer protective devices may be required when the current consumption of each block does not exceed the rated current.

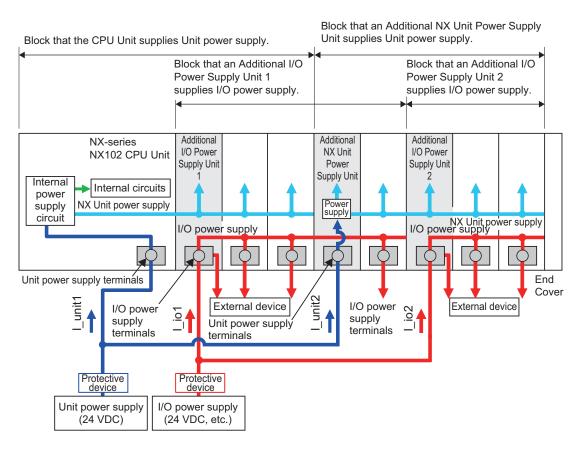
An example of this is provided below.

Using Unwired Unit Power Supply Terminals
 In this example, the current consumption from each power supply is as follows:
 Current consumption from Unit power supply: I\_unit1 + I\_unit2 ≤ Lowest rated current

 Current consumption from I/O power supply for NX Units: I io1 + I io2 ≥ Lowest rated current\*1



- \*1. The minimum value is selected among the rated currents of the multiple I/O Power Supply Units connected to the protective device. If, for example, two rated currents of 10 A and 4 A are used, 4 A will be selected.
- When Total Current Consumption for All Blocks Does Not Exceed the Rated Current
  In this example, the current consumption from each power supply is as follows:
   Current consumption from Unit power supply: I\_unit1 + I\_unit2 ≤ Lowest rated current
   Current consumption from I/O power supply for NX Units: I io1 + I io2 ≤ Lowest rated current\*1



\*1. The minimum value is selected among the rated currents of the multiple I/O power supply units connected to the protective device. If, for example, two rated currents of 10 A and 4 A are used, 4 A will be selected.

4 Designing the Power S	Supply System
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# **Installation and Wiring**

This section describes how to install and wire the NX-series NX102 CPU Unit as well as details on installation locations.

5-1	Proce	essing at Power ON and Power OFF	5-2
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# 5-1 Processing at Power ON and Power OFF

# riangle WARNING

- Do not touch any of the terminals or terminal blocks while the power is being supplied.
  - Doing so may result in electric shock.
- Do not attempt to take any Unit apart.
   In particular, high-voltage parts are present in the Power Supply Unit while power is supplied or immediately after power is turned OFF. Touching any of these parts may result in electric shock. There are sharp parts inside the Unit that may cause injury.



## 5-1-1 Power ON Operation



### **Precautions for Safe Use**

It takes a certain time for startup to enter RUN mode after the power supply is turned ON, depending on the type and configuration of the Unit and its settings.

During startup, the outputs for NX Units on the CPU Rack will be OFF. Note that the outputs on the slaves will behave according to the setting values.

Therefore, use the system-defined variables and the device variables for each Unit in the user program to confirm that startup processing and I/O data communications are established before attempting control operations.

External communications are also not performed during startup.

# **Operation Until Operation Ready Status**

Once the Unit power supply to the Unit power supply terminal starts, approximately 20 seconds elapses before the CPU Unit enters the operation-ready status. This period is called the *startup* status.

The *startup* time depends on the slave/NX Unit configuration\*1, user program, SD Memory Card usage, SD Memory Card self-diagnosis usage\*2, etc.

While the CPU Unit is in the startup status, the RUN indicator flashes at a one second interval.

- \*1. Some EtherCAT slaves can set a maximum standby time of 1 to 200 seconds. For the CPU Unit, however, the operation-ready status exists as soon as the EtherCAT Master Function Module is functioning, regardless of the standby time of the EtherCAT slaves. For the EtherCAT Master Function Module, slaves that do not start within the maximum waiting time are treated as having an error.
- \*2. This function performs self-diagnosis on the inserted SD Memory Card. This is executed if the self-diagnosis at startup is enabled in the **Operation Settings** under **Configurations and Setup Controller Setup** in the Sysmac Studio.

The following processing is performed during the *startup* status of the CPU Unit.

Process	Description
Self diagnosis at startup	Operation is monitored for the following errors: Power Supply Er-
	ror, CPU Unit Error, Hardware Initialization Error, and System Ini-
	tialization Error. *1

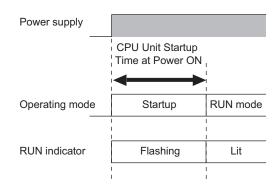
Process	Description
Data check	The _RetainFail (Retention Failure Flag) system-defined variable changes to TRUE when the values of variables for which the Retain attribute was set to retain the values were not retained after a power interruption.
Recording Power Turned ON and Power Interrupted events	The Power Turned ON and Power Interrupted events are recorded.

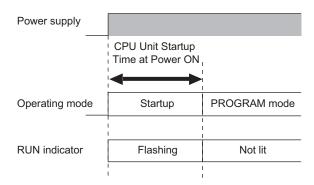
<sup>\*1.</sup> Refer to the *NJ/NX-series Troubleshooting Manual (Cat. No. W503)* for information on the Power Supply Error, CPU Unit Error, Hardware Initialization Error, and System Initialization Error.

# **Operating Mode at Startup**

The system will immediately enter RUN mode if RUN mode (default) is set as the startup operating mode. The system will immediately enter PROGRAM mode if PROGRAM mode is set as the startup operating mode.

- RUN Mode Set as Startup Mode
- PROGRAM Mode Set as Startup Mode





# 5-1-2 Power OFF Operation

# riangle WARNING

The NX-series Controller continues normal operation for a certain period of time when a momentary power interruption occurs. This means that the NX-series Controller may receive incorrect signals from external devices that are also affected by the power interruption.



Accordingly, take suitable actions, such as external fail-safe measures and interlock conditions, to monitor the power supply voltage of the external device as required.

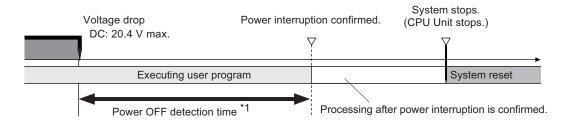
A power OFF status is detected when the Unit power supply drops to the following voltage or lower or when the following time has elapsed due to a momentary power interruption.

Momentary power inter- ruption voltage	Power OFF detection time
20.4 VDC or less	2 ms min.*1 to 8 ms max.

<sup>\*1.</sup> A power OFF status may be detected when a momentary power interruption of 2 ms or less occurs consecutively.

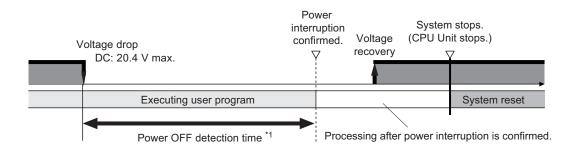
# **Operation at Power OFF**

Execution of the user program is ended if a power interruption exceeds the time shown in the table below. The processing after power interruption confirmation (described below) is performed, and then the system (i.e., CPU Unit) stops.



<sup>\*1.</sup> The power OFF detection time is 2 to 8 ms.

As shown in the following figure, the system (i.e. CPU Unit) will stop even if the voltage recovers after the power interruption detection time.



\*1. The power OFF detection time is 2 to 8 ms.

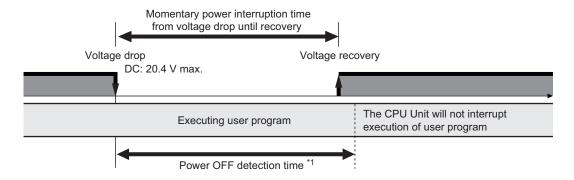
After stopping, the system will restart if the power supply remains recovery.

The table below defines the time that is used in the above two figures.

Item	Description	
Power OFF de-	The time from when the power supply voltage drops until the CPU Unit starts processing af-	
tection time	ter the power interruption is confirmed. The CPU Unit continues to operate normally until the	
	power interruption is confirmed.	

# **Momentary Power Interruption with Continued Operation**

Execution of the user program will continue if a momentary power interruption is less than the following times.



<sup>\*1.</sup> The power OFF detection time is 2 to 8 ms.

# **Processing after Power Interruption Is Confirmed**

After a power interruption is confirmed, the CPU Unit performs the following processing and then stops.

	Item	Description
I/O refresh		I/O refresh stops, and all outputs are turned OFF. Tag data links via the EtherNet/IP stop.
Processing	SD Memory Card access in progress	Any writing is interrupted, files are closed, and the Card is unmounted.
	Transferring user program (including online editing)	Interrupted. As a result, an error will occur the next time that the power is turned ON. The Controller will not operate.
	User program execution	User program execution is aborted even during execution of an instruction.
Saving event log		The time that a power interruption occurs and the cause (primary power interruption) of the interruption are recorded.

# 5-1-3 Resetting the Controller from the Sysmac Studio

You can reset the CPU Unit from the Sysmac Studio.

A reset from the Sysmac Studio follows the same operation as cycling the power supply of the Unit power.

Resetting is possible, however, only when the CPU Unit is in PROGRAM mode.

Confirm the following status before the CPU Unit Reset.

- · Check the status of output loads.
- · Make sure that SD Memory Card access is not in progress.

# 5-2 Fail-safe Circuits

# 

Provide safety measures in external circuits to ensure safety in the system if an abnormality occurs due to malfunction of the CPU Unit, slaves, or Units or due to other external factors affecting operation. Not doing so may result in serious accidents due to incorrect operation.

- Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.
- The Controller outputs may remain ON or OFF due to deposition or burning of the output relays or destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safe operation of the system.



# 

The CPU Unit will turn OFF digital outputs on the CPU Rack in the following cases.

- While the CPU Unit is on standby until RUN mode is entered after the power is turned ON
- · If an error occurs in the power supply
- · If a system initialization error occurs

Digital outputs on the CPU Rack will produce outputs according to the settings in the following cases.



- · If a CPU Unit error or CPU Unit reset occurs
- · If a major fault level Controller error occurs

External safety measures must be provided to ensure safe operation of the system in such cases.

# **⚠ WARNING**

- If there is interference in remote I/O communications or if a major fault level error occurs, output status will depend on the products that are used.
   Confirm the operation that will occur when there is interference in communications or a major fault level error, and implement safety measures.
   Correctly set all of the settings in the slaves and Units.
- If external power supplies for Units, slaves or other devices are overloaded or short-circuited, the voltage will drop, outputs will turn OFF, and the system may be unable to read inputs. Provide external safety measures in controls with monitoring of external power supply voltage as required so that the system operates safely in such a case.
- Unintended outputs may occur when an error occurs in variable memory. As a countermeasure for such problems, external safety measures must be provided to ensure safe operation of the system.
- Provide measures in the communications system and user program to ensure safety in the overall system even if errors or malfunctions occur in data link communications or remote I/O communications.
- You must take fail-safe measures to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.
  - Not doing so may result in serious accidents due to incorrect operation.



# Order of Powering On and Off the Controller and Controlled System

Outputs from Units, such as DC Output Units, may malfunction momentarily when the Unit power supply is turned ON. This may cause problems in the system if the Unit power supply is turned ON after the I/O power supply (i.e. controlled system's power supply) is turned ON. To prevent possible malfunctions, configure an external circuit that prevents the power supply to the controlled system from turning ON before the power supply to the Controller itself.

Also, the external circuit must be configured so that the Unit power supply turns OFF only after the power supply to the controlled system has turned OFF.



### **Precautions for Safe Use**

It takes a certain time for startup to enter RUN mode after the power supply is turned ON, depending on the type and configuration of the Unit and its settings.

During startup, the outputs for NX Units on the CPU Rack will be OFF. Note that the outputs on the slaves will behave according to the setting values.

Therefore, use the system-defined variables and the device variables for each Unit in the user program to confirm that startup processing and I/O data communications are established before attempting control operations.

External communications are also not performed during startup.

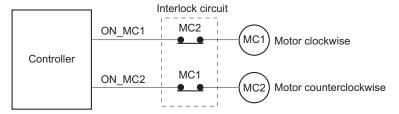
# Failure of the Output Section of the Output Unit

It is possible for an output to remain ON due to a malfunction in the internal circuit of the Output Unit, such as a relay or transistor in the output section. Be sure to add any circuits necessary outside of the Controller to ensure the safety of the system in the event that an output section fails to go OFF.

# **Interlock Circuits**

When the Controller controls an operation such as the clockwise and counterclockwise operation of a motor, provide an external interlock such as the one shown in the following example to prevent both the forward and reverse outputs from turning ON at the same time if required by the application.

### Example:



This circuit prevents outputs MC1 and MC2 from both being ON at the same time even if both Controller outputs ON\_MC1 and ON\_MC2 are ON due to a malfunction.

# 5-3 Mounting and Removing Units

This section describes how to mount and remove NX-series Units.



### **Precautions for Safe Use**

Always turn OFF the power supply to the Controller before you attempt any of the following.

- · Mounting or removing the Units
- · Assembling the Units
- · Setting DIP switches or rotary switches
- · Connecting cables or wiring the system
- · Connecting or disconnecting the terminal blocks or connectors

The power supply circuit in the CPU Unit may continue to supply power to the Controller for a few seconds after the power supply turns OFF. The POWER indicator is lit during this time. Confirm that the POWER indicator is not lit before you perform any of the above.



#### **Precautions for Correct Use**

- Follow the instructions in this manual to correctly perform installation.
- Do not operate or store the Controller in the following locations. Doing so may result in burning, in operation stopping, or in malfunction.
  - a) Locations subject to direct sunlight
  - b) Locations subject to temperatures or humidity outside the range specified in the specifications
  - c) Locations subject to condensation as the result of severe changes in temperature
  - d) Locations subject to corrosive or flammable gases
  - e) Locations subject to dust (especially iron dust) or salts
  - f) Locations subject to exposure to water, oil, or chemicals
  - g) Locations subject to shock or vibration
- Take appropriate and sufficient countermeasures when installing the Controller in the following locations.
  - a) Locations subject to strong, high-frequency noise
  - b) Locations subject to static electricity or other forms of noise
  - c) Locations subject to strong electromagnetic fields
  - d) Locations subject to possible exposure to radioactivity
  - e) Locations close to power lines

### 5-3-1 Installation in a Control Panel

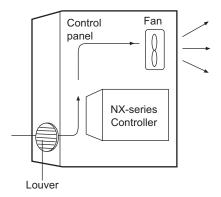
## **Installation in Cabinets or Control Panels**

When the NX-series Controller is being installed in a cabinet or control panel, be sure to provide proper ambient conditions as well as access for operation and maintenance.

### • Temperature Control

The ambient operating temperature of the NX-series Controller must be within the range of 0 to 55°C. When necessary, take the following steps to maintain the proper temperature.

- Provide enough space for good air flow.
- Do not install the Controller above equipment that generates a large amount of heat such as heaters, transformers, or high-capacity resistors.
- If the ambient temperature exceeds 55°C, install a cooling fan or air conditioner.

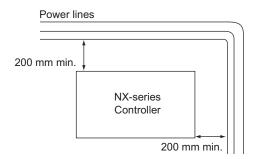


## Accessibility for Operation and Maintenance

- To ensure safe access for operation and maintenance, separate the Controller as much as possible from high-voltage equipment and power machinery.
- It will be easy to operate the Controller if it is mounted at a height of 1.0 to 1.6 m above the floor.

### Improving Noise Resistance

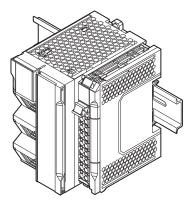
- Do not mount the Controller in a control panel containing high-voltage equipment.
- Install the Controller at least 200 mm away from power lines.



• Ground the mounting plate between the Controller and the mounting surface.

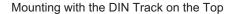
### Controller Orientation

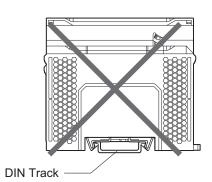
• Each Rack must be mounted in the following position to provide proper cooling. This position is called an upright position.

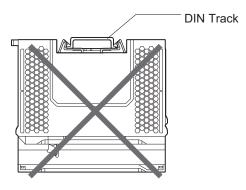


• Do not install a Rack in any of the following positions.

Mounting with the DIN Track on the Bottom

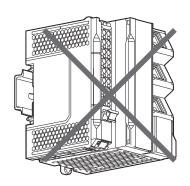


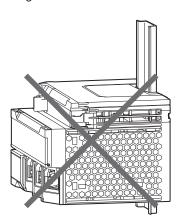




Mounting with the Rack Upside Down

Mounting with the DIN Track Installed Vertically





# **Installation Method in Control Panels**

An NX-series Controller must be mounted inside a control panel on DIN Track.

• Consider the width of wiring ducts, wiring, ventilation, and Unit replacement when determining the space between the CPU Rack and other devices.



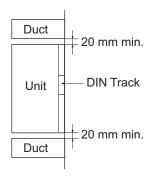
### **Additional Information**

A Controller must be mounted on DIN Track. It cannot be mounted with screws.

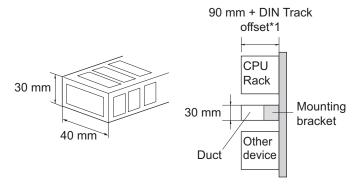
### Wiring Ducts

Whenever possible, route I/O wiring through wiring ducts.

Install mounting bracket so that it is easy to fish wire through the duct. It is handy to have the duct at the same height as the CPU Rack.



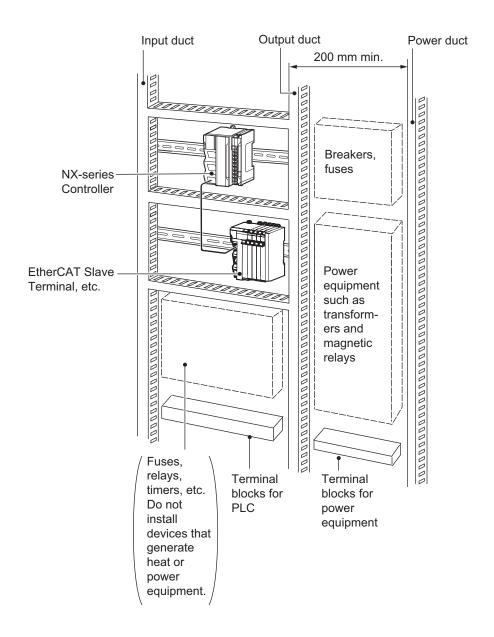
# Wiring Duct Example



\*1. It varies depending on the DIN Track to be used. Refer to *Installation Dimensions* on page 5-31 under 5-3-12 Assembled Appearance and Dimensions on page 5-31 for details. It corresponds to the dimension (B).

### Routing Wiring Ducts

Install the wiring ducts at least 20 mm away from the tops of the Rack and any other objects (e.g., ceiling, wiring ducts, structural supports, devices, etc.) to provide enough space for air circulation and replacement of Units.



# 5-3-2 Preparations for Installation

We recommend using the following products to install the Unit on a DIN Track.

Name	Model	Manufacturer	Remarks
35-mm DIN Track	PFP-50N	OMRON Corporation	Length: 50 cm
			Material: Aluminum
			Surface treatment: Insulated
	PFP-100N	OMRON Corporation	Length: 100 cm
			Material: Aluminum
			Surface treatment: Insulated
	NS 35/ 7,5 PERF	Phoenix Contact	• Length: 75.5, 95.5, 115.5, or 200 cm
			Material: Steel
			Surface treatment: Conductive
	NS 35/ 15 PERF	Phoenix Contact	• Length: 75.5, 95.5, 115.5, or 200 cm
			Material: Steel
			Surface treatment: Conductive

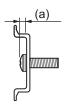
Name	Model	Manufacturer	Remarks
End Plate	PFP-M	OMRON Corporation	Two End Plates are required for each CPU Rack.
	CLIPFIX 35	Phoenix Contact	Two End Plates are required for each CPU Rack.

Not all of the combinations of the DIN Tracks and End Plates listed above are possible. Confirm applicability of the combinations in the following table.

DIN Track model	PFP-M (OMRON)	CLIPFIX 35 (Phoenix Contact)
PFP-50N	Possible	Possible
PFP-100N	Possible	Possible
NS 35/ 7,5 PERF	Possible	Possible
NS 35/ 15 PERF	Not possible	Possible

Also, use screws and washers of the following sizes to fix the DIN Tracks.

(a): Dimensions from the screw head to the fastening surface

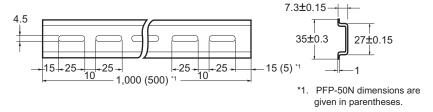


DIN Track model	Applicable screw size	(a)
PFP-50N	M4	4.1 mm max.
NS 35/ 7,5 PERF	M6	4.6 mm max.
NS 35/ 15 PERF	M6	10 mm max.

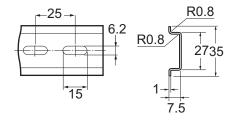
If you use any DIN Track other than those listed in the table above, refer to the dimensions shown in 5-3-12 Assembled Appearance and Dimensions on page 5-31 and use proper screws and washers.

### DIN Tracks

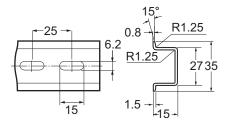
PFP-100N/50N DIN Track



NS 35/7,5 PERF

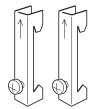


NS 35/ 15 PERF

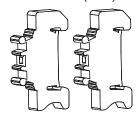


# End Plate





CLIPFIX 35 (Two)



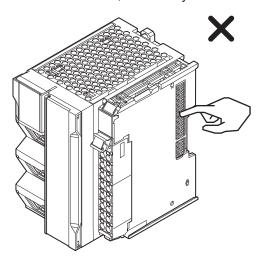
# 5-3-3 Installing the CPU Unit

This section describes how to install the CPU Unit.



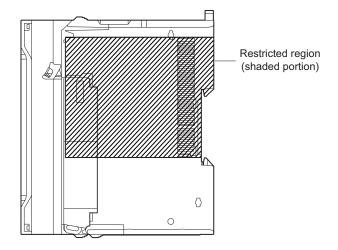
### **Precautions for Safe Use**

- Do not apply labels or tape to the Unit. When the Unit is installed or removed, adhesive or scraps may adhere to the pins in the NX bus connector, which may result in malfunctions.
- Do not touch the pins in the NX bus connector on the Unit. Dirt may adhere to the pins in the NX bus connector, which may result in malfunctions.



Do not write anything with ink within the restricted region of the CPU Unit that is shown in the
following figure. Also do not get this area dirty. When the Unit is installed or removed, ink or
dirt may adhere to the pins in the NX bus connector, which may result in malfunctions in the
Unit.

Refer to the user's manual for the connected NX Unit for information on the restricted region for the NX Unit.





### **Precautions for Correct Use**

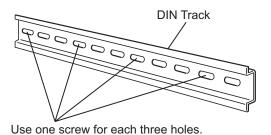
- When you install the Unit, be careful not to touch or bump the pins in the NX bus connector.
- When you handle the Unit, be careful not to apply stress to the pins in the NX bus connector.
   If the Unit is installed and the power supply is turned ON when the pins in the connector are deformed, contact failure may cause malfunctions.



Install the DIN Track.

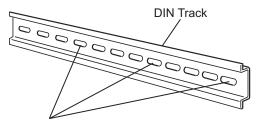
• Using a PFP-50N/100N DIN Track

Use one M4 screw for each three holes in the DIN Track. There must be a screw for each interval of 105 mm or less. The screw tightening torque is 1.2 N·m.



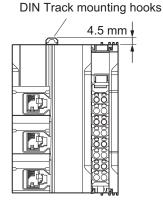
• Using an NS 35/7,5 PERF or NS 35/15 PERF DIN Track

Use one M6 screw for each four holes in the DIN Track. There must be a screw for each interval of 100 mm or less. The screw tightening torque is 5.2 N·m.

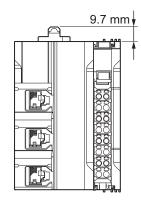


Use one screw for each four holes.

**2** Make sure that the DIN Track mounting hook on the CPU Unit is in the unlock position.



DIN Track Mounting Hooks in Locked Position



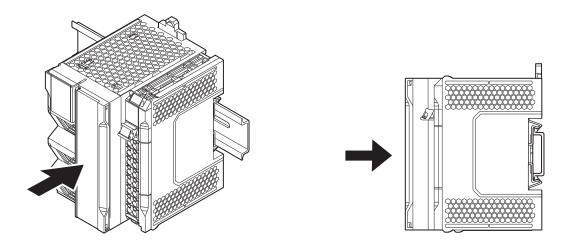
DIN Track Mounting Hooks in Unlocked Position

If the DIN Track mounting hooks are pulled up, they are in the unlocked position.

If the DIN Track mounting hooks are pressed down, they are in the locked position.

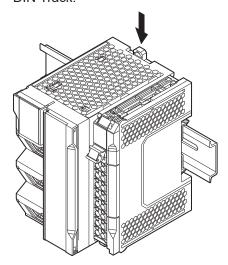
Use a flat-blade screwdriver to pull up the DIN Track mounting hook on the Unit to release the locked position.

**3** Press the CPU Unit straight against the DIN Track.



4 Press the DIN Track mounting hooks down to the locked position.

After mounting, make sure that the CPU Unit and the End Cover are securely mounted on the DIN Track.



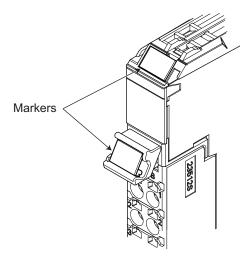
### 5-3-4 Attaching Markers

Markers can be attached to NX Units and their terminal blocks to identify them.

The plastic markers made by OMRON are installed for the factory setting. The ID information can be written on them.

Commercially available markers can also be installed.

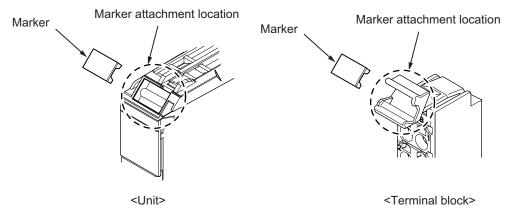
Replace the markers made by OMRON if you use commercially available markers now.



The marker attachment locations on the NX Units depend on the type of external connection terminals. Refer to the user's manual for the NX Units that you will use for the marker attachment locations.

#### Installation Method

Insert the protrusions on the markers into the marker attachment locations on the NX Units and terminal blocks on NX Units.



### Commercially Available Markers

Commercially available markers are made of plastic and can be printed on with a special printer. To use commercially available markers, purchase the following products.

Product name	Model number				
Product name	Manufactured by Phoenix Contact	Manufactured by Weidmuller			
Markers	UC1-TMF8	DEK 5/8			
Special marker printer	UM EN BLUEMARK X1	PrintJet PRO			

The markers made by OMRON cannot be printed on with commercially available special printers.

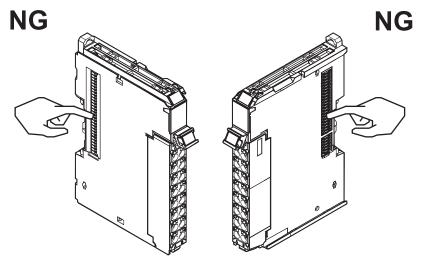
### 5-3-5 Installing and Connecting NX Units

This section describes how to mount NX Units to the CPU Unit and how to connect NX Units to each other.



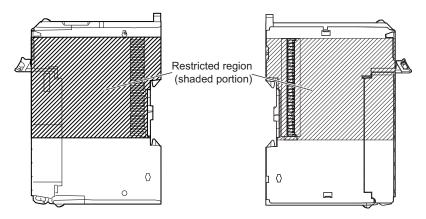
#### **Precautions for Safe Use**

- Always turn OFF the power supply before mounting the Units. If the power supply is not OFF, the Unit may result in malfunction or may be damaged.
- Do not apply labels or tape to the Unit. When the Unit is installed or removed, adhesive or scraps may adhere to the pins in the NX bus connector, which may result in malfunctions.
- Do not touch the pins in the NX bus connector on the Unit. Dirt may adhere to the pins in the NX bus connector, which may result in malfunctions.



Example: NX Unit (12 mm width)

 Do not write on an NX Unit with ink within the restricted region that is shown in the following figure. Also do not get this area dirty. When the Unit is installed or removed, ink or dirt may adhere to the pins in the NX bus connector, which may result in malfunctions in the CPU Rack.





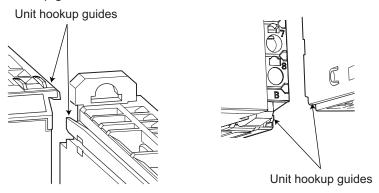
#### **Precautions for Correct Use**

- When you mount an NX Unit to the CPU Unit or when you connect NX Units to each other, always mount the Units one at a time on the DIN Track.
   If you connect NX Units to each other and attempt to mount them together to the DIN Track at the same time, the Units may separate from each other and fall.
- When you handle a Unit, be careful not to apply stress to the pins in the NX bus connector. If the Unit is installed and the power supply is turned ON when the pins in the NX bus connector are deformed, contact failure may cause malfunctions.
- · When you handle a Unit, be careful not to touch or bump the pins in the NX bus connector.

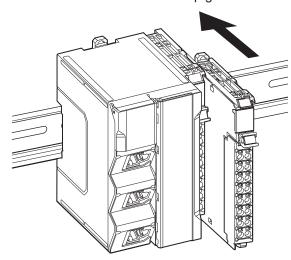
### Mounting NX Unit to CPU Unit

Mount the NX Unit to the CPU Unit after removing the End Cover.

1 From the front of the CPU Unit, engage the Unit hookup guides on the NX Unit with the Unit hookup guides on the Communication Control Unit.



2 Slide the NX Unit on the hookup guides.



**3** Press the NX Unit with a certain amount of force against the DIN Track until you hear the DIN Track mounting hook lock into place.

When you mount the NX Unit, it is not necessary to release the DIN Track mounting hook on the NX Unit. After you mount the NX Unit, make sure that it is locked to the DIN Track.



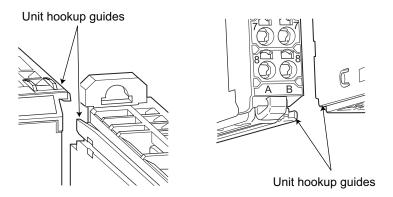
#### **Additional Information**

It is not normally necessary to unlock the DIN Track mounting hook when you mount the NX Unit. However, if you mount the NX Unit on a DIN Track that is not one of the recommended DIN Tracks, the DIN Track mounting hook may not lock properly. If that happens, unlock the DIN Track mounting hook at the start of the procedure, mount the NX Unit to the DIN Track, and then lock the DIN Track mounting hook.

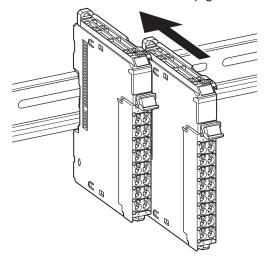
#### Mounting NX Units to Each Other

Use the following procedure to mount NX Units to each other.

1 From the front of the previously mounted NX Unit, engage the Unit hookup guides on a new Unit with the Unit hookup guides on the previously mounted NX Unit.



2 Slide the NX Unit on the hookup guides.



**3** Press the NX Unit with a certain amount of force against the DIN Track until you hear the DIN Track mounting hook lock into place.

When you mount the NX Unit, it is not necessary to release the DIN Track mounting hook on the NX Unit.

After you mount the NX Unit, make sure that it is locked to the DIN Track.



#### **Additional Information**

It is not normally necessary to unlock the DIN Track mounting hook when you mount the NX Unit. However, if you mount the NX Unit on a DIN Track that is not one of the recommended DIN Tracks, the DIN Track mounting hook may not lock properly. If that happens, unlock the DIN Track mounting hook at the start of the procedure, mount the NX Unit to the DIN Track, and then lock the DIN Track mounting hook.

### 5-3-6 Mounting the End Cover

Always mount the End Cover (NX-END02) provided with the product to the end of the CPU Rack.



#### **Precautions for Safe Use**

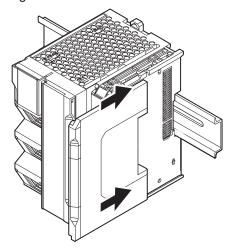
The End Cover has a metal portion and is heavier than it looks. Be careful not to drop it when handling.



#### **Precautions for Correct Use**

Always mount an End Cover to the end of the CPU Rack to protect the last Unit on the CPU Rack. Not mounting the End Cover may result in malfunction or failure of the CPU Unit.

**1** From the front of the rightmost Unit, slide the End Cover along the Unit hookup guides on the rightmost Unit on the CPU Rack.



**2** Press the End Cover firmly against the DIN Track until you hear it lock into place on the DIN Track.

After you mount the End Cover, make sure that it is securely mounted on the DIN Track.

### 5-3-7 Mounting the End Plates

After you mount the End Cover, always secure the Unit with End Plates at both sides.



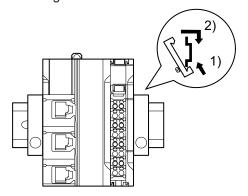
#### **Precautions for Correct Use**

After you mount the Unit on the DIN Track, always secure it with End Plates at both sides. If you do not secure it, the Unit may be damaged or malfunction.

### Using PFP-M (OMRON)

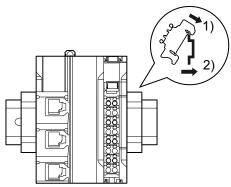
To mount an End Plate, 1) hook the bottom of it on the bottom of the DIN Track and 2) rotate the End Plate to hook the top of it on the top of the DIN Track.

Then tighten the screw to lock the End Plate in place.

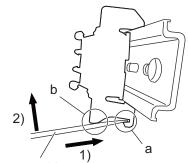


#### Using CLIPFIX 35 (Phoenix Contact)

To mount an End Plate, 1) hook the top of it on the top of the DIN Track and 2) rotate the Plate to hook the bottom of it on the bottom of the DIN Track. Press in until you hear the End Plate lock into place.



To remove an End Plate 1) insert the tip of a flat-blade screwdriver into groove "a" and 2) use "b" as a fulcrum and lift the end of the screwdriver, as shown in the following diagram.



Flat-blade screwdriver

### 5-3-8 Installing and Removing the SD Memory Card

### **Before Using an SD Memory Card**

- · Keep the following precautions because an SD Memory Card may become unusable.
  - a) Do not turn OFF the power supply to the Controller while the SD BUSY indicator is lit (i.e., while SD Memory Card access is in progress).
    - The SD BUSY indicator is lit when the SD Memory Card is accessed from the user program or from a computer through FTP.
  - b) Do not remove the SD Memory Card while the SD BUSY indicator is lit or the SD PWR indicator is lit (i.e., while SD Memory Card power is supplied).
    - Press the SD Memory Card power supply switch and confirm that the SD BUSY indicator or SD PWR indicator is not lit before you remove the SD Memory Card.
- Never insert the SD Memory Card facing the wrong way.
   If the SD Memory Card is inserted forcibly, it may become unusable.
- To format the SD Memory Card (e.g., to delete all of the data), insert the SD Memory Card in the CPU Unit and perform the operation from the Sysmac Studio.
- The SD Memory Card uses flash memory, and so its service life is limited. When the end of the SD
  Memory Card's service life approaches, the ability to write data is lost, and data is sometimes not
  retained after writing. The service life depends on the size of the data that is written and on the

ambient temperature. For the unlikely event that data is lost, it is recommended to periodically back up data.

- The service life may be extremely short if a non-OMRON SD Memory Card is used. Also, operation may be affected due to deterioration in writing performance.
- If you use an OMRON SD Memory Card, the end of the life of the SD Memory Card can be detected in the following ways.
  - a) \_Card1Deteriorated (SD Memory Card Life Warning Flag) system-defined variable
  - b) SD Memory Card Life Exceeded event in the event log

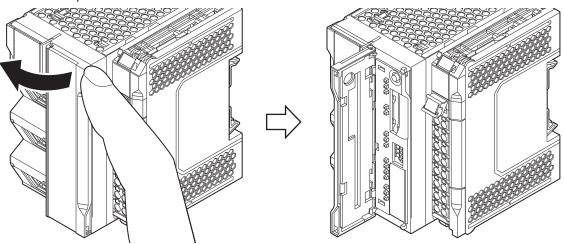


#### **Version Information**

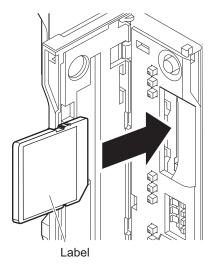
Combination of the CPU Unit version and SD Memory Card determines whether the SD memory card life expiration detection function can be used or not. Refer to *Specification of Supported SD Memory Cards, Folders, and Files* in the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for details.

### **Installing the SD Memory Card**

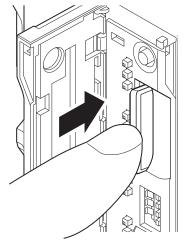
**1** Place your finger on the upper side panel of the memory card cover located in the middle of CPU Unit and open it to the left.



2 Insert the SD Memory Card with the label facing to the right.



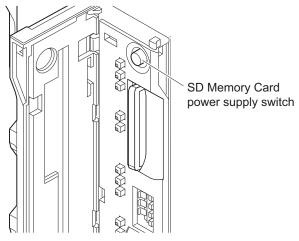
**3** Push the SD Memory Card securely into the compartment.



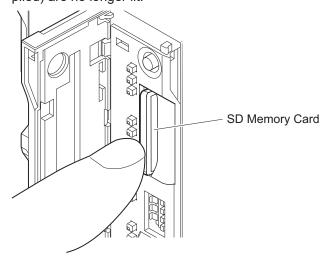
**4** Close the Memory Card cover.

### **Removing the SD Memory Card**

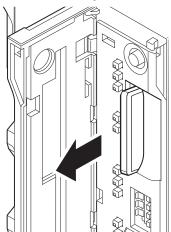
**1** Press the SD Memory Card power supply switch.



**2** Press the SD Memory Card after you confirm that the SD BUSY indicator (lit while SD Memory Card access is in progress) and SD PWR indicator (lit while SD Memory Card power is supplied) are no longer lit.



The SD Memory Card will be ejected from the compartment.



- **3** Pull out the SD Memory Card.
- **4** Close the Memory Card cover.

### 5-3-9 Battery Installation

### **Battery to Use**

Use the Battery CJ1W-BAT01 which is sold separately.



#### **Precautions for Correct Use**

Be sure to install a Battery within two years of the production date shown on the Battery label. Production Date



Manufactured in March 2018.

### **Battery Installation Procedure**

Use the following procedure to install the Battery.



#### **Precautions for Safe Use**

We recommend mounting or replacing the Battery with the power turned OFF to prevent the CPU Unit's sensitive internal components from being damaged by static electricity and to prevent malfunctions. The Battery can be mounted or replaced without turning OFF the power supply. To do so, always touch a grounded piece of metal to discharge static electricity from your body before you start the procedure.

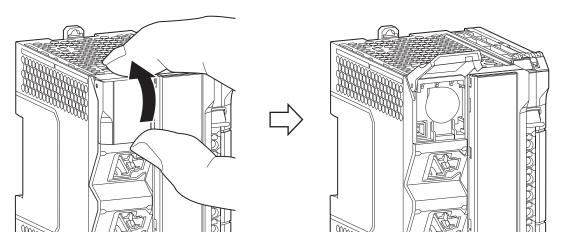
If the Low Battery Voltage error occurs after you mount the Battery, connect the Sysmac Studio and clear the error.



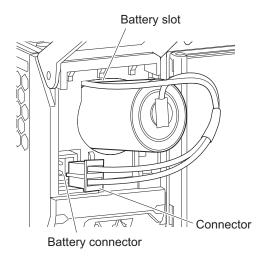
#### **Additional Information**

UL standards require that batteries be replaced by experienced technicians. Always place an experienced technician in charge of battery replacement.

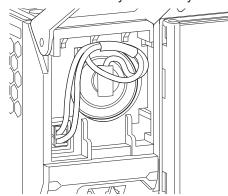
- Turn OFF the power supply to the Controller.
  If the CPU Unit has not been ON, turn it ON for at least five minutes and then turn it OFF.
- **2** Put your fingers on the bottom edges of the battery cover on the upper left corner of the CPU Unit and open the cover upward.



3 Connect the connector of the battery to the battery connector and insert the battery in the battery slot.



**4** Press in the battery harness by twisting and attach the battery cover.



**5** Set the **Battery-related error detection** to **Use** and adjust the CPU Unit's clock data to the current time.

Refer to the Sysmac Studio Version 1 Operation Manual (Cat. No. W504) for how to make the setting.



#### **Precautions for Safe Use**

- The Battery may leak, rupture, heat, or ignite. Never short-circuit, charge, disassemble, heat, or incinerate the Battery or subject it to strong shock.
- Dispose of any Battery that has been dropped on the floor or otherwise subjected to excessive shock. Batteries that have been subjected to shock may leak if they are used.

### 5-3-10 Removing CPU Unit

This section describes how to remove the CPU Unit.

If an NX Unit is mounted, remove the CPU Unit after removing the NX Unit next to the CPU Unit. Refer to 5-3-11 Removing NX Units on page 5-29 for details on how to remove the NX Units.

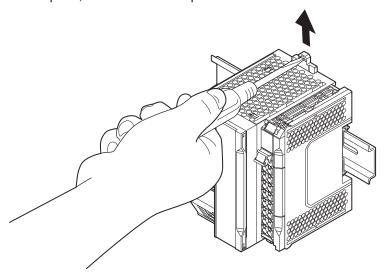


#### **Precautions for Correct Use**

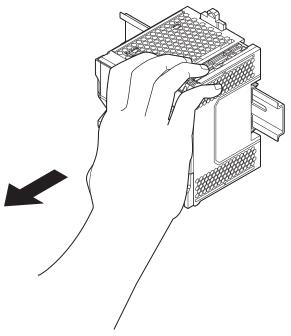
When you remove a Unit, be careful not to touch or bump the pins in the NX bus connector.

Unlock the DIN Track mounting hook.Use a flat-blade screwdriver to pull up the DIN Track mounting hook to unlocked position.

At this point, be sure not to drop the CPU Unit.



Remove the CPU Unit from the DIN Track.
Pull the Unit straight forward to remove. Be careful not to drop it.



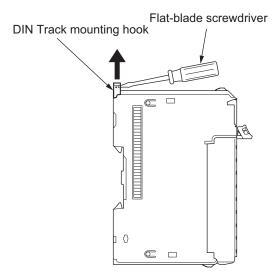
### 5-3-11 Removing NX Units



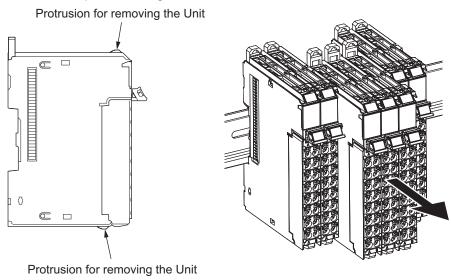
#### **Precautions for Safe Use**

Always turn OFF the Unit power supply and I/O power supply before you remove the NX Unit.

**1** Use a flat-blade screwdriver to pull up the DIN Track mounting hook on the Unit to remove.



Put your fingers on the protrusions for removing multiple NX Units including the Unit to be removed, then pull out straight forward to remove.



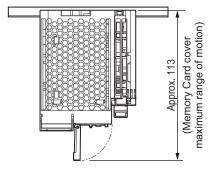


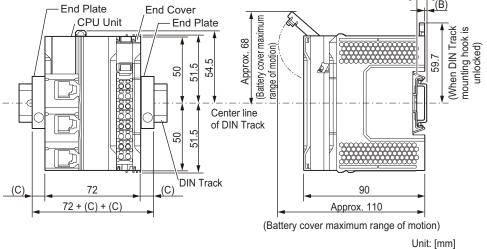
#### **Precautions for Correct Use**

- When removing an NX Unit, remove multiple Units together which include the one you want to remove. If you attempt to remove only one Unit, it is stuck and hard to pull out.
- Do not unlock the DIN Track mounting hooks on all of the NX Units at the same time. If you unlock the DIN Track mounting hooks on all of the NX Units at the same time, all of the Units may come off.
- When you remove a Unit, be careful not to touch or bump the pins in the NX bus connector.

### 5-3-12 Assembled Appearance and Dimensions

### **Installation Dimensions**





W: Width of CPU Unit (including the End Cover)

• Unit width

Model	Unit width [mm]
NX102-□□□□	72

· DIN Track dimension

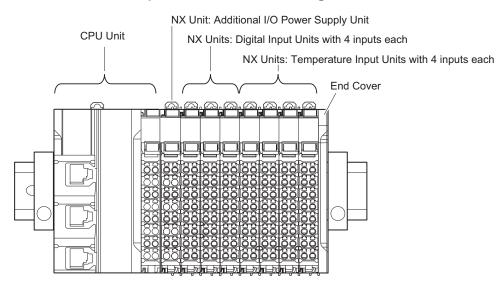
DIN Track model	(A) DIN Track dimension	(B) Dimension from the back of the Unit to the back of the DIN Track
PFP-100N	7.3 mm	1.5 mm
PFP-50N	7.3 mm	1.5 mm
NS 35/7,5 PERF	7.5 mm	1.7 mm
NS 35/15 PERF	15 mm	9.2 mm

· End Plate dimension

End Plate model	(C) End Plate dimension		
PFP-M	10 mm		

End Plate model	(C) End Plate dimension
CLIPFIX 35	9.5 mm

### • Calculation Example of CPU Rack Configuration Width



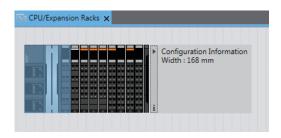
The widths of the Units in the example CPU Rack configuration and the total configuration width are given below.

Unit name	Model	Unit width	Qty	Subtotal unit width	
CPU Unit	NX102-1200	72 mm	1	72 mm	
Additional I/O Power Supply Unit	NX-PF0630	12 mm	1	12 mm	
NX Units: Digital Input Units	NX-ID3317	12 mm	3	36 mm	
NX Units: Temperature Input Units	NX-TS3101	24 mm	2	48 mm	
Total (W=)			•	168 mm	



#### **Additional Information**

You can check the width of the CPU Rack when you create the Unit configuration on the CPU and Expansion Racks Tab Page on the Sysmac Studio. On the CPU and Expansion Racks Tab Page on the Sysmac Studio, click on the right end of the CPU Rack to display the width.



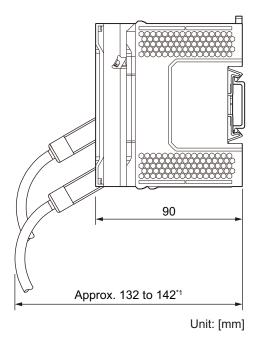
### **Installation Height**

The installation height of the CPU Rack depends on the model of DIN Track and on the models of NX Units that are mounted.

Also, additional space is required for the cables that are connected to the Unit. Allow sufficient depth in the control panel and allow extra space when you mount the CPU Rack.

The following figure shows the dimensions from the cables connected to the CPU Rack to the back of the Unit. The unit of dimension is millimeter.

The height from the mounting surface of the DIN Track varies depending on the DIN Track to be used. Refer to *Installation Dimensions* on page 5-31 for the height of individual DIN Track type.



\*1. This is the dimension from the back of the Unit to the communications cables. Approx. 132 mm: When MPS588-C connector is used

Approx. 142 mm: When XS6G-T421-1 connector is used



#### **Precautions for Safe Use**

Do not pull on the cables or bend the cables beyond their natural limit. Doing so may break the cables.

# 5-4 Wiring

# riangle WARNING

Make sure that the voltages and currents that are input to the slaves and Units are
within the specified ranges.



Inputting voltages or currents that are outside of the specified ranges may cause accidents or fire.

# **A** CAUTION

- Be sure that all terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. Loose screws may result in fire or malfunction.
- Do not touch any Unit when power is being supplied or immediately after the power supply is turned OFF. Doing so may result in burn injury.





#### **Precautions for Safe Use**

Use the methods that are specified in this manual for wiring the terminal blocks.

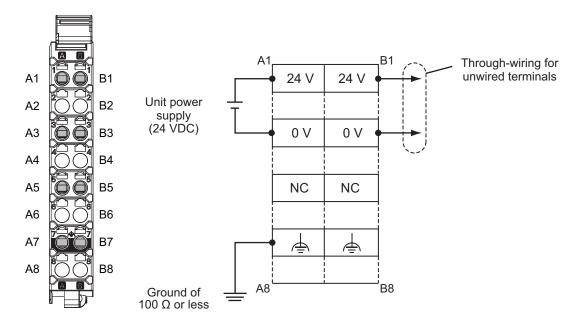


#### **Precautions for Correct Use**

Do not allow wire clippings, shavings, or other foreign material to enter any Unit. Otherwise, Unit burning, failure, or malfunction may occur. Cover the Units or take other suitable countermeasures, especially during wiring work.

### 5-4-1 Wiring the Unit Power Supply

This section describes the wiring of the Unit power supply to the Unit power supply terminals on the CPU Unit.



Connect the DC power supply to the Unit power supply terminals.

Terminal number indi- cation	Terminal name	Description
A1, B1	24 V	Connect the + terminal (24 VDC) of the Unit power supply to A1 or B1.
A3, B3	0 V	Connect the - terminal (0 VDC) of the Unit power supply to A3 or B3.

The 24-V terminals and 0-V terminals are internally connected to each other.

You can use the unwired terminals for through-wiring to an Additional NX Unit Power Supply Unit or to the Unit power supply terminals on another NX102 CPU Unit.

When you supply the Unit power through the unwired terminals, be careful not to exceed 4 A, the current capacity of power supply terminals.

### 5-4-2 Wiring the Additional NX Unit Power Supply Unit

For information on wiring the Additional NX Unit Power Supply Unit, refer to the *NX-series System Units User's Manual* (Cat. No. W523-E1-05 or later).

### 5-4-3 Wiring the Additional I/O Power Supply Unit

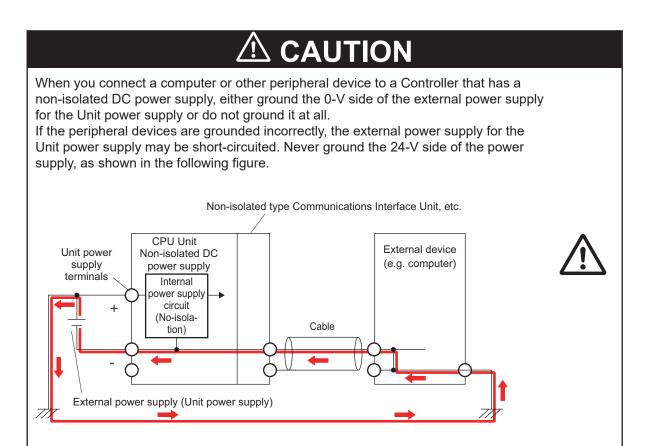
For information on wiring the Additional I/O Power Supply Unit, refer to the *NX-series System Units User's Manual* (Cat. No. W523-E1-05 or later).

### 5-4-4 Wiring the Protective Devices

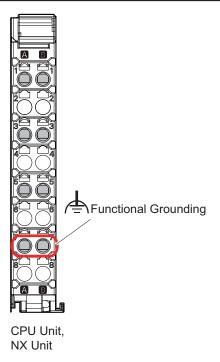
For information on wiring the protective devices to protect against short circuits and overcurrents of external circuits, refer to *4-4-3 Selecting Protective Devices* on page 4-24.

### 5-4-5 Grounding

This section describes how to ground the CPU Rack.



### **Units with Ground Terminals and Type of Ground Terminals**



#### Units with Ground Terminals

- CPU Unit
- · Additional NX Unit Power Supply Unit
- · Shield Connection Unit

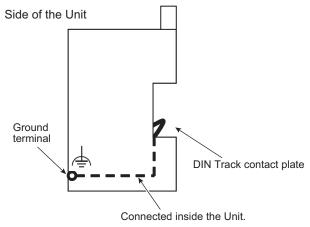
Grounding type	Symbol	Function
A7, B7		Functional grounding is done to protect device and system functions, including prevention of noise from external sources, or prevention of noise from devices or equipment that could have harmful effects on other devices or equipment.

### **DIN Track Contact Plates**

A Unit that has a ground terminal also has a DIN Track contact plate on the back of the Unit.

The DIN Track contact plate is connected internally to the ground terminal on the Unit.

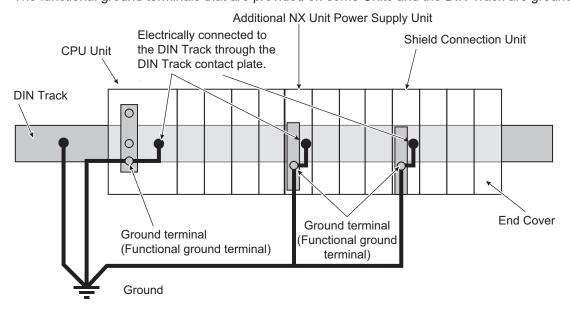
This means that the ground terminal will be electrically connected to the DIN Track.



### **Grounding the CPU Rack**

This section describes how to ground the ground terminals on the CPU Rack.

The functional ground terminals that are provided on some Units and the DIN Track are grounded.

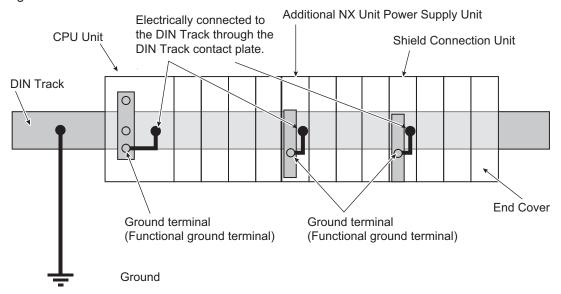


- Using a dedicated ground wire, ground the ground terminals and DIN Track with a ground resistance of 100  $\Omega$  or less.
- The ground wire should not be more than 20 m long.

• Use a ground wire that is 2.0 mm<sup>2</sup> or larger. Refer to 5-4-8 Wiring to the CPU Unit Terminal Block on page 5-40 for information on ground wires that are applicable to the functional ground terminal on the CPU Unit.

For information on ground wires that are applicable to the functional ground terminals on the Additional NX Unit Power Supply Unit or Shield Connection Unit, refer to the *NX-series System Units User's Manual (Cat. No. W523)*.

If the DIN Track is made of steel and the surface is not treated to produce an insulating material, you can omit grounding the functional ground terminal on any Unit that has one, as shown in the following figures.



If the surface of the DIN Track is treated to produce an insulating material (e.g., anodized aluminum), the DIN Track contact plate will not be electrically connected to the DIN Track even if they are in physical contact.

### **Grounding the DIN Track**

Attach a crimped terminal to the ground wire and then connect it to mounting hole on the DIN Track with a screw to ground the DIN Track.

# Grounding the CPU Rack with Peripheral Devices and in Control Panels

Refer to *5-5-6 Grounding* on page 5-62 for the grounding procedures for the CPU Rack with peripheral devices and in control panels.

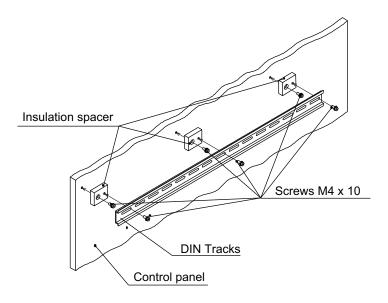
### Isolating the CPU Rack from the Control Panel

If the ground wire for a Unit with a ground terminal is shared with power equipment, noise will adversely affect the Units.

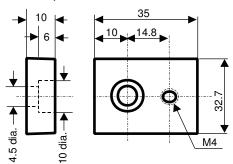
You can use OMRON NX-AUX01 DIN Track Insulation Spacers with PFP-50N or PFP-100N DIN Tracks to isolate the CPU Rack from the control panel.

#### Installing DIN Track Insulation Spacers and DIN Track

Secure the DIN Track Insulation Spacers to the control panel with screws, and then secure the DIN Track to the DIN Track Insulation Spacers. The recommended tightening torque for M4 screws is  $1.2 \text{ N} \cdot \text{m}$ .



 DIN Track Insulation Spacers NX-AUX01 (OMRON Corporation)
 Three Spacers are included in one model.





#### **Precautions for Correct Use**

If you use DIN Track Insulation Spacers to install a CPU Rack, the height will be increased by approximately 10 mm. Make sure that the CPU Rack and connecting cables do not come into contact with other devices.

### 5-4-6 Wiring the Built-in EtherCAT Port

For information on wiring the built-in EtherCAT port, refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual (Cat. No. W505)*.

### 5-4-7 Wiring the Built-in EtherNet/IP Port

For information on wiring the built-in EtherNet/IP port, refer to the *NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual (Cat. No. W506*).

### 5-4-8 Wiring to the CPU Unit Terminal Block

This section describes how to connect wires to the screwless clamping terminal block on the CPU Unit, the installation and removing methods, and functions for preventing incorrect attachment.

You can connect ferrules that are attached to the twisted wires to the screwless clamping terminal block. You can also connect the twisted wires or the solid wires to the screwless clamping terminal block. If you connect the ferrules, all you need to do to connect the wires is to insert the ferrules into the terminal holes.

# riangle WARNING

Make sure that the voltages and currents that are input to the slaves and Units are within the specified ranges.



Inputting voltages or currents that are outside of the specified ranges may cause accidents or fire.



#### **Precautions for Safe Use**

Use the correct wiring parts and tools when you wire the system. Otherwise, cables may be disconnected to cause short-circuit or wire breakage.

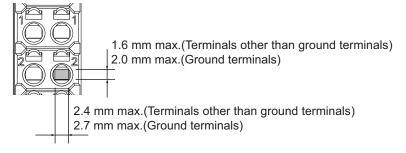
### **Applicable Wires**

The wires that you can connect to the screwless clamping terminal block are twisted wires, solid wires, and ferrules that are attached to the twisted wires. The following section describes the dimensions and processed methods for applicable wires.

### • Dimensions of Wires Connected to the Terminal Block

The dimensions of wires that you can connect into the terminal holes of the screwless clamping terminal block are as in the figure below.

Process the applicable wires that are specified in the following description to apply the dimensions.



### Using Ferrules

If you use ferrules, attach the twisted wires to them.

Observe the application instructions for your ferrules for the wire stripping length when attaching ferrules.

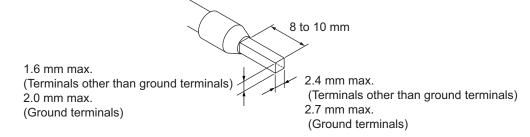
Always use plated one-pin ferrules. Do not use unplated ferrules or two-pin ferrules.

The applicable ferrules, wires, and crimping tools are listed in the following table.

Terminal types	Manufac- turer	Ferrule model*1	Applica- ble wire (mm <sup>2</sup> (AWG))	Crimping tool	
All terminals except	Phoenix	AI0,34-8	0.34 (#22)	Phoenix Contact (Applicable wire size given	
ground terminals	Contact	AI0,5-8	0.5 (#20)	in parentheses)	
		AI0,5-10		CRIMPFOX 6 (0.25 to 6 mm <sup>2</sup> , AWG24 to	
		AI0,75-8	0.75 (#18)	10)	
		AI0,75-10			
		AI1,0-8	1.0 (#18)		
		AI1,0-10			
		AI1,5-8	1.5 (#16)		
		AI1,5-10			
Ground terminals		AI2,5-10	2.0*2		
All terminals except	Weidmul-	H0.14/12	0.14 (#26)	Weidmuller (Applicable wire size given in	
ground terminals	ler	H0.25/12	0.25 (#24)	parentheses)	
		H0.34/12	0.34 (#22)	PZ6 Roto (0.14 to 6 mm <sup>2</sup> , AWG26 to 10)	
		H0.5/14	0.5 (#20)		
		H0.5/16			
		H0.75/14	0.75 (#18)		
		H0.75/16			
		H1.0/14	1.0 (#18)		
		H1.0/16			
		H1.5/14	1.5 (#16)		
	H1.5/16				

<sup>\*1.</sup> This represents a typical model. Actually, colored codes and other information is added.

When you use any ferrules other than those in the above table, crimp them to the twisted wires so that the following processed dimensions are achieved.



### Using Twisted or Solid Wires

If you use twisted wires or solid wires, use the following table to determine the correct wire specifications.

<sup>2.</sup> For the ferrule type Al2,5-10, use wires with a diameter of 2.0 to 2.1 mm<sup>2</sup>. Wires with a diameter exceeding 2.1 mm<sup>2</sup> cannot be used with the screwless clamping terminal block.

Terminals		Wire type					Conductor
Terminais		Twisted wires Solid wire		Wire size	length		
Classification	Current ca- pacity	Plated	Unplat- ed	Plated	Unplat- ed	Wile Size	(stripping length)
All terminals ex-	2 A max.	Possi-	Possible	Possible	Possible	0.08 to 1.5	8 to 10 mm
cept ground ter- minals	Greater than 2 A and 4 A or less	ble	Not pos- sible	Possible *1	Not pos- sible	mm <sup>2</sup> (AWG 28 to 16)	
Ground termi- nals		Possi- ble	Possible	Possible	Possible	2.0 mm <sup>2</sup>	10 to 12 mm

<sup>\*1.</sup> Secure wires to the screwless clamping terminal block. Refer to *Securing Wires* on page 5-45 for how to secure wires.



#### **Precautions for Correct Use**

- Use cables with suitable wire sizes for the carrying current. There are also restrictions on the current due to the ambient temperature. Refer to the manuals for the cables and use the cables correctly for the operating environment.
- For twisted wires, strip the sheath and twist the conductor portion. Do not unravel or bend the conductor portion of twisted wires or solid wires.





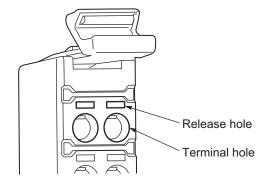
#### **Additional Information**

If more than 2 A will flow on the wires, use plated wires or use ferrules.

### **Connecting/Removing Wires**

This section describes how to connect and remove wires.

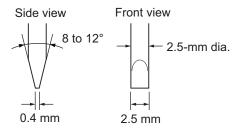
#### Terminal Block Parts and Names



### Required Tools

Use a flat-blade screwdriver to connect and remove wires.

Use the following flat-blade screwdriver.



Recommended screwdriver model

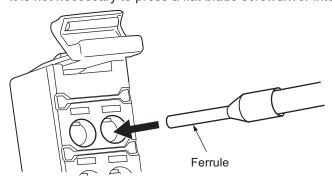
Model	Manufacturer
XW4Z-00B*1	OMRON Corporation
SZF 0-0,4×2,5	Phoenix Contact

<sup>\*1.</sup> The minimum standard number of package is 10 pcs.

### Connecting Ferrules

Insert the ferrule straight into the terminal hole.

It is not necessary to press a flat-blade screwdriver into the release hole.

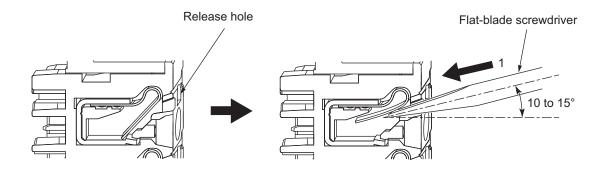


After you make a connection, make sure that the ferrule is securely connected to the terminal block.

### Connecting Twisted Wires/Solid Wires

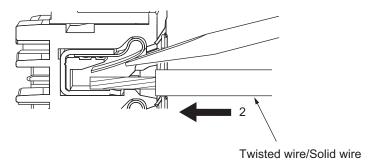
Use the following procedure to connect the twisted wires or solid wires to the terminal block.

Press a flat-blade screwdriver at an angle into the release hole.
The appropriate angle of the screwdriver is 10 to 15° to the horizontal.
If you press in the screwdriver correctly, you will feel the springback in the release hole.

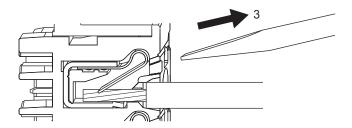


**2** Leave the flat-blade screwdriver pressed into the release hole and insert the twisted wire or the solid wire into the terminal hole.

Insert the twisted wire or the solid wire until the stripped portion is no longer visible in the terminal hole to prevent shorting.



**3** Remove the flat-blade screwdriver from the release hole.

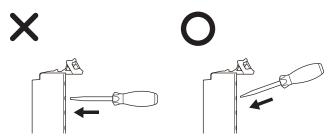


After you make a connection, lightly pull the twisted wire or the solid wire to make sure that the wire is securely connected to the terminal block.

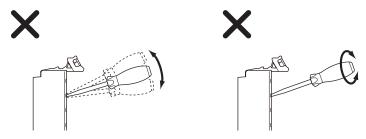


#### **Precautions for Safe Use**

• Do not press a flat-blade screwdriver straight into the release hole on a screwless clamping terminal block. Doing so may break the terminal block.



- When you insert a flat-blade screwdriver into a release hole on a screwless clamping terminal block, press it down with a force of 30N or less. Applying excessive force may damage the terminal block.
- Do not incline or twist the flat-blade screwdriver while it is in a release hole on a screwless clamping terminal block. Doing so may break the terminal block.



- · Follow the instructions in this manual to correctly perform wiring.
- Do not pull on the cables or bend the cables beyond their natural limit.
   Doing so may break the cables.

#### Securing Wires

It is necessary to secure wires to the screwless clamping terminal block depending on the wire types that are used or the current flows on the wires.

The following table gives the necessity for securing wires.

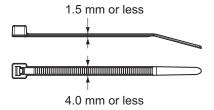
Terminals  Classification Current capacity		Wire type				
		Ferrule	Twisted wires		Solid wire	
		rerruie	Plated	Unplated	Plated	Unplated
All terminals except ground	2 A max.	No	No	No	No	No
terminals	Greater than 2 A and			Not possi-	Yes	Not possible
	4 A or less			ble		
Ground terminals			No	No	No	No

Use the following procedure to secure the wires.

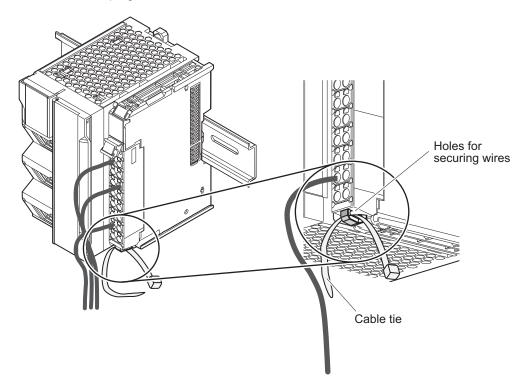


Prepare a cable tie.

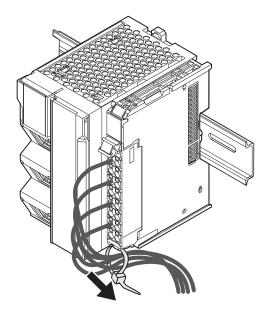
A cable tie can be used with a width of 4 mm or less and a thickness of 1.5 mm or less. Select a cable tie correctly for the operating environment.



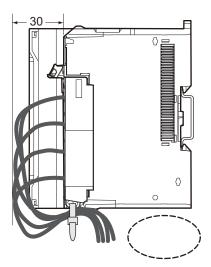
**2** Pass a cable tie through the holes for securing wires on the upper and lower sides of the screwless clamping terminal block.



**3** Bundle wires with a cable tie and secure them to the screwless clamping terminal block.



In such a case, secure wires within the range of 30 mm from the screwless clamping terminal block. Also, leave spaces below the CPU Rack to ensure ventilation, as shown in the following figure.



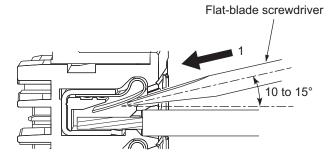
Space to ensure ventilation

### Removing Wires

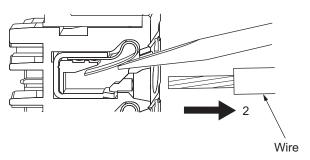
Use the following procedure to remove the wires from the terminal block. The removal method is the same for ferrules, twisted wires, and solid wires.

If wires are secured firmly to the terminal block, release them first.

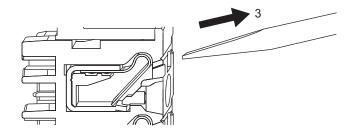
Press a flat-blade screwdriver at an angle into the release hole.
The appropriate angle of the screwdriver is 10 to 15° to the horizontal.
If you press in the screwdriver correctly, you will feel the springback in the release hole.



**2** Leave the flat-blade screwdriver pressed into the release hole and pull out the wire.



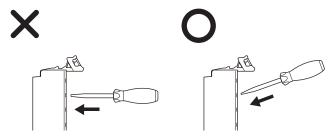
**3** Remove the flat-blade screwdriver from the release hole.



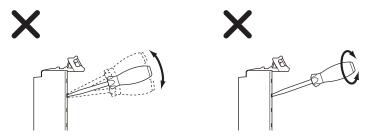


#### **Precautions for Safe Use**

• Do not press a flat-blade screwdriver straight into the release hole on a screwless clamping terminal block. Doing so may break the terminal block.



- When you insert a flat-blade screwdriver into a release hole on a screwless clamping terminal block, press it down with a force of 30N or less. Applying excessive force may damage the terminal block.
- Do not incline or twist the flat-blade screwdriver while it is in a release hole on a screwless clamping terminal block. Doing so may break the terminal block.



- Follow the instructions in this manual to correctly perform wiring.
- Do not pull on the cables or bend the cables beyond their natural limit.
   Doing so may break the cables.

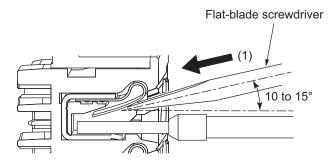


#### **Additional Information**

### **Procedure to Remove Tight Ferules**

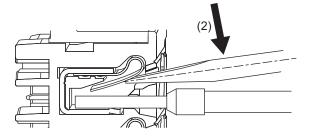
Use the following procedure to remove tight ferrules.

Press a flat-blade screwdriver at an angle into the release hole.
 The appropriate angle of the screwdriver is 10 to 15° to the horizontal.
 The tip of the flat-blade screwdriver contacts the ferrule if you press the driver too deep, and this makes the ferrule difficult to be pulled out. Press the flat-blade screwdriver lightly and stop there when you feel some resistance.

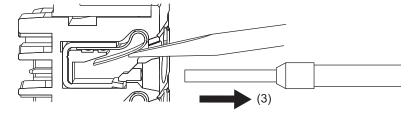


2. Leave the flat-blade screwdriver pressed into the release hole and tilt the flat-blade screwdriver approximately 5° to the direction of the ferrule.

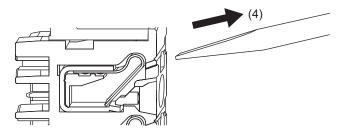
The position of spring in the release hole changes by the tilted flat-blade screwdriver, and this creates a gap between the ferrule and the spring.



3. Leave the flat-blade screwdriver tilted and pull out the ferrule.

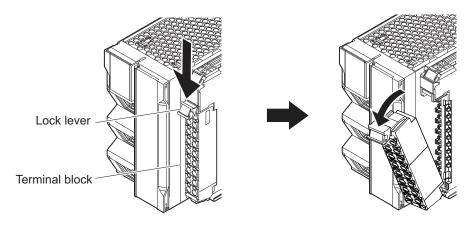


4. Remove the flat-blade screwdriver from the release hole.



### **Removing a Terminal Block**

1 While pressing the terminal block lock lever, pull the terminal block and remove it.

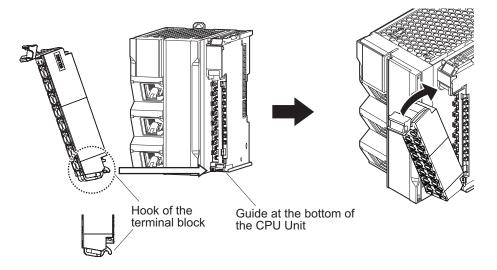


### **Attaching a Terminal Block**

1 Put the hook of the terminal block on the guide at the bottom of the CPU Unit, raise the terminal block, and press it until it clicks.

The terminal block is fixed in place to the Unit when it clicks.

After you mount the terminal block, make sure that it is fixed to the Unit.

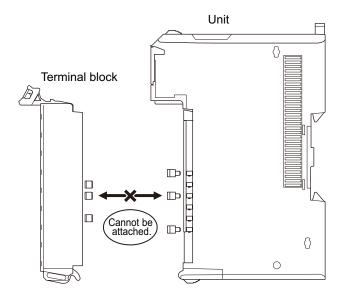


### **Preventing Incorrect Attachment of Terminal Blocks**

In order to prevent unintentional installing of wrong terminal blocks, you can limit the combinations between Units and terminal blocks.

Insert three Coding Pins (NX-AUX02) into three of the six incorrect attachment prevention holes on the Unit and on the terminal block. Insert these pins into positions so that they do not interfere with each other when the Unit and terminal block are connected to each other.

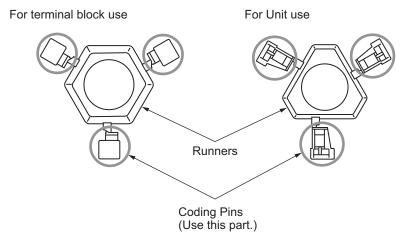
You can use these pins to create a combination in which the wrong terminal block cannot be attached because the pin patterns do not match.



### Types of Coding Pins

There are two types of Coding Pins, both with their own unique shape: one for terminal blocks and one for Units.

Three pins comes with each runner.



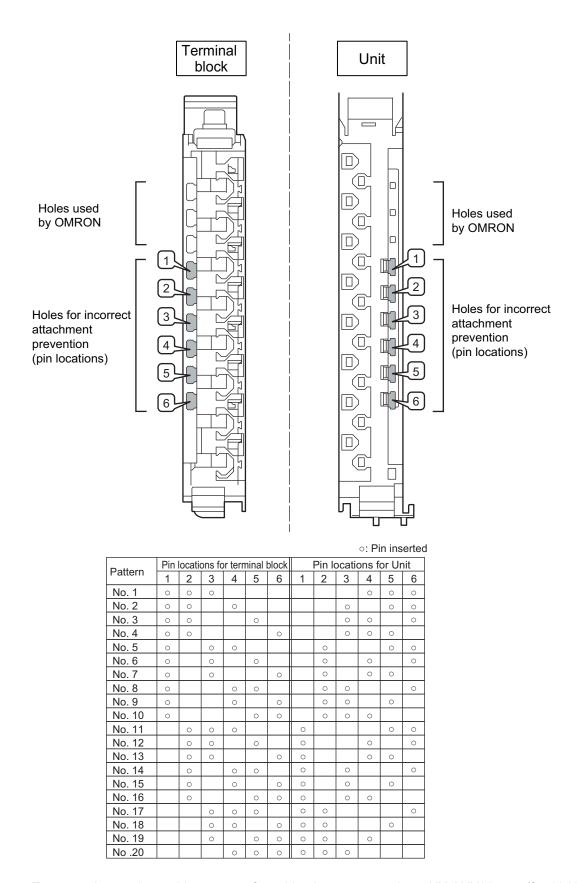
Use the following Coding Pins.

Name	Model	Specification
Coding Pin	NX-AUX02	For 10 Units
		(Terminal block: 30 pins, Unit: 30 pins)

### Insertion Locations and Patterns of Coding Pins

Insert three Coding Pins of each on the terminal block and on the Unit at the positions designated by the numbers 1 through 6 in the figure below.

As shown in the following table, there are 20 unique pin patterns that can be used.



To create the maximum 20 patterns of combinations, you need two NX-AUX02 sets (for 10 Units).

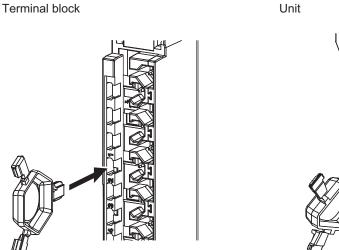


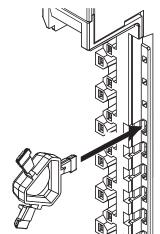
#### **Precautions for Correct Use**

- OMRON uses the holes other than No. 1 to 6 in the figure above. If you insert a Coding Pin
  into one of the holes used by OMRON on the terminal block side, this makes it impossible to
  mount the terminal block on a Unit.
- Do not use Coding Pins that have been attached and removed. Doing so may cause it to drop.

### Inserting the Coding Pins

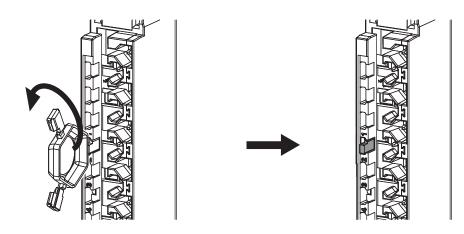
1 Hold the pins by the runner and insert a pin into one of the incorrect attachment prevention holes on the terminal block or on the Unit.

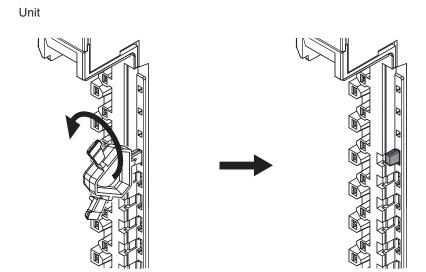




**2** Rotate the runner to break off the Coding Pin.

Terminal block





## 5-5 Control Panel Installation

To ensure system reliability and safety, the system must be designed and configured according to the installation environment (temperature, humidity, vibration, shock, corrosive gases, overcurrent, noise, etc.).

## 5-5-1 Temperature

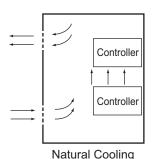
Panels have been reduced in size due to space-saving and miniaturization in devices and systems, and the temperature inside the panel may be at least 10 to 15°C higher than outside the panel. Implement the following measures against overheating at the installation site and in the panel, and allow a sufficient margin for the temperature before use.

## **High Temperatures**

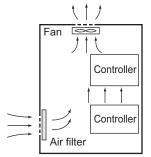
Use the following cooling methods as required, taking into account the ambient temperature and the amount of heating inside the panel.

### Natural Cooling

- Natural cooling relies on natural ventilation through slits in the panel, rather than using cooling devices such as fans or coolers. When using this method, observe the following points.
- Do not install the Controller at the top of the panel, where hot air tends to stagnate.
- To provide ventilation space above and below the Controller, leave sufficient distance from other devices, wiring ducts, etc.
- Do not mount the Units in the wrong direction (e.g., vertically or upside down). Doing so may cause abnormal heating in the Controller.
- Do not install the Controller directly above any heat-generating equipment, such as heaters, transformers, and devices with high resistance.
- · Do not install the Controller in a location exposed to direct sunlight.

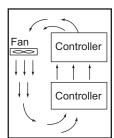


### Forced Ventilation (by Fan at Top of Panel)



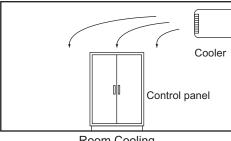
Forced Ventilation Method

### Forced Air Circulation (by Fan in Closed Panel)



Forced Air Circulation

### Room Cooling (Cooling the Entire Room Where the Control Panel Is Located)



Room Cooling

## **Low Temperatures**

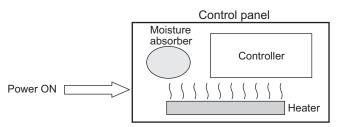
The Controller may not start normally if the temperature is below 0°C when the power is turned ON. Maintain an air temperature of at least approximately 5°C inside the panel, by implementing measures such as installing a low-capacity space heater in the panel.

Alternatively, leave the Controller power ON to keep the Controller warm.

#### 5-5-2 **Humidity**

Rapid temperature changes can cause condensation to occur, resulting in malfunctioning due to shortcircuiting.

When there is a possibility of this occurring, take measures against condensation, such as leaving the Controller power ON at night or installing a heater in the control panel to keep it warmer.



**Examples of Measures against Condensation** 

#### 5-5-3 Vibration and Shock

The Controller is tested for conformity with the sine wave vibration test method (IEC 60068-2-6) and the shock test method (IEC 60068-2-27) of the Environmental Testing for Electrotechnical Products. It is designed so that malfunctioning will not occur within the specifications for vibration and shock. If, however, the Controller is to be used in a location in which it will be directly subjected to regular vibration or shock, then implement the following countermeasures:

- Separate the control panel from the source of the vibration or shock.
   Or secure the Controller and the panel with rubber padding to prevent vibration.
- · Make the building or the floor vibration-resistant.
- To prevent shock when other devices in the panel such as electromagnetic contactors operate, secure either the source of the shock or the Controller with rubber padding.

## 5-5-4 Atmosphere

Using the Controller in any of the following locations can cause defective contact with connectors and corrosion of components. Implement countermeasures such as purging the air as required.

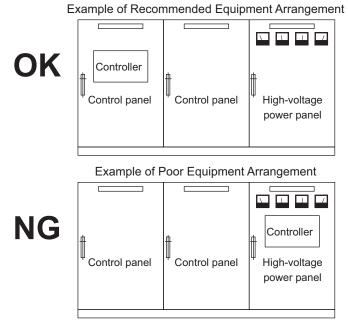
- In locations exposed to dust, dirt, salt, metal powder, soot, or organic solvents, use a panel with an airtight structure. Be careful of temperature increases inside the panel.
- In locations exposed to corrosive gas, purge the air inside the panel to clear the gas and then pressurize the inside of the panel to prevent gas from entering from outside.
- In locations where flammable gas is present, either use an explosion-protected construction or do not use the Controller.

### 5-5-5 Electrical Environment

When installing or wiring devices, make sure that there will be no danger to people and that noise will not interfere with electrical signals.

### **Controller Installation Location**

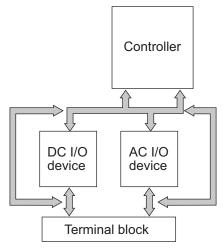
Install separately the Controller from high-voltage (600 V or higher) and power devices to ensure safe operation and maintenance. Install the Controller as far away as possible in case of unavoidable circumstances.



Examples of Equipment Arrangement in Panel with High-voltage Devices

## **Arrangement of Controller and Units**

The coils and contacts in electromagnetic contacts and relays in an external circuit are sources of noise. Do not install them close to the Controller. Locate them at least 100 mm away from the Controller.



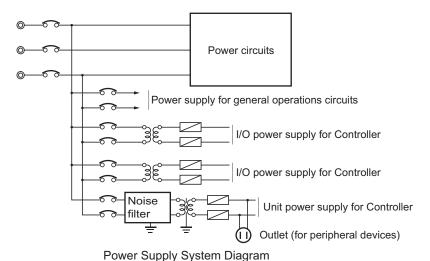
**Example of Arrangement in Panel** 

## Wire Layout for the Power Supply System

Observe the following points when wiring the power supply system.

• Separate the Controller power supply from the I/O device power supply and install a noise filter near the Controller power supply feed section.

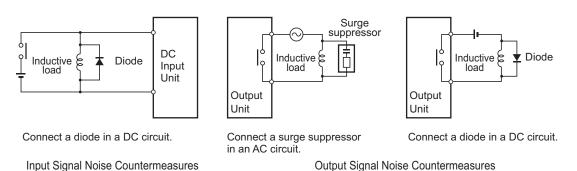
- Use an isolating transformer to significantly reduce noise between the Controller and the ground. Install the isolating transformer between the Controller power supply and the noise filter, and do not ground the secondary coil of the transformer.
- Keep the wiring between the transformer and the Controller as short as possible, twist the wires well, and keep the wiring separate from high-voltage and power lines.



## Wiring External I/O Signal Lines

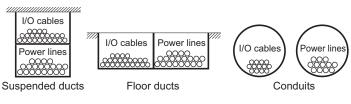
Observe the following points when wiring external I/O signal lines.

To absorb reverse electromotive force when an inductive load is connected to an output signal, connect a surge suppressor near the inductive load in an AC circuit, or connect a diode near the inductive load in a DC circuit.



Never bundle output signal lines with high-voltage or power lines, and do not route them in close
proximity or parallel to such lines.

If output signal lines must be routed in close proximity to such lines, place them in separate ducts or conduits. Be sure to ground the ducts or conduits.



I/O Cable Arrangement

- If the signal lines and power lines cannot be routed in separate ducts, use shielded cable. Connect the shield to the ground terminal at the Controller, and leave it unconnected at the input device.
- Wire the lines so that common impedance does not occur.
   Such wiring will increase the number of wires, so use common return circuits.
   Use thick wires with sufficient allowance for the return circuits, and bundle them with lines of the same signal level.
- For long I/O lines, wire the input and output signal lines separately.
- · Use twisted-pair wires for pilot lamps (and particularly lamps with filaments).
- Use countermeasures, such as CR surge absorbers and diodes, for input device and output load device noise sources, as required.

## **External Wiring**

Wiring, and noise countermeasures in particular, are based on experience, and it is necessary to closely manage wiring based on experience and information in the manuals.

#### Wiring Routes

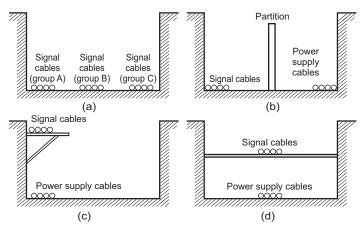
Each of the following combinations includes different signal types, properties, or levels. They will cause the signal-to-noise ratio to drop due to factors such as electrical induction. As a general rule when wiring, either use separate cables or separate wiring routes for these items. Future maintenance operations and changes to the system will also be made easier by carefully organizing the wiring from the start.

- · Power lines and signal lines
- Input signals and output signals
- · Analog signals and digital signals
- · High-level signals and low-level signals
- Communications lines and power lines
- · DC signals and AC signals
- High-frequency devices (such as Inverters) and signal lines (communications)

### Wiring

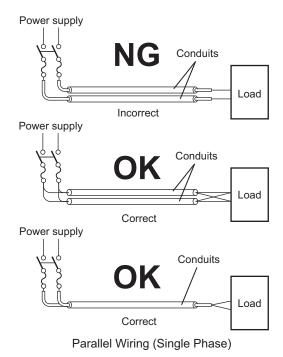
Observe the following points when wiring power supply and signal cables.

- When routing signal cables with differing characteristics through the same duct, always keep them separated.
- As much as possible, avoid routing multiple power supply lines through the same duct.
   If it cannot be avoided, then construct a partition between them in the duct and ground the partition.

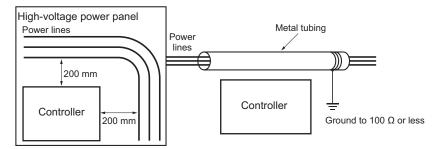


Partitioning Methods for Signal and Power Supply Cables

• To avoid overheating the conduits when using conduits for wiring, do not place wires for a single circuit in separate conduits.



- · Power cables and signal cables adversely affect each other. Do not wire them in parallel.
- Noise induction may occur if the Controller is installed in a panel that includes high-voltage devices. Wire and install them as far apart as possible. (Refer to Controller Installation Location on page 5-57.)
- Either install the Controller a minimum of 200 mm away from high-voltage lines or power lines, or place the high-voltage lines or power lines in metal tubing and completely ground the metal tubing to 100 Ω or less.



Example: Separating Controller from Power Lines

#### Other Precautions

Digital I/O Units have both plus and minus commons, so pay attention to the polarity when wiring.

### 5-5-6 Grounding

This section describes the earthing methods and precautions.

## **Considerations for Earthing Methods**

Local potential fluctuations due to lightning or noise occurred by power devices will cause potential fluctuations between ground terminals of devices. This potential fluctuation may result in device malfunction or damage. To prevent this, it is necessary to suppress the occurrence of a difference in electrical potential between ground terminals of devices. You need to consider the earthing methods to achieve this objective.

The recommended earthing methods for each usage condition are given in the following table.

	Earthing methods				
	Star eart		arthing		
Specification of communications cables for EtherCAT and EtherNet/IP	Equipotential bonding system	Connecting devi- ces and noise sources to sepa- rate earth elec- trodes	Connecting devi- ces and noise sources to a common earth electrode	Daisy chain	
The cable shield connected to the connector	Recommend-	Recommended	Not recommend-	Not recom-	
hood at both ends of the communications cable	ed		ed	mended	
Neither EtherCAT nor EtherNet/IP used	Recommend- ed	Recommended	Not recommend- ed	Not recom- mended	



#### **Additional Information**

- In a country or region where the earthing method is regulated, you must comply with the regulations. Refer to the applicable local and national ordinances of the place where you install the system, or other international laws and regulations.
- For details on wiring EtherCAT or EtherNet/IP, refer to the *NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual* (Cat. No. W505) or the *NJ/NX-series CPU Unit Built-in EtherNet/IP Port User's Manual* (Cat. No. W506).
- Ethernet switches are used with the EtherNet/IP. For information on the environmental resistance of the Ethernet switch to use, the grounding between Ethernet switches, or the specifications of cables, ask the Ethernet switch manufacturer.

Each of these earthing methods is given below.

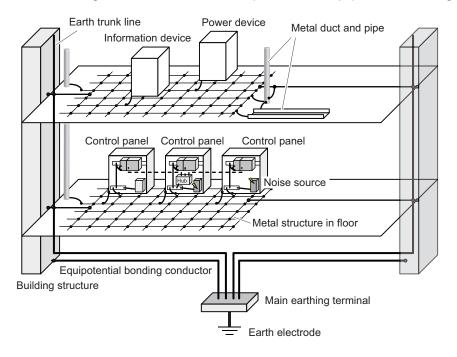
### Equipotential Bonding System

Equipotential bonding is an earthing method in which steel frames and building structures, metal ducts and pipes, and metal structures in floors are connected together and make connections to the earth trunk line to achieve a uniform potential everywhere across the entire building. We recommend this earthing method.

The following figure shows an example of an equipotential bonding system.

Connect the main earthing terminal and building structures together with equipotential bonding conductors and embed the mesh ground line in each floor.

Connect the ground line of each control panel to the equipotential bonding system.

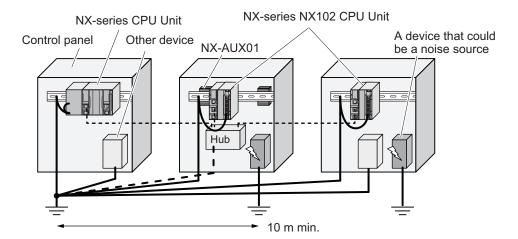


### Star Earthing

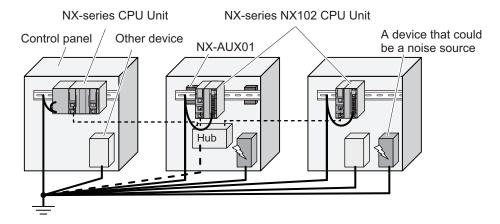
If the earthing method used for the building is not equipotential bonding or the earthing system is unknown, choose (a) from the earthing methods given below.

a. Installation method by connecting devices and noise sources to separate earth electrodes. This is an earthing method to separately ground an earth electrode of the device that is connected with a communications cable or other devices and an earth electrode of a high-power device that could be a noise source, such as a motor or inverter. Each earth electrode must be ground to  $100 \Omega$  or less.

Connect the ground lines of the device that is connected with a communications cable and other devices as a bundle to a single earth electrode. Be sure that the earth electrode is separated by a minimum of 10 m from any other earth electrode of a device that could be a noise source.



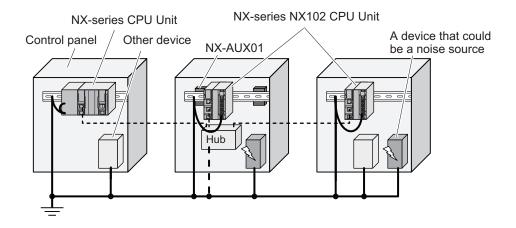
b. Installation method by connecting devices and noise sources to a common earth electrode This is an earthing method to connect the device that is connected with a communications cable, other devices, and a device that could be a noise source, to a common earth electrode. This earthing method is not recommended, because the device that is a potential noise source may interfere electromagnetically with other devices.



### Daisy Chain

This is an earthing method to connect the device that is connected with a communications cable, other devices, and a device that could be a noise source using a daisy-chain topology to a common earth electrode.

This earthing method is not recommended because the device that could be a noise source may interfere electromagnetically with other devices.

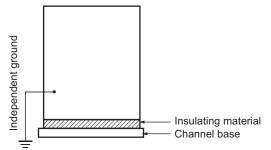


## **Precautions for Grounding**

#### General Precautions

- To prevent electrical shock, do not connect devices to ground poles (or steel frames) with nonequalized potential to which multiple devices are connected.
- Use a ground pole as close to the Controller as possible and keep the ground line as short as possible.
- If the same ground is used for both the signal lines and the enclosure, isolate the channel base (a grounded metal plate inside a control panel) with an insulating material.

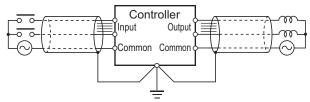
Refer to *Isolating the CPU Rack from the Control Panel* on page 5-38 for how to isolate the CPU Rack of an NX102 CPU Unit.



Example: Insulating and Grounding an Enclosure

- If high-frequency equipment is present, then ground not only the high-frequency equipment but also the panel itself in which the Controller is housed.
- As shown in the following diagram, when using shielded cable for I/O wiring, connect the shield near the Controller to the enclosure ground terminal.

Follow the instructions in the Communications Unit manual for preparing shielded communications cable.



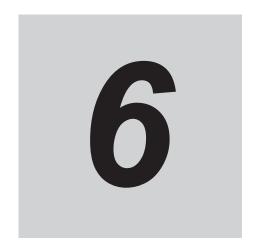
Shielded Cable Ground

### Controller Ground Terminals

The Controller has the following ground terminal.

Grounding type	Symbol	Connection
Functional Grounding		Ground this terminal when power supply noise causes malfunctioning.

When the functional ground terminal is correctly grounded, it is generally effective in suppressing power supply common noise. Occasionally, however, grounding this terminal will result in picking up more noise, so be careful when using it.



# **Troubleshooting**

This section describes the overview of the methods for checking errors.

6-1 Overview of Troubleshooting......6-2

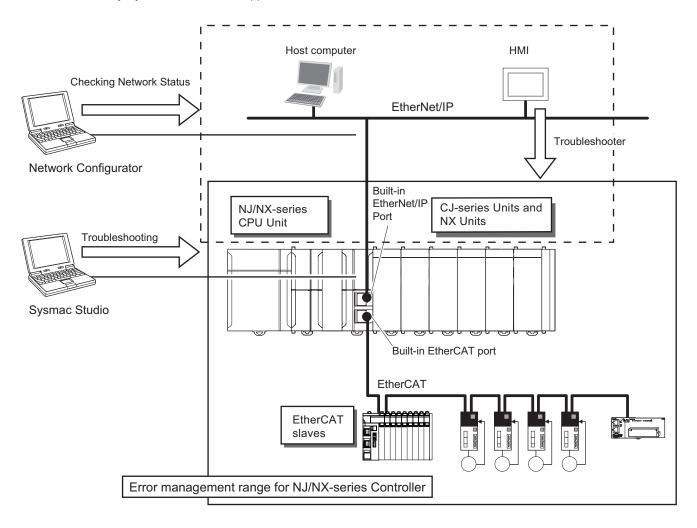
## 6-1 Overview of Troubleshooting

You manage all of the errors that occur on the NJ/NX-series Controller as events.

This allows you to see what errors have occurred and find corrections for them with the same methods for the entire range of errors that is managed (i.e., CPU Unit, NX Units, NX-series Slave Terminals,

EtherCAT slaves,\*1 and CJ-series Units).

\*1. Only Sysmac devices are supported.



You can use the troubleshooting functions of the Sysmac Studio or the Troubleshooter on an HMI to quickly check for errors that have occurred and find corrections for them.

Refer to the *NJ/NX-series Troubleshooting Manual (Cat. No. W503)* for error types and details, specific corrections when errors occur, and troubleshooting information on the entire NJ/NX-series Controllers.



# **Inspection and Maintenance**

This section describes the required inspections and maintenance. It also describes the service life and replacement procedure for the Battery.

7-1	Cleani	ng and Maintenance	7-2
	7-1-1	Cleaning	7-2
	7-1-2	Periodic Inspections	7-3
	7-1-3	Unit Replacement Precautions	7-4
7-2	Replac	ing the Battery	7-6

## 7-1 Cleaning and Maintenance

This section describes daily maintenance and the cleaning and inspection methods. Daily or periodic inspections are required in order to maintain the NX-series NX102 CPU Unit's functions in peak operating condition.

## 7-1-1 Cleaning

Perform the following cleaning procedures periodically to ensure the NX-series CPU Unit is maintained in the best operating condition. Always turn OFF the power supply to the Controller before performing the cleaning procedures.

- Wipe off the dust or dirt on the front, top or bottom of the Unit over with a dry, soft cloth when doing daily cleaning.
- If dust or dirt remains even after wiping with a soft, dry cloth, wipe over with a cloth that has been wet with a sufficiently diluted detergent (2%) and wrung dry.
- A smudge may remain on the Unit from gum, vinyl, or tape that was left on for a long time. Remove the smudge when cleaning.



#### **Precautions for Correct Use**

- Never use volatile solvents, such as paint thinner, benzene, or chemical wipes.
- · Do not touch the connectors.

## 7-1-2 Periodic Inspections

Although the major components in NX-series Controllers have an extremely long life time, they can deteriorate under improper environmental conditions. Periodic inspections are thus required to ensure that the required conditions are being kept.

Inspection is recommended at least once every six months to a year, but more frequent inspections may be necessary depending on the severe environments.

Take immediate steps to correct the situation if any of the conditions in the following table are not met.

## **Periodic Inspection Items**

No.	Inspec- tion item	Inspection details	Criteria	Correction
1	External power supply	Check for voltage fluctuations at the power supply terminals.	The voltage must be within the allow- able voltage fluctu- ation range.	Use a voltage tester to check the power supply at the terminals. Take necessary steps to bring voltage of the supplied power to within the allowable voltage fluctuation range.
2	I/O power supply	Check for voltage fluctuations at the I/O terminals.	Voltages must be within specifications for each Unit.	Use a voltage tester to check the I/O power supply at the terminals. Take necessary steps to bring voltage fluctuations within limits.
3	Ambient environ- ment	Check the ambient temperature. (Inside the control panel if the Controller is in a control panel.)	0 to 55°C	Use a thermometer to check the temperature and ensure that the ambient temperature remains within the allowed range of 0 to 55°C.
		Check the ambient humidity. (Inside the control panel if the Controller is in a control panel.)	Relative humidity must be 10% to 95% with no con- densation.	Use a hygrometer to check the humidity and ensure that the ambient operating humidity remains between 10% and 95%. Make sure that condensation does not occur due to rapid changes in temperature.
		Check that the Controller is not in direct sunlight.	Not in direct sun- light	Protect the Controller if necessary.
		Check for accumulation of dirt, dust, salt, metal powder, etc.	No accumulation	Clean and protect the Controller if necessary.
		Check for water, oil, or chemical sprays hitting the Controller.	No spray	Clean and protect the Controller if necessary.
		Check for corrosive or flam- mable gases in the area of the Controller.	No corrosive or flammable gases	Check by smell or use a gas sensor.
		Check the level of vibration or shock.	Vibration resist- ance and shock resistance must be within specifica- tions.	Install cushioning or shock absorbing equipment if necessary.
		Check for noise sources near the Controller.	No significant noise sources	Either separate the Controller and noise source or protect the Controller.

No.	Inspec- tion item	Inspection details	Criteria	Correction
4	Installa- tion and wiring	Check that the DIN Track mounting hooks on all Units are securely locked.	No looseness	Securely lock the DIN Track mounting hooks.
		Check that cable connectors are fully inserted and locked.	No looseness	Correct any improperly installed connectors.
		Check that the screws on the End Plates (PFP-M) are tight.	No looseness	Tighten loose screws with a Phillips-head screwdriver.
		Check that each Unit is connected along the hook-up guides, and fully inserted until it contacts the DIN Track.	The Units must be connected and securely in place on the DIN Track.	Connect each Unit along the hookup guides, and insert each Units until it contacts the DIN Track.
		Check for damaged external wiring cables.	No visible damage	Check visually and replace cables if necessary.
5	User- servicea- ble parts	Battery Set CJ1W-BAT01 Check whether the battery has reached its service life.	Service life expect- ancy is 5 years at 25°C. Depending on model and ambi- ent temperature.	Replace the battery when its service life has passed even if a battery error has not occurred. (Battery life depends upon the model, and ambient conditions.) Refer to 7-2 Replacing the Battery on page 7-6 for the service life of individual model.

## **Tools Required for Inspections**

### Required Tools

- · Flat-blade screwdriver
- · Phillips screwdriver
- · Voltage tester or digital multimeter
- · Industrial alcohol and pure cotton cloth
- · Antistatic gas duster

### Tools Required Occasionally

- Oscilloscope
- Thermometer and hygrometer

## 7-1-3 Unit Replacement Precautions

If you find any faulty Unit after check, replace the Unit according to the following points.

- · Do not replace a Unit until the power is turned OFF.
- Check the new Unit to make sure that there are no errors.
- If you return a faulty Unit for repair, describe the problem in as much detail as possible, enclose this description with the Unit before returning it.
- For poor contact, take a clean cotton cloth, soak the cloth in industrial alcohol, and carefully wipe the contacts clean. Be sure to remove any lint prior to remounting the Unit.



#### **Precautions for Safe Use**

- Make sure that the required data, including the user program, configurations, settings, and variables, is transferred to a CPU Unit that was replaced and to externally connected devices before restarting operation. Be sure to include the tag data link settings and routing tables, which are stored in the CPU Unit.
- The absolute encoder home offsets are retained in the CPU Unit as absolute encoder information.
  - When you change the combination of the CPU Unit and Servomotor, e.g., when you add or replace a Servomotor, define the absolute encoder home again.



#### **Precautions for Correct Use**

- If you replace a slave or Unit, refer to the operation manual for the slave or Unit for information on the data required for individual slaves or Units and redo the necessary settings.
- If you use the OPC UA server function, refer to the *NJ/NX-series CPU Unit OPC UA User's Manual (Cat. No. W588)* for the description of how to replace CPU Units.

## 7-2 Replacing the Battery

The separately-sold Battery for clock is one of the NX-series components that require periodic replacement as preventive maintenance. This section describes how to replace the Battery.

## **Replacement Battery**

Use the Battery CJ1W-BAT01 for replacement.



#### **Precautions for Correct Use**

Be sure to mount a Battery within two years of the production date shown on the Battery label. Production Date



Manufactured in March 2018.

## **Replacement Procedure**

Use the following procedure to replace the battery.



#### **Precautions for Safe Use**

We recommend mounting or replacing the Battery with the power turned OFF to prevent the CPU Unit's sensitive internal components from being damaged by static electricity and to prevent malfunctions. The Battery can be mounted or replaced without turning OFF the power supply. To do so, always touch a grounded piece of metal to discharge static electricity from your body before you start the procedure.

If the Low Battery Voltage error occurs after you mount the Battery, connect the Sysmac Studio and clear the error.



#### **Additional Information**

UL standards require that batteries be replaced by experienced technicians. Always place an experienced technician in charge of battery replacement.

1 Turn OFF the power supply to the Controller.
If the CPU Unit has not been ON, turn it ON for at least five minutes and then turn it OFF.



#### **Additional Information**

The CPU Unit has a built-in capacitor that retains the clock data during battery replacement or power interruptions.

If power is not turned ON for at least five minutes before replacing the battery, the built-in capacitor cannot be fully charged and the clock data may be lost during battery replacement.

Remove the battery cover.
Refer to 5-3-9 Battery Installation on page 5-26 for how to remove it.

**3** After removing an old battery, install a new battery.





#### **Precautions for Safe Use**

- Apply power for at least five minutes before changing the Battery. Install a new Battery within
  five minutes (at 25°C) of turning OFF the power supply. If power is not supplied for at least 5
  minutes, the retained clock data may be initialized.
- The Battery may leak, rupture, heat, or ignite. Never short-circuit, charge, disassemble, heat, or incinerate the Battery or subject it to strong shock.
- Dispose of any Battery that has been dropped on the floor or otherwise subjected to excessive shock. Batteries that have been subjected to shock may leak if they are used.



#### **Precautions for Correct Use**

Turn ON the power after replacing the Battery for a CPU Unit that has been unused for a long time. Leaving the CPU Unit unused again without turning ON the power even once after the Battery is replaced may result in a shorter Battery life.



#### **Additional Information**

The *Low Battery Voltage* event is cleared automatically the next time the Controller is turned ON after replacing the Battery.

## **Battery Service Life and Replacement Period**

The service life of a battery is five years. Generally, the service life of a battery varies depending on the ambient temperature and the power ON time rate. The NX102 CPU Unit, due to low power consumption, ensures a battery life of 60 months (five years), which is equivalent to the battery service life.

Make a plan to replace the Battery so that the service life of the Battery will not exceed the minimum lifetime under the normal product usage condition.

The Battery service life when power ON time rate is 0% (i.e., power OFF)

Unit model number	Approx. m	inimum lifetime	nimum lifetime [month]*1		
Ont model number	25°C	40°C	55°C		
NX102-□□□	60				

<sup>\*1.</sup> This is the life expectancy which Omron guarantees, based on the calculation worst value of the part's specification of the product.

## **Low Battery Indicators**

If the Controller Setup has been set to detect a low-battery error, the ERROR indicator on the front of the CPU Unit will flash when the battery is nearly discharged.

If the ERROR indicator flashes, connect the Sysmac Studio, and then check the CPU Unit's Battery connection if the Sysmac Studio shows a *Low Battery Voltage* or *Real-Time Clock Stopped* event. If the Battery is properly connected, replace the Battery with a new one as soon as possible.

Once a low-battery error has been detected, it will take 5 days (at an ambient temperature of 25°C or less) before the battery fails if power has been supplied at least once a day.

Clock data can be retained by ensuring that the CPU Unit power is not turned OFF until the Battery has been replaced.



### **Additional Information**

The Battery will lose its charge faster at high ambient temperatures.



# **Appendices**

The appendices provide the general specifications of the CPU Unit and Unit dimensions.

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## **A-1 Specifications**

This section gives the general specifications that are common to NX-series NX102 CPU Unit and their relevant products.

For the electrical and mechanical specifications, refer to the Models and Specifications section for each product.

Item		Specification	
Enclosure		Mounted in a panel	
Grounding me	thod	Ground to less than 100 $\Omega$ .	
Operating environment	Ambient operating temperature	0 to 55°C	
	Ambient operating humidity	10% to 95% (with no condensation)	
	Atmosphere	Must be free from corrosive gases.	
	Ambient storage temperature	-25 to 70°C (excluding battery)	
	Altitude	2,000 m max.	
	Pollution degree	2 or less: Meets IEC 61010-2-201.	
	Noise immunity	2 kV on power supply line (Conforms to IEC 61000-4-4.)	
	Overvoltage category	Category II: Meets IEC 61010-2-201.	
	EMC immunity level	Zone B	
	Vibration resistance	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz, acceleration of 9.8 m/s <sup>2</sup> 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)	
		Gravity acceleration is assumed to be G=9.8 m/s <sup>2</sup> .	
		Conforms to IEC 60068-2-27.	
	Shock resistance	147 m/s <sup>2</sup> , 3 times in X, Y, and Z directions	
		Gravity acceleration is assumed to be G=9.8 m/s <sup>2</sup> .	
Battery	Life	5 years at 25°C (Power ON time rate 0% (power OFF))	
	Model	CJ1W-BAT01 (sold separately)	
Applicable	EU Directives	EN 61131-2	
standards*1	cULus	Listed(UL 61010-2-201), ANSI/ISA 12.12.01	
	Shipbuilding Standards	NK and LR	
	Other than the above.	RCM, KC, EAC	

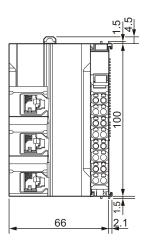
<sup>\*1.</sup> Refer to the OMRON website (http://www.ia.omron.com/) or consult your OMRON representative for the most recent applicable standards for each model.

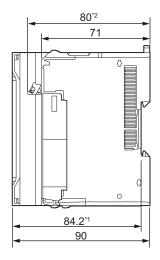
## A-2 Dimensions

Dimensions of the Units are shown as follows. The unit of dimension is millimeter.

## A-2-1 NX-series NX102 CPU Unit

## **NX102-**□□□□





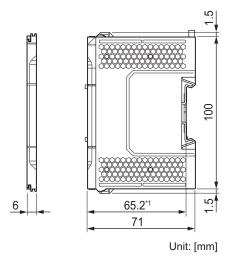
Unit: [mm]

- \*1. The dimension from the attachment surface of the DIN Track to the front surface of the CPU Unit.
- \*2. The dimension from the terminal block lock lever to the back surface of the CPU Unit.

For dimensions after attaching the communications cables, refer to *5-3-12 Assembled Appearance* and *Dimensions* on page 5-31.

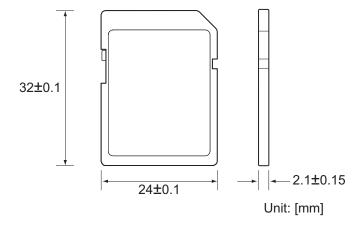
## A-2-2 End Cover

## NX-END02



\*1. The dimension from the attachment surface of the DIN Track to the front surface of the end cover.

## A-2-3 SD Memory Card

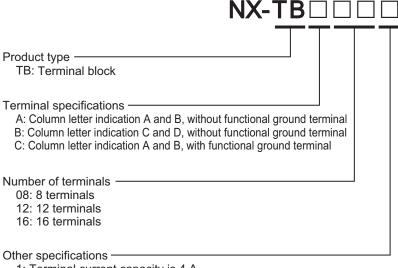


## **List of Terminal Block Models**

This section provides a list of screwless clamping terminal block models that you can use with an NXseries NX102 CPU Unit, EtherCAT Coupler Unit, or NX Unit.

#### A-3-1 **Model Notation**

The model designation of a terminal block is given as follows.



- 1: Terminal current capacity is 4 A.
- 2: Terminal current capacity is 10 A.

#### A-3-2 **List of Terminal Block Models**

The following table shows a list of terminal blocks.

Use the NX-TBC082 for NX-series NX102 CPU Units.

If the NX-TBC082 is attached to an NX102, limit the current that passes through the terminals via unwired terminals to 4 A or less, although the terminal capacity of the NX-TBC082 is 10 A.

Terminal block model	Number of terminals	Ground terminal indication	Current capacity of ter- minals
NX-TBA081	8	Not provided	4 A
NX-TBA121	12	Not provided	4 A
NX-TBA161	16	Not provided	4 A
NX-TBB121	12	Not provided	4 A
NX-TBB161	16	Not provided	4 A
NX-TBA082	8	Not provided	10 A
NX-TBA122	12	Not provided	10 A
NX-TBA162	16	Not provided	10 A
NX-TBB082	8	Not provided	10 A
NX-TBB122	12	Not provided	10 A
NX-TBB162	16	Not provided	10 A
NX-TBC082	8	Provided	10 A

Terminal block model	Number of terminals	Ground terminal indication	Current capacity of ter- minals
NX-TBC162	16	Provided	10 A

**Note** When you purchase a terminal block, purchase an NX-TB  $\square$   $\square$   $\square$  2.

## A-4 Version Information

Refer to *Version Information for NX-series Controllers* in the *NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501)* for the relationship between the unit versions of NX-series NX102 CPU Unit and the Sysmac Studio versions, and for the functions that are supported by each unit version. Refer to *A-5 Support Functions of the CPU Units and Restrictions on the NX Units* on page A-8 for information on NX Units that can be connected to the CPU Unit.

# A-5 Support Functions of the CPU Units and Restrictions on the NX Units

Some support functions of the CPU Unit are restricted depending on the models and unit versions of NX Units mounted on it.

The table below shows the functions that are restricted depending on the models and unit versions of the NX Units.

Refer to the *NX-series Data Reference Manual* (Cat. No. W525) for details on supported models and unit versions of NX Units.

Function			
Restarting	Restarting a specified NX Unit		
Monitoring total power-ON time			
Restarting after transferring Unit operation settings	Restarting the NX Unit to which the Unit operation settings were transferred when you transfer the settings to a specified NX Unit		

Refer to the *NX-series Data Reference Manual* (Cat. No. W525) for information on NX Units that can be connected to the NX-series NX102 CPU Unit.



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